GRAPH MODIFICATION PROBLEMS

A Modern Perspective



Setting the stage: Definitions and Preliminary Observations

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Brief excursions into specific examples

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Current Trends & Future Directions



Ingredients of a typical Graph Modification Problem



Input Graph, G



Input Graph, G





Input Graph, G



Input Graph, G

Input Graph, G





vertex deletions

Input Graph, G





vertex deletions edge deletions

Input Graph, G





vertex deletions edge deletions edge additions

Input Graph, G





vertex deletions edge deletions edge additions edge contractions

Input Graph, G





vertex deletions edge deletions edge additions edge contractions edge editing

Input Graph, G





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VERTEX COVER

Input Graph, G



Edgeless Graphs



vertex deletions edge deletions edge additions edge contractions edge editing

FEEDBACK VERTEX SET

Input Graph, G



Acyclic Graphs



vertex deletions edge deletions edge additions edge contractions edge editing

Minimum Fill-In

Input Graph, G

Chordal Graphs



vertex deletions edge deletions edge additions edge contractions edge editing

CLUSTER EDITING

Input Graph, G



Cluster Graphs



Minimum π -Completion

Minimum π -Completion

Minimum **π**-Supergraph

Minimum π -Completion

Minimum **π**-Supergraph

Minimum π -Deletion

Minimum π -Completion

Minimum π -Supergraph

Minimum π -Deletion

Maximum π -Spanning Subgraph

Minimum π -Completion

Minimum π -Supergraph

Minimum π -Deletion

Maximum **π**-Spanning Subgraph

Minimum π -Editing

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Closest π-Graph

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Closest π-Graph

Minimum π -Vertex Deletion

Minimum π -Completion

Minimum π -Deletion

Minimum **π**-Supergraph

Maximum **π**-Spanning Subgraph

Minimum **π**-Editing

Closest **π**-Graph

Minimum π -Vertex Deletion

Maximum π-Induced Subgraph

Minimum π -Completion

Minimum **π**-Supergraph

Minimum π -Deletion

Maximum **π**-Spanning Subgraph

Minimum **π**-Editing

Closest **π**-Graph

Minimum π -Vertex Deletion

Maximum **π**-Induced Subgraph

Completion to Minimum Max-Clique

Minimum π -Completion

Minimum **π**-Supergraph

Minimum **π**-Deletion

Maximum **π**-Spanning Subgraph

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Modification with Restrictions, eg, the Sandwich problem

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Restricted Classes of Input



<u>Non-Trivial</u> π admits infinitely many graphs, and also excludes infinitely many graphs.



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Connectivity, Biconnectivity, Trees, Stars, Eulerian, etc.





The vertex-deletion problem is **NP-complete** for non-trivial, hereditary properties.

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Add edges to make the input graph a cluster graph.

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<u>Colbourn &</u> <u>El-Mallah</u> [1988]

Making a graph P_k -free by deleting the minimum number of edges is NP-hard for every k > 2.

edge editing edge contractions vertex deletions edge additions edge deletions



Perfect

Trivially Perfect Cographs **Permutation Graphs** Bipartite Trees Weakly Chordal Chordal Strongly Chordal Split Interval Proper Interval Unit Interval Forests Caterpillars Chain **Chordal Bipartite Distance Hereditary** Comparability Trapezoid CoChordal Circle Planar

edge editing edge contractions vertex deletions edge additions edge deletions



GRAPH MODIFICATION PROBLEMS

A Modern Perspective

GRAPH MODIFICATION PROBLEMS

Why bother?

Planar Graphs

Interval Graphs

Cluster Graphs

k-Connected Graphs

Directed Acyclic Graphs

Chordal Graphs

Planar Graphs

Interval Graphs

Cluster Graphs

k-Connected Graphs

Directed Acyclic Graphs

Chordal Graphs

Graph Drawing

Physical Mapping of DNA

Correlation Clustering

Reliability of Networks

Deadlock Recovery, Operating Systems

Gaussian Elimination over Sparse Matrices

We would like to "achieve" these properties with minimum cost, which naturally leads us to the graph modification framework.

Planar Graphs Graph Drawing

Interval Graphs

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GRAPH MODIFICATION PROBLEMS

Algorithms



Graph Class or "property", $\boldsymbol{\pi}$

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Forbidden Minor Characterization

A graph G belongs to π if, and only if, G does not contain any graph from Forb(π) as a **minor**.

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A graph admits a **forbidden subgraph characterization** if, and only if, it is **closed under taking induced subgraphs (hereditary)**, that is, the property is preserved under vertex deletions.



A graph G belongs to π if, and only if, G does not contain any graph from Forb(π) as a minor.



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Now: the graph modification problem has boiled down to a membership testing problem, which can be done in cubic time, given the finite forbidden set. Forbidden Subgraph Characterization

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Can the node deletion question for hereditary properties always be answered with the "graph minors hammer"?

Forbidden Minor Characterization

A graph admits a **forbidden minor characterization** if, and only if, it is **closed under taking minors**, that is, the property is preserved under vertex deletions, edge deletions and edge contractions. Consider the property π of being wheel-free, that is, not having any wheel as an induced subgraph.



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<u>Lokshtanov</u> Wheel-Free Deletion and Wheel-Free Vertex Deletion (2008) are **W[2]-hard.**

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Ramsey Numbers!

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Reduction from Independent Set

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Vertex Cover

Can G be made edgeless by the removal of at most k vertices?



A simple randomized algorithm with an error probability of 2^{-k}.

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Can G be made acyclic by the removal of at most k vertices?



Let's stare at the *structure* of a YES-instance.

#whisper: Let us also restrict ourselves to graphs of constant maximum degree, say five.

the k vertices corresponding to the FVS



(n-k) vertices and at most (n-k-1) edges "outside".

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Bad scenario: **one of the pieces is large.**


These pieces have **simple structure** and **bounded interaction** with the outer world.



These pieces have **simple structure** and **bounded interaction** with the outer world. Such pieces are called **"protrusions".**

A Boundary of Constant Size



Constant Treewidth

A Boundary of Constant Size



Constant Treewidth

A Boundary of Constant Size



Constant Treewidth





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For some problems, the number of equivalence classes is **finite**, allowing us to replace protrusions in graphs.





Finding protrusions? What do we replace them with?

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The Planar \mathcal{F} -Deletion Problem

Ensure that protrusions are removed.

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Pick an edge uniformly at random.

Ensure that protrusions are removed. Pick an edge uniformly at random.

Include both endpoints.

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Pick an endpoint u.a.r.

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Include both endpoints.

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Repeat till G is *F*-free.

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Include both endpoints. (Approximation algorithm.) Pick an endpoint u.a.r.

Repeat till G is *F*-free.

Ensure that protrusions are removed.

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Pathwidth-1-Deletion has a O*(4.65^k) algorithm.



Planar *SF*-Deletion admits a randomized (2^{0(k)}n) algorithm when every graph in *SF* is connected.



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Best possible under ETH.

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Planar F-Deletion admits a polynomial kernel. Best possible under standard assumptions.

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Marx and Schlotter [2012] Planarization admits an algorithm with running time $O(2^{g(k)}n^2)$ where $g(k) = k^{O(k3)}$

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The question of kernels is **completely open**.

GRAPH MODIFICATION PROBLEMS

When the operation induces hardness

CONTRACTION PROBLEMS

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Forbidden Subgraph Characterization

A graph admits a **forbidden subgraph characterization** if, and only if, it is **closed under taking induced subgraphs (hereditary)**, that is, the property is preserved under vertex deletions.

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Graph Class or "property", π

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Not true any more!

CONTRACTION TO C4-FREE GRAPHS

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W[2]-hard by a simple reduction from Hitting Set.

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Contracting to paths is **FPT** and has a **linear-vertex kernel**; while contracting to trees is **FPT** but is **unlikely to admit a polynomial kernel**.

GRAPH MODIFICATION PROBLEMS

Completion

<u>Yannakakis</u> [1981] The minimum fill-in problem is **NP-complete** (was left open in the first edition of Garey and Johnson).

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Fomin & Villanger [2013] Chordal Completion admits a **sub exponential** parameterized algorithm with a running time of $O(2^{\sqrt{k \log k}} + k^2 m n)$.

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<u>Tarjan</u> [1999] Chordal Completion, Strongly Chordal Completion, and Proper Interval Completion are fixed-parameter tractable (FPT).

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Interval Completion is **fixed-parameter tractable** (FPT), with a running time of O(k^{2k}n³m).

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<u>Cao</u> [2007]	Interval Completion has a single-exponential parameterized algorithm, with a running time of O(6 ^k (n+m)).
<u>Bliznets, Fomin,</u> <u>Pilipczuk & Pilipczuk</u> [2014]	Interval Completion admits a subexponential parameterized algorithm with a running time of $k^{O(\sqrt{k})}n^{O(1)}$.

GRAPH MODIFICATION PROBLEMS

A Summary

Edge Deletions

Kernels on Planar Graphs & the Meta-Kernel project

Special Graph Classes, eg, Feedback Arc Set on Tournaments

Connectivity Augmentation

The descriptive complexity of graph modification

Structural parameters and other objective functions

Backdoor Sets!



