Twisted Covariance and DFR Spacetime Quantisation

Gherardo Piacitelli SISSA - Trieste e-mail: piacitel@sissa.it

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1 Part I. Tensor character of θ

NC Coordinates and Twisted Products Moyal Expansion; Drinfeld Twist Twisted Poincaré Action Twisted Covariance; is θa Tensor? Tensor or not? Back to Interpretation! Weyl quantisation requires θ tensor

- Part II. From DFR Model to Twisted Covariance DFR coordinates Algebra of generalised symbols DFR C*algebra, and symbol calculus A certain class of localisation states θ – Universality Twisted Covariance Recovered
- 3 Interlude: Many Events
- 4 Conclusions

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Part I Tensor character of θ

NC Coordinates and Twisted Products

Commutation Relations: $[q^{\mu}, q^{\nu}] = i\theta^{\mu\nu}, \theta$ fixed once and for all in a given reference frame. Weyl Form:

$$e^{ihq}e^{ikq} = e^{-\frac{i}{2}h\theta k}e^{i(h+k)q}$$

Weyl quantisation:

$$W_ heta(f) = \int dk\,\check{f}(k) e^{ikq}.$$

Twisted Product defined by:

$$W_{ heta}(f)W_{ heta}(g) = W_{ heta}(f\star_{ heta} g).$$

Easier to work in momentum space:

$$f \star_{\theta} g = \check{f} \times_{\theta} \check{g}$$

where $h\theta k = h_{\mu}\theta^{\mu\nu}k_{\nu} = h^t G\theta Gk$ and

$$(\check{f} \times_{\theta} \check{g})(k) = \int dh\check{f}(h)\check{g}(k-h)e^{-\frac{i}{2}h\theta k}.$$

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Let's write for the ordinary and twisted convolution

 $c(\check{f}\otimes\check{g})(k)=(\check{f}\times\check{g})(k),\quad c_{ heta}(\check{f}\otimes\check{g})(k)=(\check{f} imes_{ heta}\check{g})(k);$

We define the multiplication operator

$$(T_{\theta}\check{f}\otimes\check{g})(h,k)=e^{-rac{i}{2}h\theta k}\check{f}(h)\check{g}(k),$$

fulfilling $T_{\theta}^{-1} = T_{-\theta}$ and (only on analytic symbols!)

$$(\widetilde{T_{\theta} f \otimes \check{g}})(x, y) = \left(e^{-\frac{i}{2}\theta^{\mu\nu}\partial_{\mu}\otimes\partial_{\nu}}f \otimes g\right)(x, y),$$

so that

$$c_{\theta} = c \circ T_{\theta}.$$

We recover position space definition

$$\widehat{c_{\theta}(f\otimes g)} = m_{\theta}(f\otimes g) = m(F_{\theta}f\otimes g)$$

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Twisted Poincaré Action

Define

$$(\alpha(L)\check{f})(k) = e^{-ika}\check{f}(\Lambda^{-1}k), \quad L \in \mathscr{P}$$

(Fourier Transform of $f \mapsto {}_{L}f(x) = f(L^{-1}x)$). Twisted product not covariant in general (θ constant):

$$\alpha(L)\boldsymbol{c}_{\theta}(\check{\boldsymbol{f}}\otimes\check{\boldsymbol{g}})\neq\boldsymbol{c}_{\theta}(\alpha(L)\check{\boldsymbol{f}}\otimes\alpha(L)\check{\boldsymbol{g}}).$$

Solution (Chaichian & cols, Wess & cols): twist the coproduct action: namely replace $\alpha^{(2)}(L) = \alpha(L) \otimes \alpha(L)$ by

$$\alpha_{\theta}^{(2)}(L) = T_{\theta}^{-1} \alpha^{(2)}(L) T_{\theta}.$$

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Easy to check that

$$\alpha(L)c_{\theta}(\check{f}\otimes\check{g})=c_{\theta}(\alpha_{\theta}^{(2)}(L)\check{f}\otimes\check{g}). \tag{(*)}$$

Standard interpretation: θ not a tensor! Is that obvious? Other way to check (*). Set $\theta' = A \theta A^t (\theta'^{\mu\nu} = A^{\mu}{}_{\mu'}A^{\nu}{}_{\nu'}\theta^{\mu'\nu'})$. Remark that

$$\alpha^{(2)}(L)T_{\theta} = T_{\theta'}\alpha^{(2)}(L)$$

 $[h^{t}G\theta Gk \mapsto (\Lambda^{-1}h)^{t}G\theta G\Lambda^{-1}k, \text{ use } \Lambda^{-1} = G\Lambda^{t}G, G^{2} = 1.]$ so that $\alpha_{\theta}^{(2)}(L) = T_{\theta}^{-1}\alpha^{(2)}(L)T_{\theta} = T_{\theta}^{-1}T_{\theta'}\alpha^{(2)}(L)$ and

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where $\check{f}'(k) = e^{-ika}\check{f}(\Lambda^{-1})$. in other words: (twstd covariance + θ invariant) \Leftrightarrow (ordinary cov'nce + θ tensor): $(f \star_{\theta} g)' = f' \star_{\theta'} g'$.

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Untwisted form covariance + tensoriality of θ may seem appealing, but form covariance alone not a guidance, when equivalence of observers is broken at a fundamental level. Up to now the two formalisms have same dignity.

Problem is: above only formal remark. To decide, go back to interpretation of $i\theta$ as the commutator of the coordinates. Assume Jack=preferred observer, Jane=observer connected to Jack by *L*.

- Jane:
 - $[q^{\prime\mu},q^{\prime\nu}]=?$ (no a priori assumption)
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We first compute ($L = (\Lambda, 0)$ for simplicity))

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Part II From DFR Model to Twisted Covariance

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DFR coordinates

 \exists ! the regular representation of the relations

$$[q^{\mu},q^{\nu}]=iQ^{\mu\nu}, \quad [q^{\mu},Q^{\nu,\rho}]=0,$$

where

$$jSp(\boldsymbol{Q}) = \boldsymbol{\Sigma} = \{ \boldsymbol{\sigma} : \boldsymbol{\sigma} = \boldsymbol{\Lambda} \boldsymbol{\sigma}_{0} \boldsymbol{\Lambda}^{t}, \boldsymbol{\Lambda} \in \boldsymbol{\mathscr{L}} \}.$$

Motivations: cf preceding talk. Covariance:

$$U(a,\Lambda)^{-1}q^{\mu}U(a,\Lambda) = \Lambda^{\mu}{}_{\mu'}q^{\mu'} + a^{\mu},$$
$$U(a,\Lambda)^{-1}Q^{\mu\nu}U(a,\Lambda) = \Lambda^{\mu}{}_{\mu'}\Lambda^{\nu}{}_{\nu'}Q^{\mu'\nu'}$$

Weyl quantisation:

$$W(f)=\int dk\check{f}(k)e^{ikq}.$$

Problem with twisted product: they depend on an operator Q, not on a C-number matrix. Need more general symbols.

Algebra of generalised symbols

Symbol in Fourier space:

$$\varphi: \Sigma \to L^1(\mathbb{R}^4)$$
 continuous, vanish at ∞

Generalised twisted product:

$$(\varphi \tilde{\times} \psi)(\sigma; \mathbf{k}) = \int d\mathbf{k} \, \varphi(\sigma; \mathbf{h}) \psi(\sigma; \mathbf{k} - \mathbf{h}) \mathbf{e}^{-\frac{i}{2}\mathbf{h}\sigma\mathbf{k}}$$

Involution and norm:

$$\|\varphi\| = \sup_{\sigma} \|\varphi(\sigma; \cdot)\|_{L^1}, \quad \varphi^*(\sigma; k) = \overline{\varphi(\sigma; -k)}.$$

Action of Poincaré group:

$$(\alpha(a,\Lambda)\varphi)(\sigma;k) = (\det\Lambda)e^{-ika}\varphi(\Lambda^{-1}\sigma\Lambda^{-1};\Lambda^{-1}k).$$

N.B. maps each fibre over sigma onto the fibre onto $\varphi_{\pm}^{\prime} = 4 \sigma \Lambda_{\pm}^{t}$

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DFR C*algebra, and symbol calculus

Theorem [DFR 95]; there is a unique C*-norm; the corresponding C*-completion is isomorphic (as a continuous field of C*-algebras) to $\mathcal{C}_0(\Sigma, \mathcal{K})$, \mathcal{K} =compact operators.

Representation of the algebra:

$$\pi(arphi) = \int dk arphi({m Q};k) {m e}^{ikq}$$

(replacement $\sigma \rightarrow Q$ understood as functional calculus). Relation with Weyl quantisation:

$$W(f) = \pi(\check{f}).$$

Symbol calculus:

$$W(f)W(g) = W(f \star_Q g),$$

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A certain class of localisation states

A localisation state is a linear functional formally written as

$$\varphi \mapsto \iint d\sigma \, dk \, K(\sigma; k) \varphi(\sigma; k)$$

with K such to ensure positivity and normalisation. We are interested in states with kernel of the form

$$K(\sigma; k) = \delta(\sigma - \theta) w(k),$$

which give

$$\varphi \mapsto \int dk \, w(k) \varphi(\theta; k)$$

More cleanly: we define the projection on the fibre over θ :

$$\Pi_{\theta}[\varphi](k) = \varphi(\theta; k);$$

extend it by continuity to a map $\Pi_{\theta} : \mathcal{C}(\Sigma, \mathcal{K}) \to \mathcal{K}$. Then we are interested in the states of the form $\omega \circ \Pi_{\theta}$ with $\omega \in \mathcal{S}(\mathcal{K})$.

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We now make an additional assumption: while in the DFR model all localisation states are available to each observer,

θ -universality.

- There is a privileged class of observers;
- The privileged observers are connected by Λ's in the stabiliser of θ;
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Twisted Covariance Recovered

The privileged observer can test the algebra only at θ ; he only sees θ -twisted products:

$$\Pi_{\theta}\varphi\tilde{\times}\psi = (\Pi_{\theta}\varphi)\times_{\theta}(\Pi_{\theta}\psi)$$

Let

$$\varphi'(\sigma; k) = (\det \Lambda)\varphi(\Lambda^{-1}\sigma\Lambda^{-1}; \Lambda^{-1}k)$$

be the Lorentz transform of φ , and analogously for ψ' ; the (possibly) unprivileged primed observer only sees the fibre over $\theta' = A\theta A^t$:

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Interlude Many Events

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Different inequivalent possibilities for defining polylocal products:

- Translations: f(q)f(q + a₂)f(q + a₃) ···; investigated in DFR. Feature: they depend on one single localisation state.
- Independent coordinates: [q_j^μ, q_k^μ] = iδ_{jk}Q^{μν}; investigated in P,BDFP. They naturally lead to ultraviolet finite theories. Note that [q_j, q_j] = iQ does not depend on *j*; corresponds to tensor products of *Z*-moduli. Irreps:

$$q_1 = q_\sigma \otimes I \otimes I \cdots, \quad q_2 = I \otimes q_\sigma \otimes \cdots, \quad \cdots$$

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"No Relations without Representation!"

Problem with Fiore Wess coordinates: assume q_j regular irrep, then:

$$[q_j^{\mu}, (q_k - q_l)^{\nu}] = 0$$
 strongly

hence by Schur's Lemma:

$$q_k - q_l = b_{kl} \in \mathbb{R}^4.$$

Set

 $a_j = b_{j1}$

so that

$$q_j = q_1 + a_j$$

There is only one set of 4 coordinates; all the other sets are just translates of the basic coordinates of a single event.

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Moreover, we have seen that the latter is equivalent to (DFR model + θ -universality).

Now one may raise the question: which are the physical motivations for restricting the admissible localisation states? Namely why θ ?

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Let me more precise by means of a trivial example: consider Newton laws for motions of a point mass in the 3-space. Let's say that we state *z*-universality: the preferred observers only can see motions with z(0) > 0. Then we may distinguish the privileged observers from unprivileged ones; e.g. Jane, who is rotated by 180° around *x* axis, only sees z'(0) < 0.

The principle of relativity requires instead that, together with each admissible state, all the states which can be reached by a symmetry of the system must be available to all observers, including the privileged ones.

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