

Introduction to Symplectic Geometry : Lecture 23

November 17, 2021

Moment polytopes

- Convexity theorem (Atiyah, Guillemin-Sternberg) : Let $T = (S^1)^n$ be a torus, and let (X, ω, T, μ) be a compact connected T -Hamiltonian space. Then
 - ▶ the level set $\mu^{-1}(c)$ is connected for any $c \in \mathfrak{t}^\vee$,
 - ▶ the image $\mu(X)$ is convex,
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- Last time : examples of moment polytopes for torus actions on $\mathbb{P}^1, \mathbb{P}^2, \mathbb{P}^n$.
- Last time : Restricting to the action of a sub-torus $T_1 \subset T$ amounts to projecting the moment polytope by the map $i^* : \mathfrak{t}^\vee \rightarrow \mathfrak{t}_1^\vee$.

Quotienting

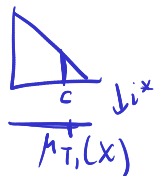
- Consider the action of $T = (S^1)^2$ on \mathbb{P}^2

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Let

$$T_1 := \{(\theta, 1) \in T\}, \quad T_2 := \{(1, \theta) \in T\}.$$

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$$(\mu_{T_1} = i^* \circ \mu_T)$$

Quotienting

$$T = T_1 \times T_2$$

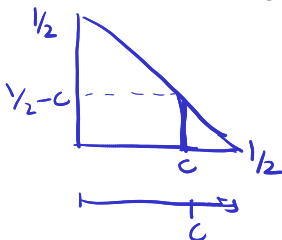
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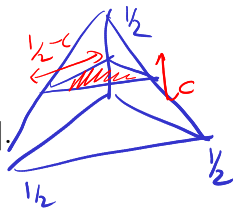
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$$\mu^{-1}(F) \simeq \mathbb{P}^2$$



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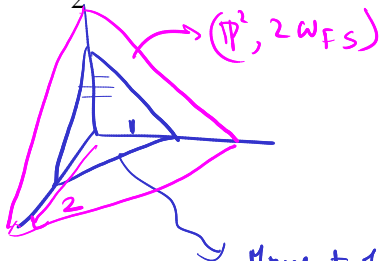
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- Consider the standard action of $(S^1)^3$ on \mathbb{C}^3 with moment map

$$\mathbb{C}^3 \rightarrow \mathbb{R}^3, \quad (z_1, z_2, z_3) \mapsto \frac{1}{2}(|z_1|^2, |z_2|^2, |z_3|^2).$$

$$\mu(\mathbb{C}^3) = (\mathbb{R}_+)^3$$



$$\{\sum |z_i|^2 = 1\}$$

Moment polytope
of $(\mathbb{P}^2, \omega_{FS})$
with action
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- Performing reduction at a different level, say $\{|z_1|^2 + |z_2|^2 + |z_3|^2 = 2\}/T_1$, gives a triangle with twice the dimensions.

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$$(\mathbb{R}/2\pi\mathbb{Z})^n$$

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- For a Hamiltonian space (M, ω, T, μ) the action

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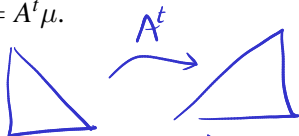
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 $\{\mu_i \in \mathfrak{t}_{\mathbb{Z}}^v\}$ is a \mathbb{Z} -basis

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$$M = \mathbb{Z}$$

$$\mathbb{Z} \mapsto \frac{1}{2} (|\mathbb{Z}|^2 \times 2)$$

$$S^1 \hookrightarrow \mathbb{C}$$

$$\mathbb{Z} \xrightarrow{\theta} e^{2i\theta} \mathbb{Z}$$

not effective

$\pi \in S^1$ fixes all points in \mathbb{C} .

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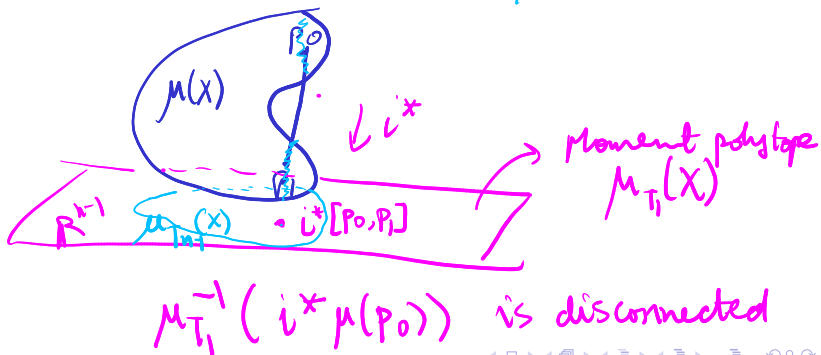
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- Idea of proof : If $\mu(X)$ is not convex there exist points $p_0, p_1 \in \mu(X)$ such that $\{(1-t)p_0 + tp_1\} \not\subset \mu(X)$.

$$\mu_{T_{n-1}} : X \rightarrow \mathbb{R}^{n-1}$$



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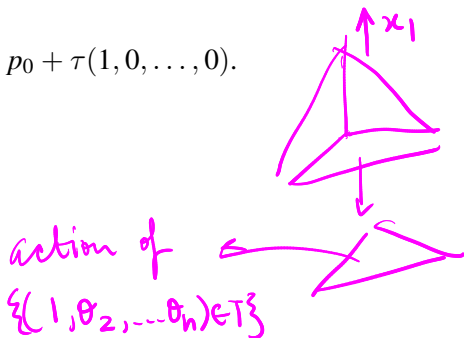
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- Proof : First assume that $p_1 = p_0 + \tau(1, 0, \dots, 0)$. Let $T_{n-1} := \{(1, t_2, \dots, t_n) \in T\}$. The moment map of the T_{n-1} -action is $\mu_{T_{n-1}} := i^* \circ \mu$ where

$$i^* : \mathbb{R}^n \rightarrow \mathbb{R}^{n-1}, \quad (x_1, \dots, x_n) \mapsto (x_2, \dots, x_n).$$

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Then $\mu_{T_{n-1}}^{-1}((x_2, \dots, x_n)(p_0))$ is disconnected.

Proof of convexity theorem, Part 1

Connectedness implies convexity.

- A non-zero vector $v \in \mathbb{Z}^n$ is **primitive** if there is no pair $t \in \mathbb{Z}_{>1}, v' \in \mathbb{Z}^n$ such that $v = tv'$.

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$(6,8)$
eg $(2,0)$ is not primitive

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 $v = (v_1, \dots, v_n)$ is primitive \Leftrightarrow
 $\gcd(v_1, \dots, v_n) = 1$
- Result on lattices : For any non-zero primitive vector v , there is a base change $A \in \text{GL}(n, \mathbb{Z})$ such that $Av = (1, 0, \dots, 0)$.

$$v = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \quad \gcd(v_1, v_2) = 1$$

$$\exists \alpha, \beta \in \mathbb{Z} : \alpha v_1 + \beta v_2 = 1$$

$$\begin{pmatrix} \alpha & \beta \\ -v_2 & v_1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Need : $p_1 - p_0 = T * \text{primitive vector} \in \mathbb{R}$

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- Result on lattices : For any non-zero primitive vector v , there is a base change $A \in GL(n, \mathbb{Z})$ such that $Av = (1, 0, \dots, 0)$.
- Proof of convexity : By wiggling p_1 , we can assume that $p_1 - p_0 \in \mathbb{Q}^n$, and so, is a multiple of a primitive vector. \square

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The proof of connectedness of fibers of μ is by induction on $\dim(T)$. The base case of $T = S^1$ is proved using Morse theory.

Detour into Morse theory

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- For a critical point p , the Hessian is symmetric. For a non-degenerate critical point, H_p has k negative eigen-values and $(n - k)$ positive eigen-values. Define the index of p as k .

Detour into Morse theory

a is a max $\text{ind}(a) = n$

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- obs $a \in M$ is a min of f $\text{ind}(a) = 0$ $f(x) = f(p) + x_1^2 + \dots + x_n^2$*
- Lemma of Morse : In a neighborhood of a critical point p , there are coordinates (x_1, \dots, x_n) such that

$$f(x) = f(p) - x_1^2 - \dots - x_k^2 + x_{k+1}^2 + \dots + x_n^2.$$

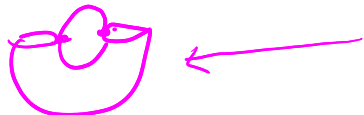
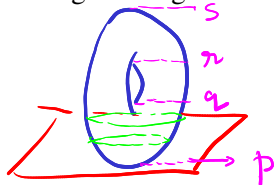
- Observation : Critical points of a Morse function are isolated.

Detour into Morse theory

- Classical Morse theory question : How does the homotopy type of

$$M_a := f^{-1}(-\infty, a] = \{f \leq a\}$$

change as we vary a ? Consider the example of the standing torus with f being the height function.



$$a < p$$

$$p \leq a < q$$

$$q \leq a < r$$

$$r \leq a < s$$

$$s \leq a$$

$$M_a = \phi$$

$$M_a = \text{disk}$$

0-cell

$$M_a = \text{0-cell} + \text{1-cell}$$

↓ + 1-cell

$$M_a = T$$

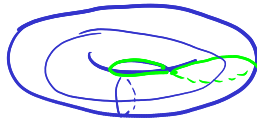
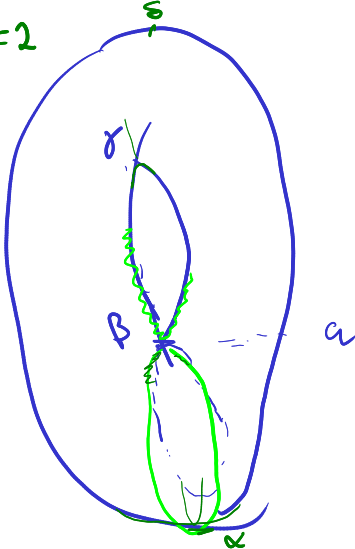
β

$$\text{ind}(\delta) = 2$$

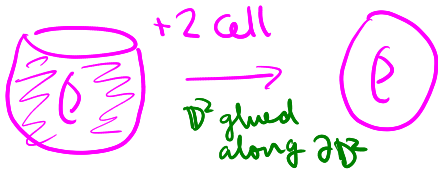
$$\text{ind}(\alpha) = 1$$

$$\text{ind}(\beta) = 1$$

$$\text{ind}(\alpha) = 0$$



$$df(\beta) = df(\alpha) = 0$$



Detour into Morse theory

- Classical Morse theory question : How does the homotopy type of

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- Theorem :

- 1 If there are no critical points in $[a, b]$ then M_a is diffeomorphic to M_b .

Detour into Morse theory

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- Theorem :

- 1 If there are no critical points in $[a, b]$ then M_a is diffeomorphic to M_b .
- 2 If $a \in \text{crit}(f)$ and the index of a is k , $M_{a+\epsilon}$ is homotopy equivalent to $M_{a-\epsilon}$ with a k -cell attached.