

Solutions to Home-work 7

1.

$$\begin{aligned}T(0 + 0) &= T0 \\ \Rightarrow T0 + T0 &= T0 \\ \Rightarrow T0 &= 0\end{aligned}$$

2.

$$Tu = Tv \Leftrightarrow T(u - v) = 0$$

and

$$u = v \Leftrightarrow u - v = 0$$

3. This was done in the lecture:

$$R_\theta \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$$

by definition of the trigonometric (=circular) functions, while an in argument involving congruent triangles yields

$$R_\theta \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}$$

Hence, the matrix representing R_θ is given by

$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

4.

$$\begin{aligned}R_{\theta+\phi} &= R_\theta R_\phi \\ &= \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \cdot \begin{bmatrix} \cos \phi & \sin \phi \\ -\sin \phi & \cos \phi \end{bmatrix} \\ &= \begin{bmatrix} \cos \theta \cos \phi - \sin \theta \sin \phi & \sin \theta \cos \phi + \cos \theta \sin \phi \\ -(\sin \theta \cos \phi + \cos \theta \sin \phi) & \cos \theta \cos \phi - \sin \theta \sin \phi \end{bmatrix}\end{aligned}$$

and hence, we see that

$$\begin{aligned}\cos(\theta + \phi) &= \cos \theta \cos \phi - \sin \theta \sin \phi \\ \sin(\theta + \phi) &= \sin \theta \cos \phi + \cos \theta \sin \phi\end{aligned}$$

5.

$$MR_\theta = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$$

while

$$R_\theta M = \begin{bmatrix} \cos \theta & -\sin \theta \\ -\sin \theta & -\cos \theta \end{bmatrix}$$

and hence

$$MR_\theta = R_\theta M \Leftrightarrow \sin \theta = 0 \Leftrightarrow \theta = n\pi$$

6. It is clear that the equation

$$T(a + ib) = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

defines a 1-1 mapping T of \mathbb{C} onto its image and that T is (real-) linear, meaning that, for any $\alpha_i, a_i, b_i \in \mathbb{R}, i = 1, 2$,

$$\begin{aligned} T(\alpha_1(a_1 + ib_1) + \alpha_2(a_2 + ib_2)) &= T((\alpha_1 a_1 + i\alpha_1 b_1) + (\alpha_2 a_2 + i\alpha_2 b_2)) \\ &= T((\alpha_1 a_1 + \alpha_2 a_2) + i(\alpha_1 b_1 + \alpha_2 b_2)) \\ &= \begin{bmatrix} \alpha_1 a_1 + \alpha_2 a_2 & -\alpha_1 b_1 - \alpha_2 b_2 \\ \alpha_1 b_1 + \alpha_2 b_2 & \alpha_1 a_1 + \alpha_2 a_2 \end{bmatrix} \\ &= \alpha_1 \begin{bmatrix} a_1 & -b_1 \\ b_1 & a_1 \end{bmatrix} + \alpha_2 \begin{bmatrix} a_2 & -b_2 \\ b_2 & a_2 \end{bmatrix} \\ &= \alpha_1 T(a_1 + ib_1) + \alpha_2 T(a_2 + ib_2) ; \end{aligned}$$

while

$$\begin{aligned} T(a_1 + ib_1) \times T(a_2 + ib_2) &= \begin{bmatrix} a_1 & -b_1 \\ b_1 & a_1 \end{bmatrix} \times \begin{bmatrix} a_2 & -b_2 \\ b_2 & a_2 \end{bmatrix} \\ &= \begin{bmatrix} a_1 a_2 - b_1 b_2 & -a_1 b_2 - a_2 b_1 \\ a_1 b_2 + a_2 b_1 & a_1 a_2 - b_1 b_2 \end{bmatrix} \\ &= T((a_1 a_2 - b_1 b_2) + i(\bar{a}_1 b_2 + a_2 b_1)) \\ &= T((a_1 + ib_1)(a_2 + ib_2)) , \end{aligned}$$

so T also preserves products.