



Spins, Games and Networks

CONGESTION AND TRAFFIC ROUTING

Sushmita Gupta

23rd December, 2024

Games in the wild

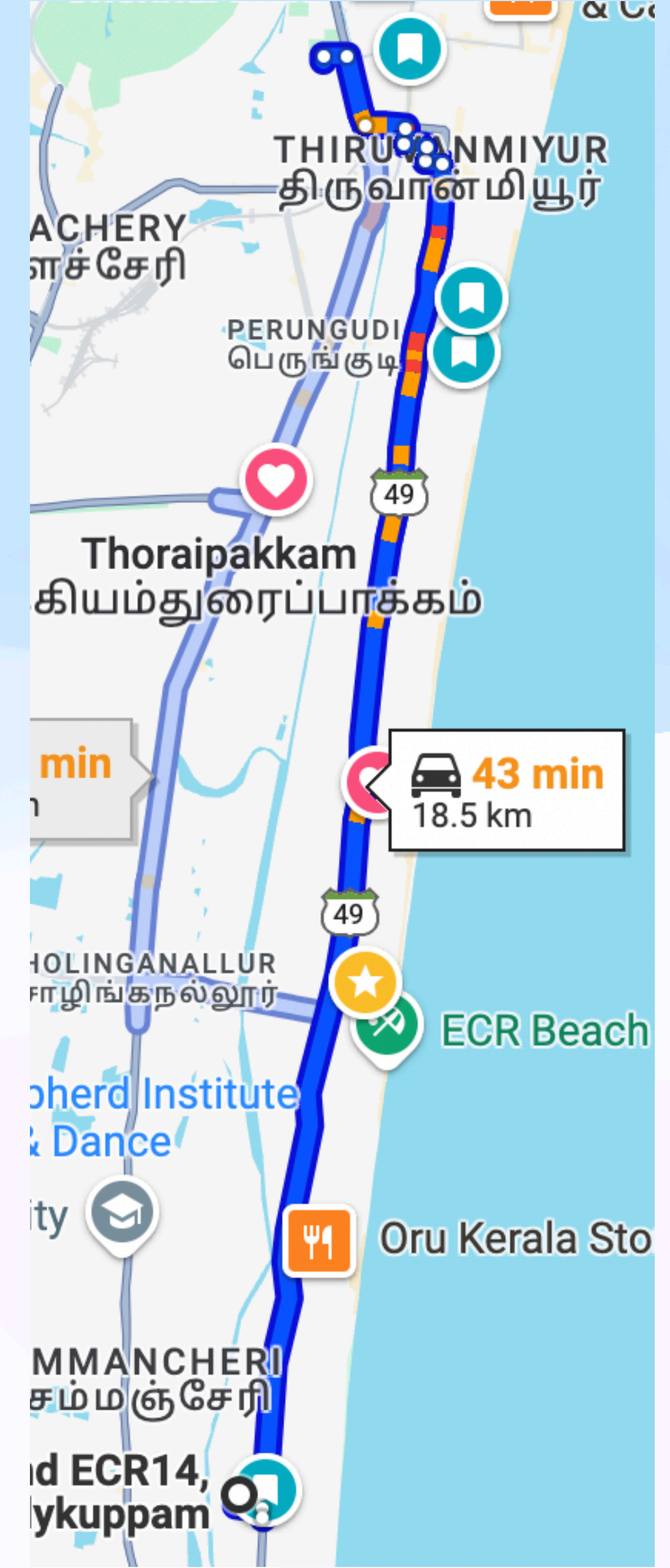
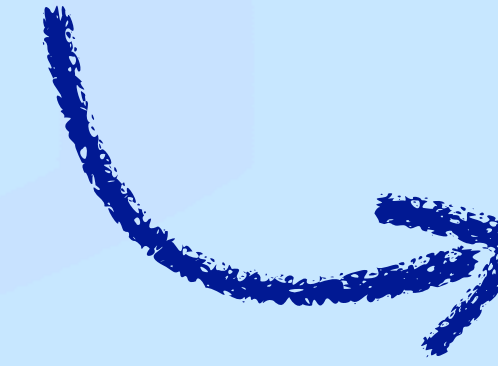
Games in the wild



So what is a (congestion) game ?

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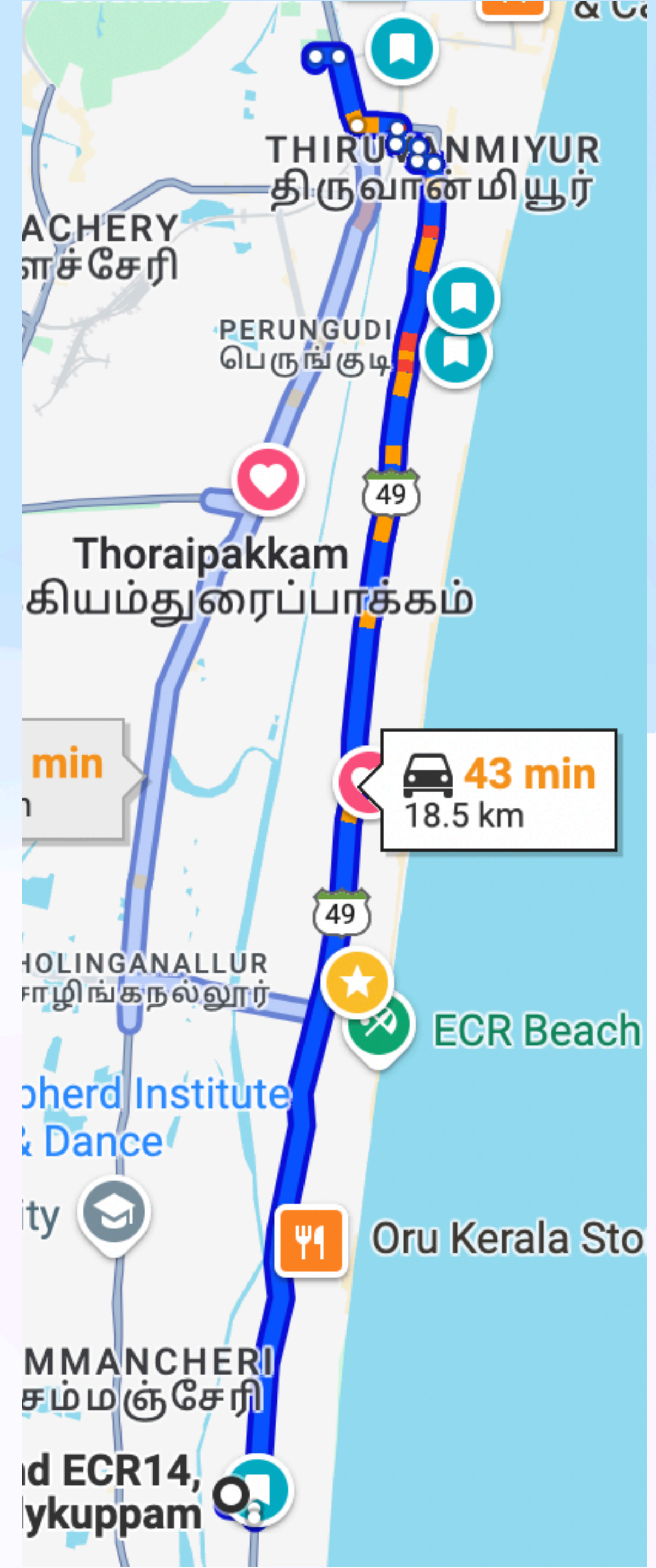
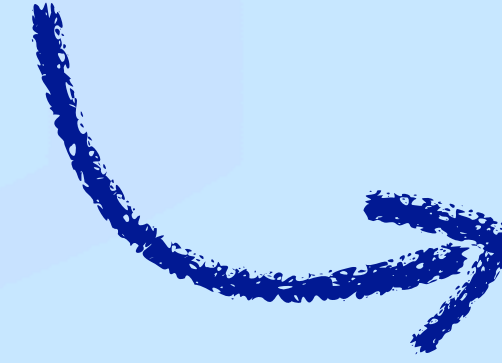
This map will give us
the answer



So what is a (congestion) game ?

When a situation consists of entities:

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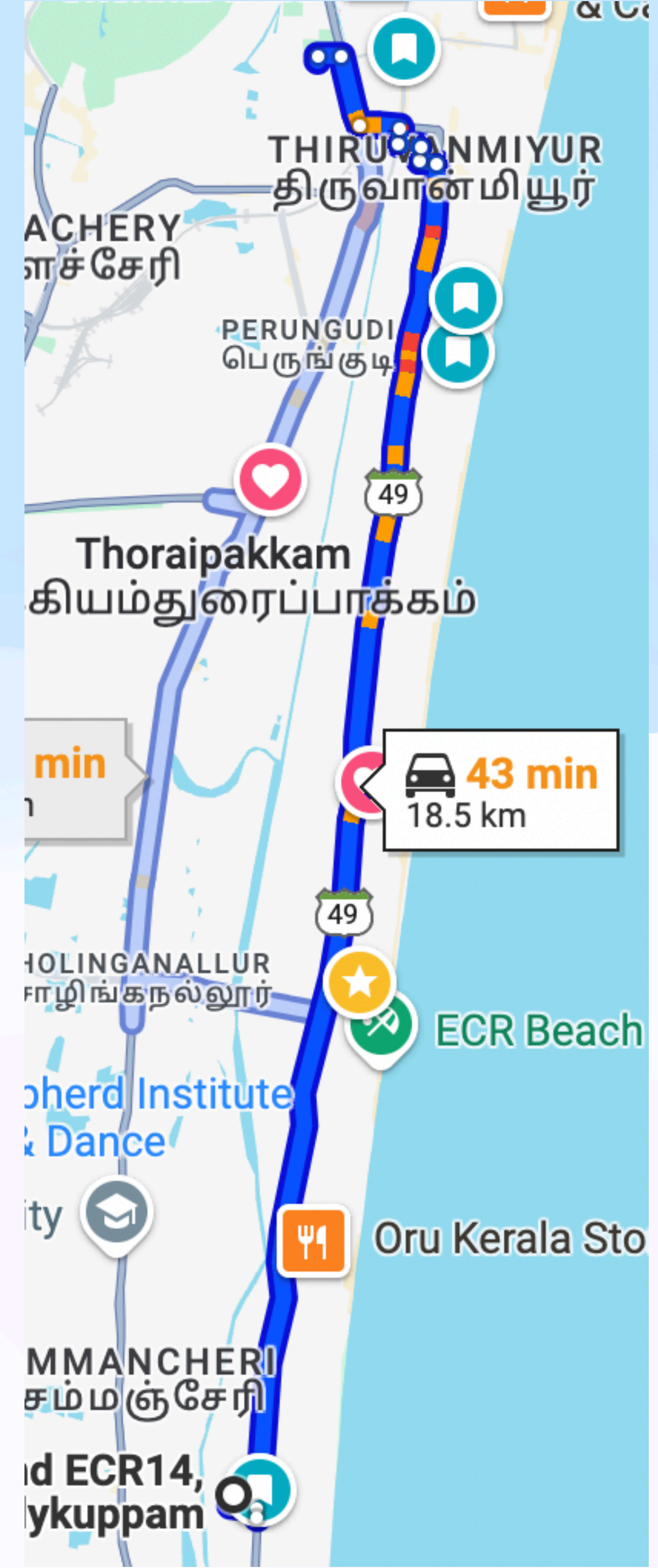


So what is a (congestion) game ?

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When a situation consists of entities:

- whose behaviour is not entirely predictable

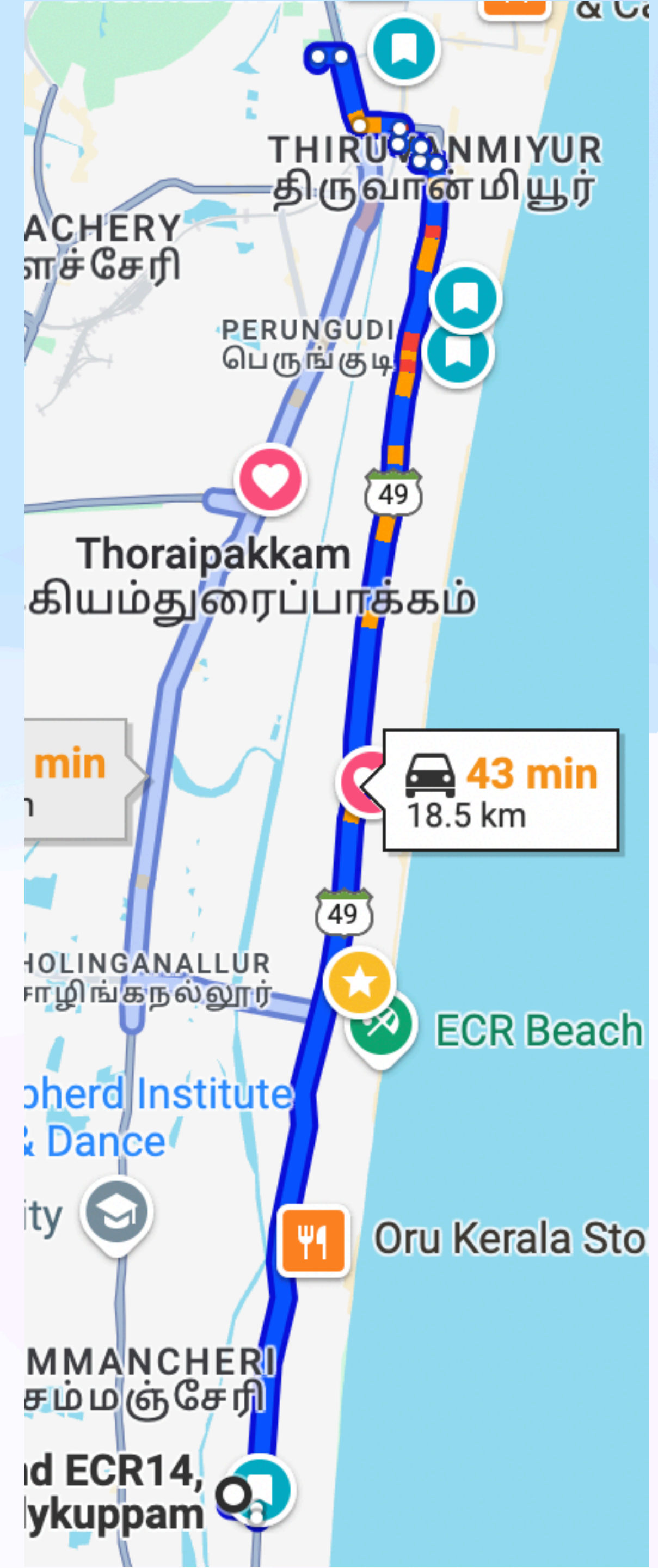


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When a situation consists of entities:

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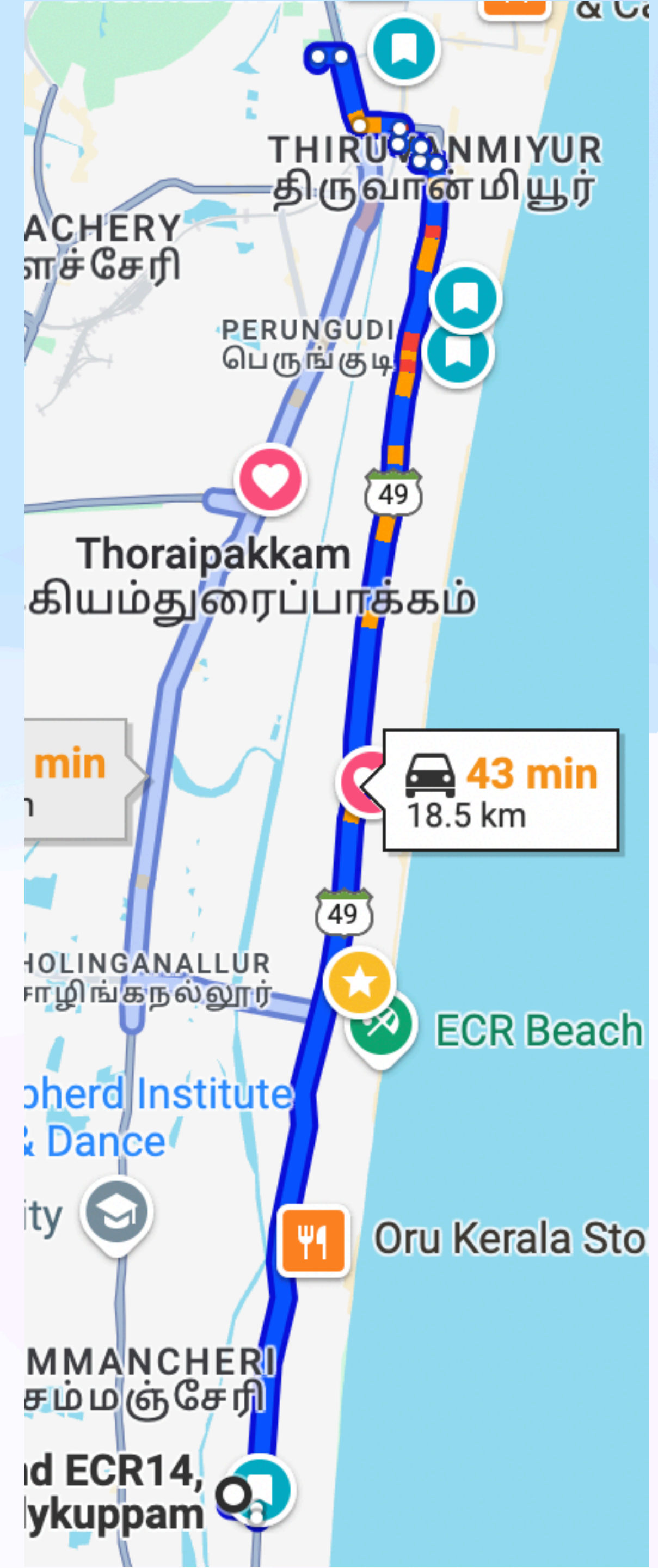


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When a situation consists of entities:

- whose behaviour is not entirely predictable
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- And its behaviour can differ based on (knowledge) of other people's behavior



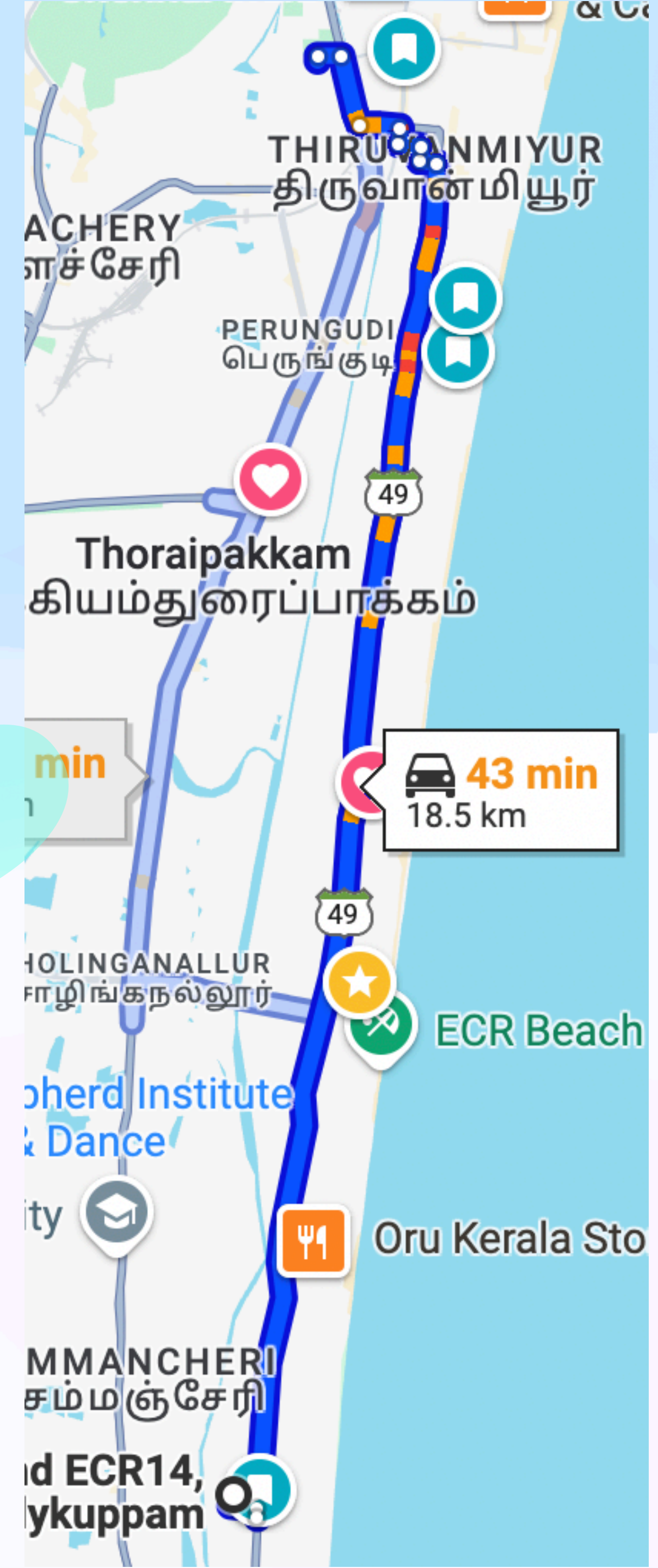
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Strategic Behavior



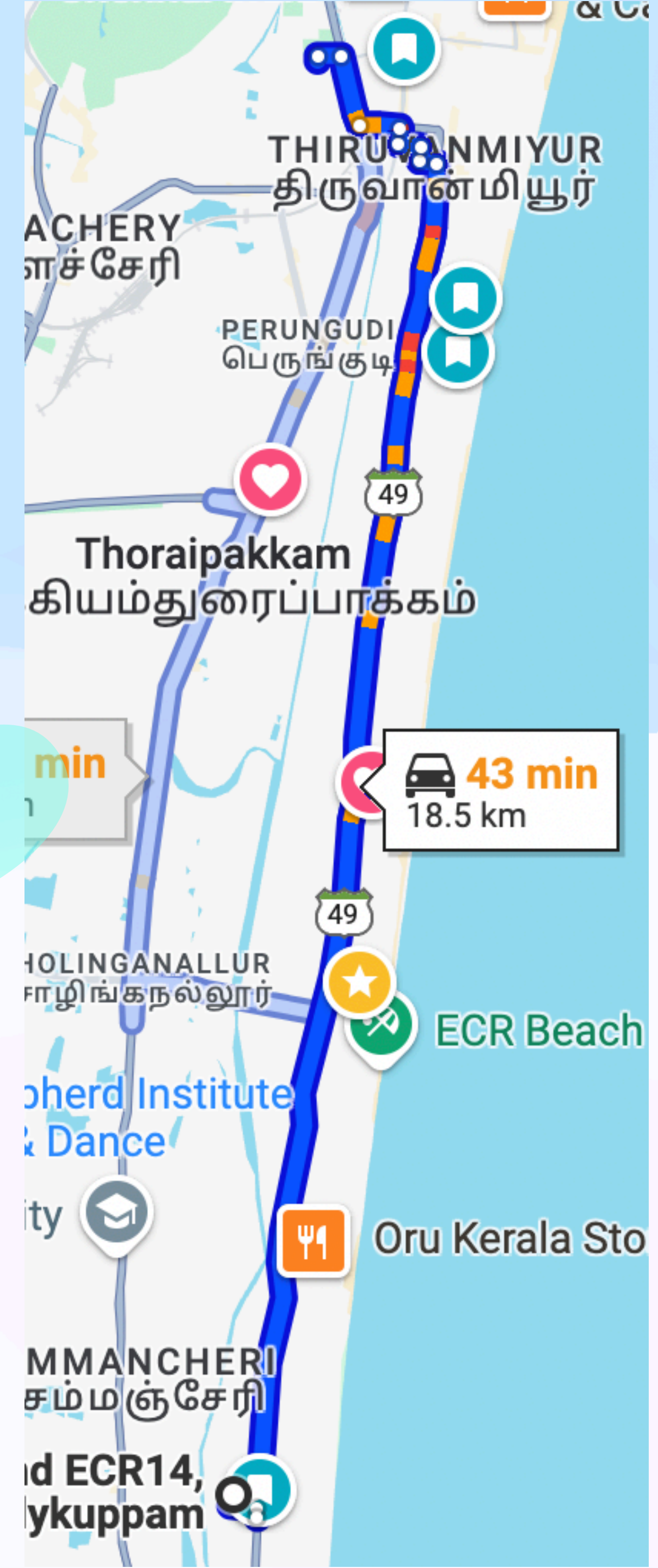
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When a situation consists of entities:

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When the outcome of one depends on the actions of other...we have a game!



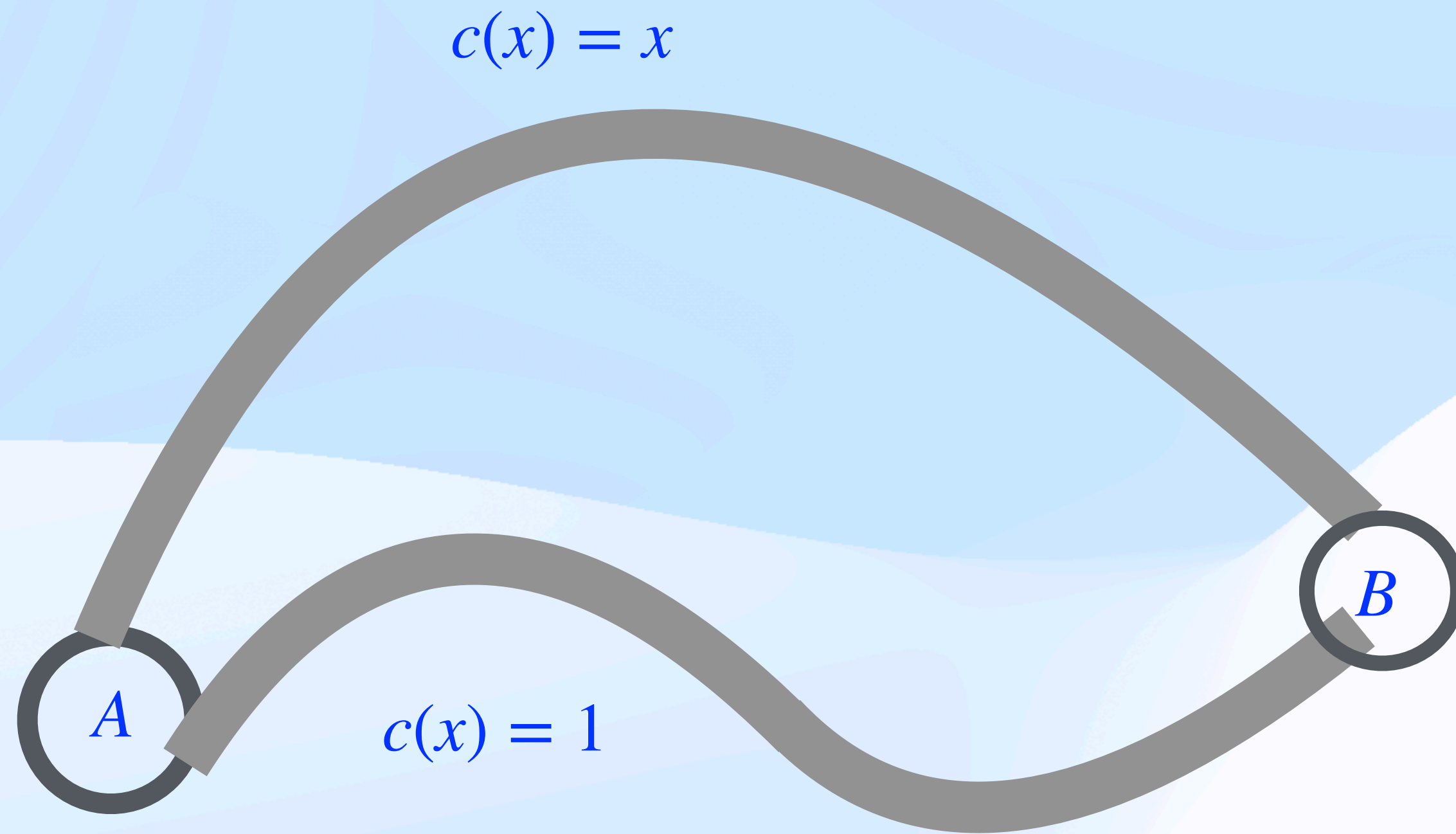
Let's try to understand this
phenomenon

*Let's try to understand this
phenomenon*

Pigou's Network 1920

Let's try to understand this phenomenon

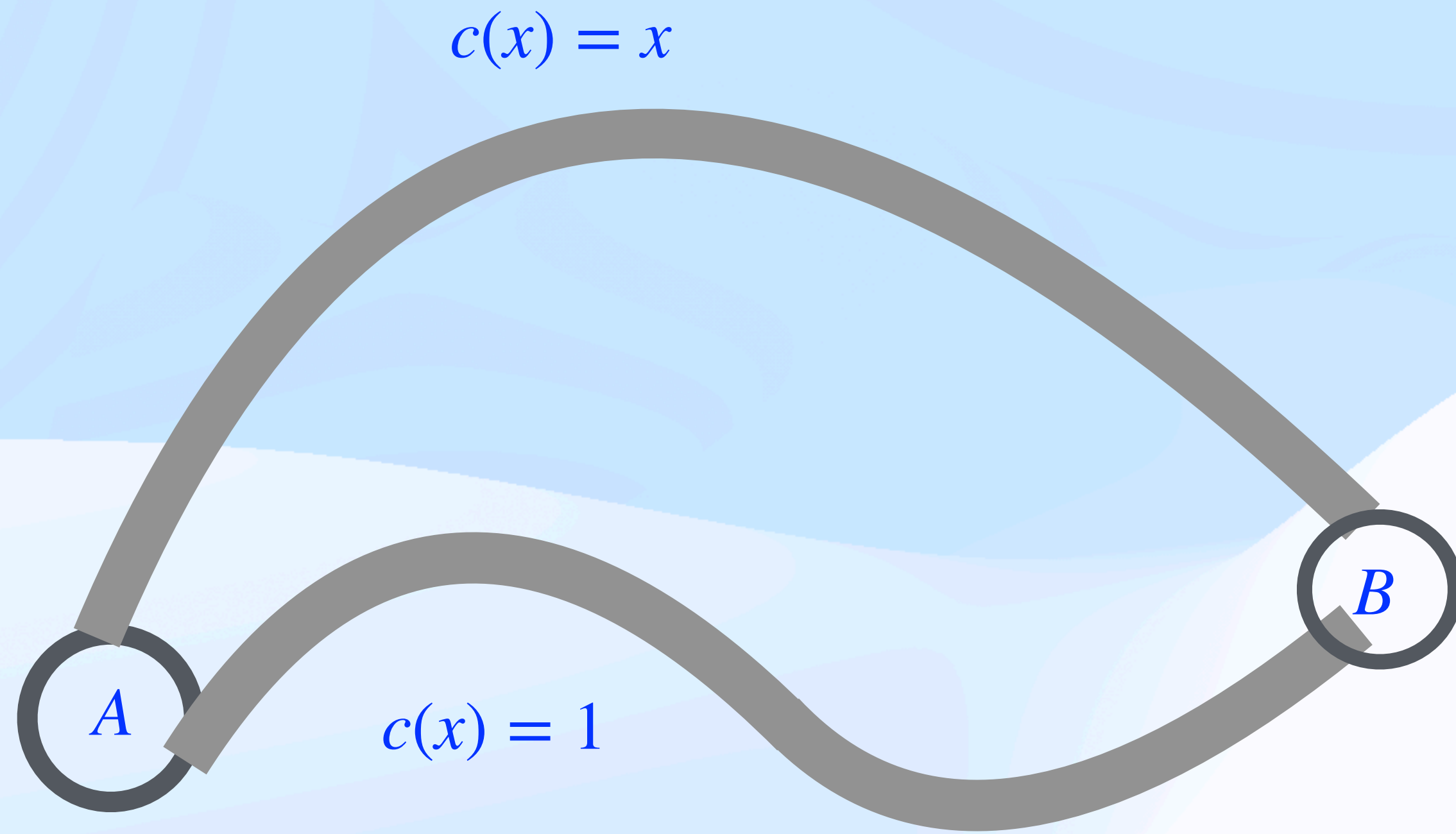
Pigou's Network 1920



Let's try to understand this phenomenon

Pigou's Network 1920

1 unit of traffic



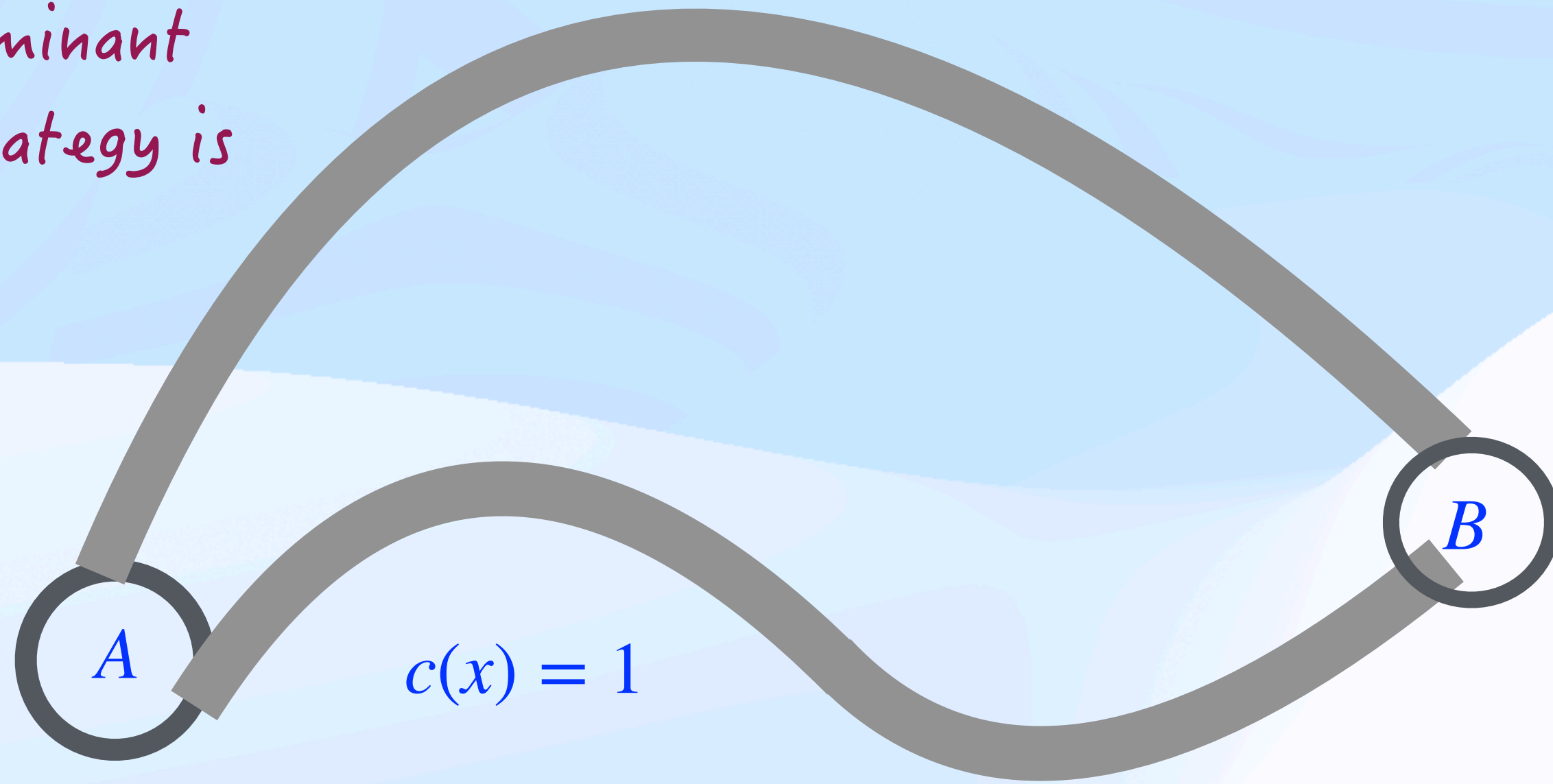
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$$c(x) = x$$

Dominant Strategy is



Let's try to understand this phenomenon

Pigou's Network 1920

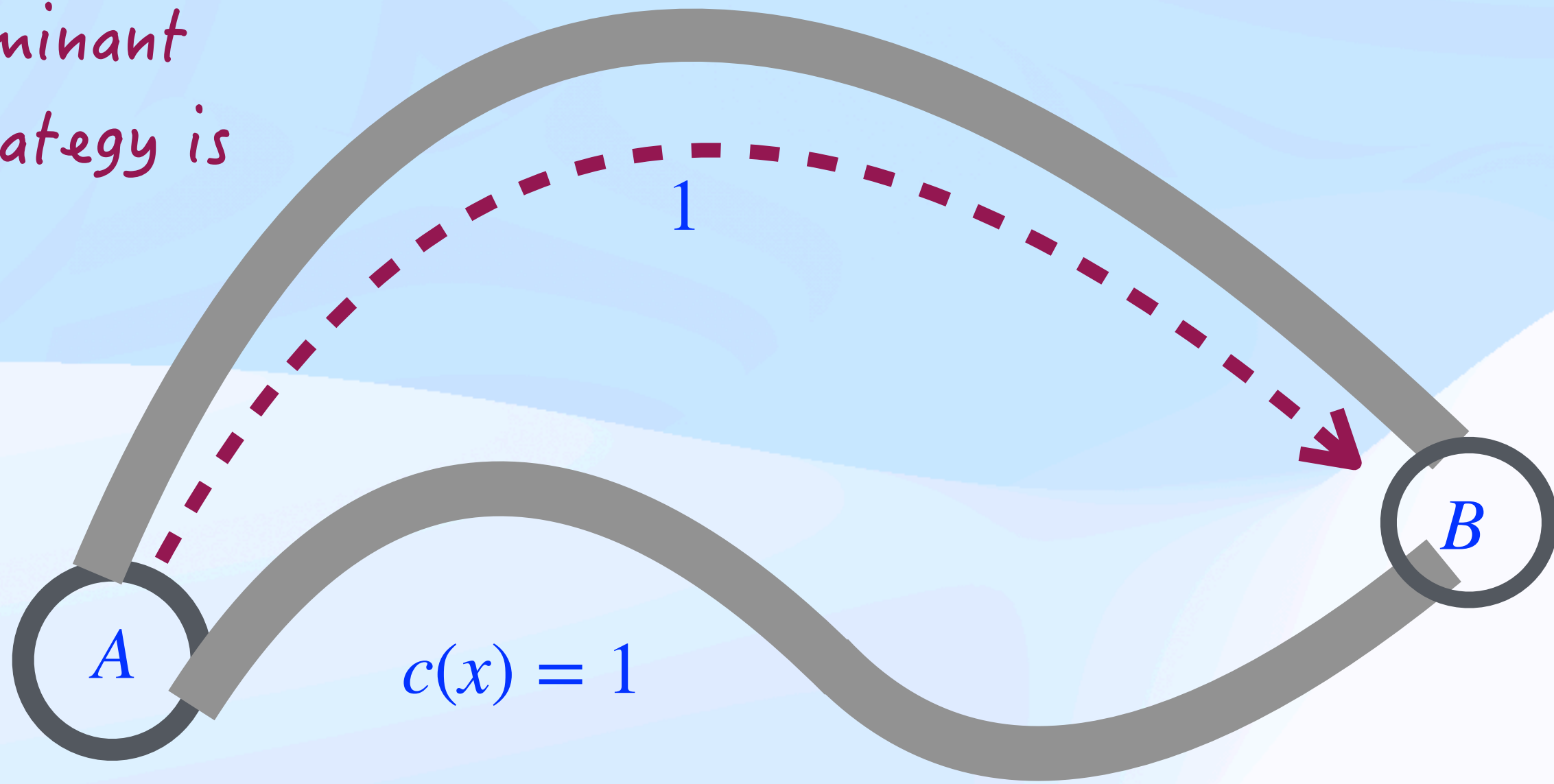
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Dominant Strategy is

1

$$c(x) = 1$$



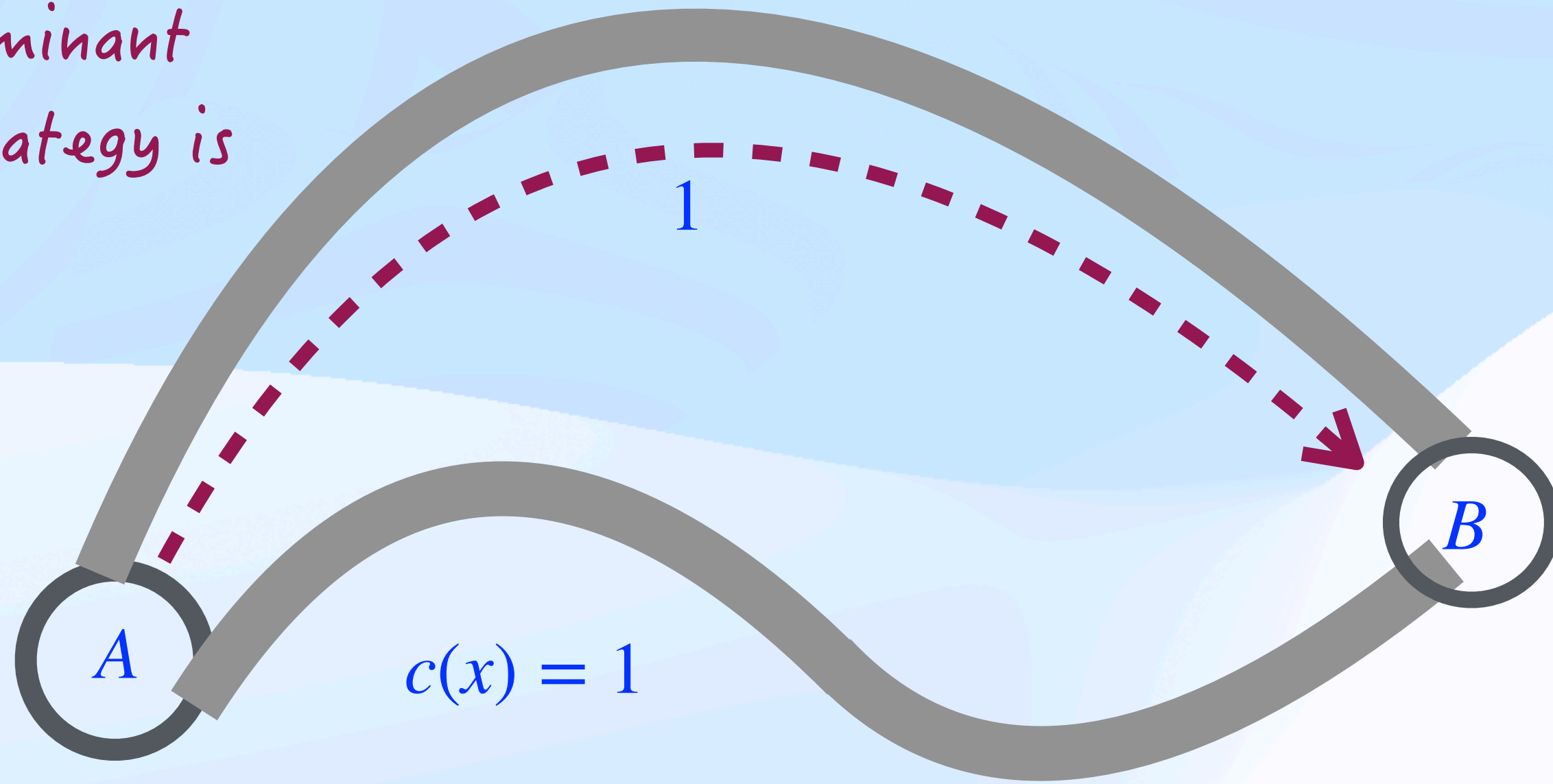
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Expected travel time in DS equilibria
 $= 1 \cdot 1 = 1$

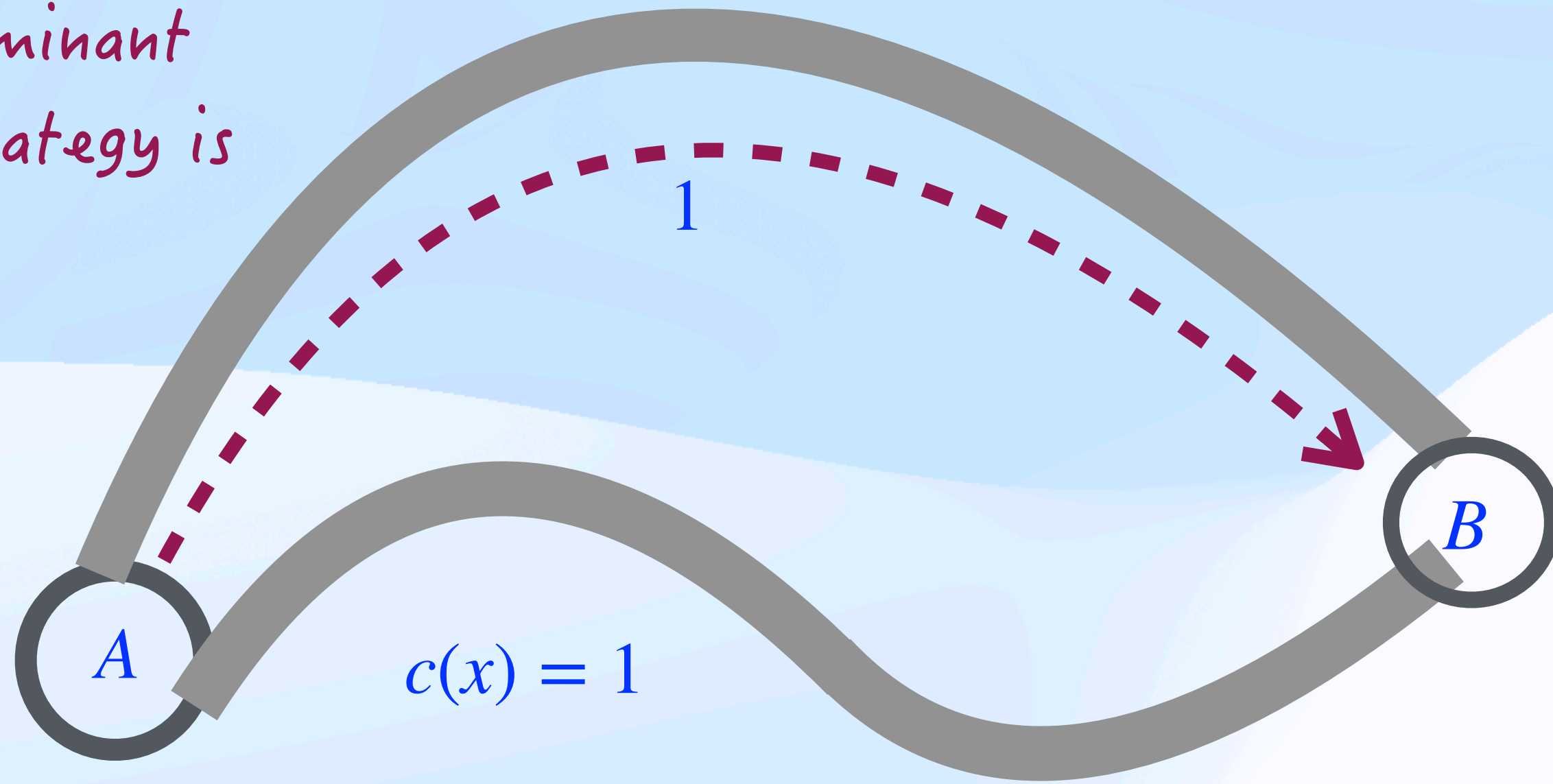
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Q: Is this the ideal outcome ?

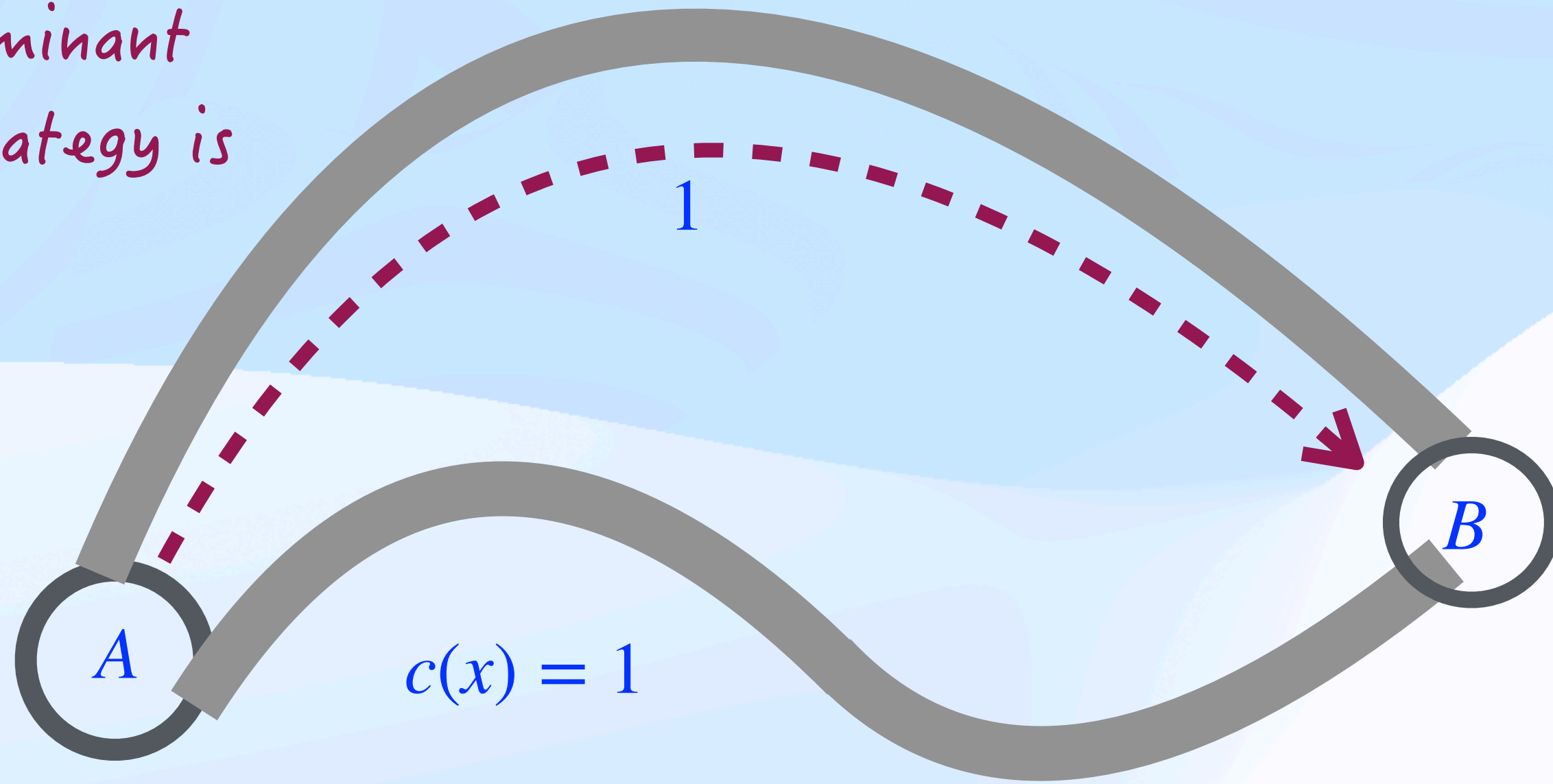
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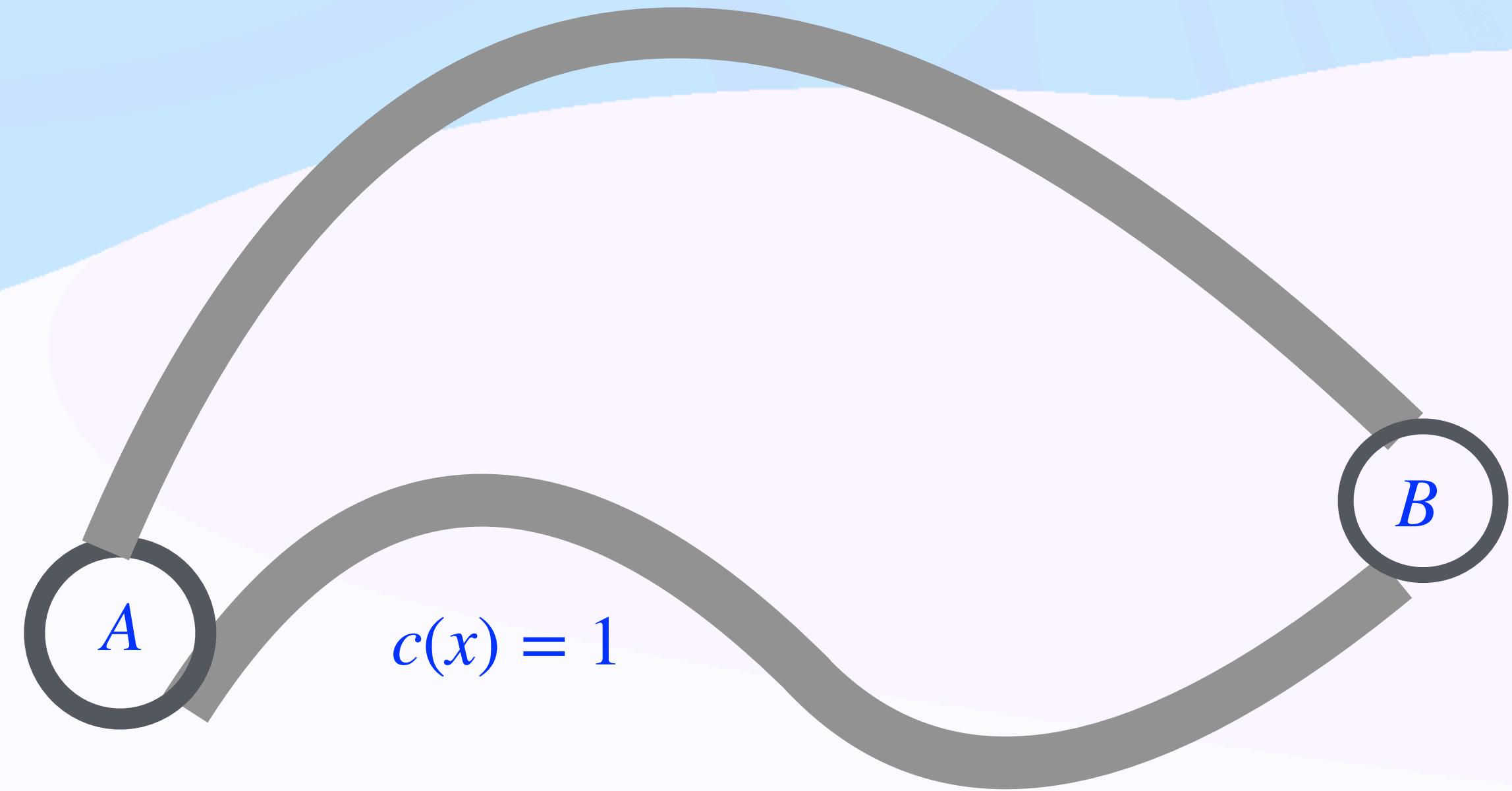
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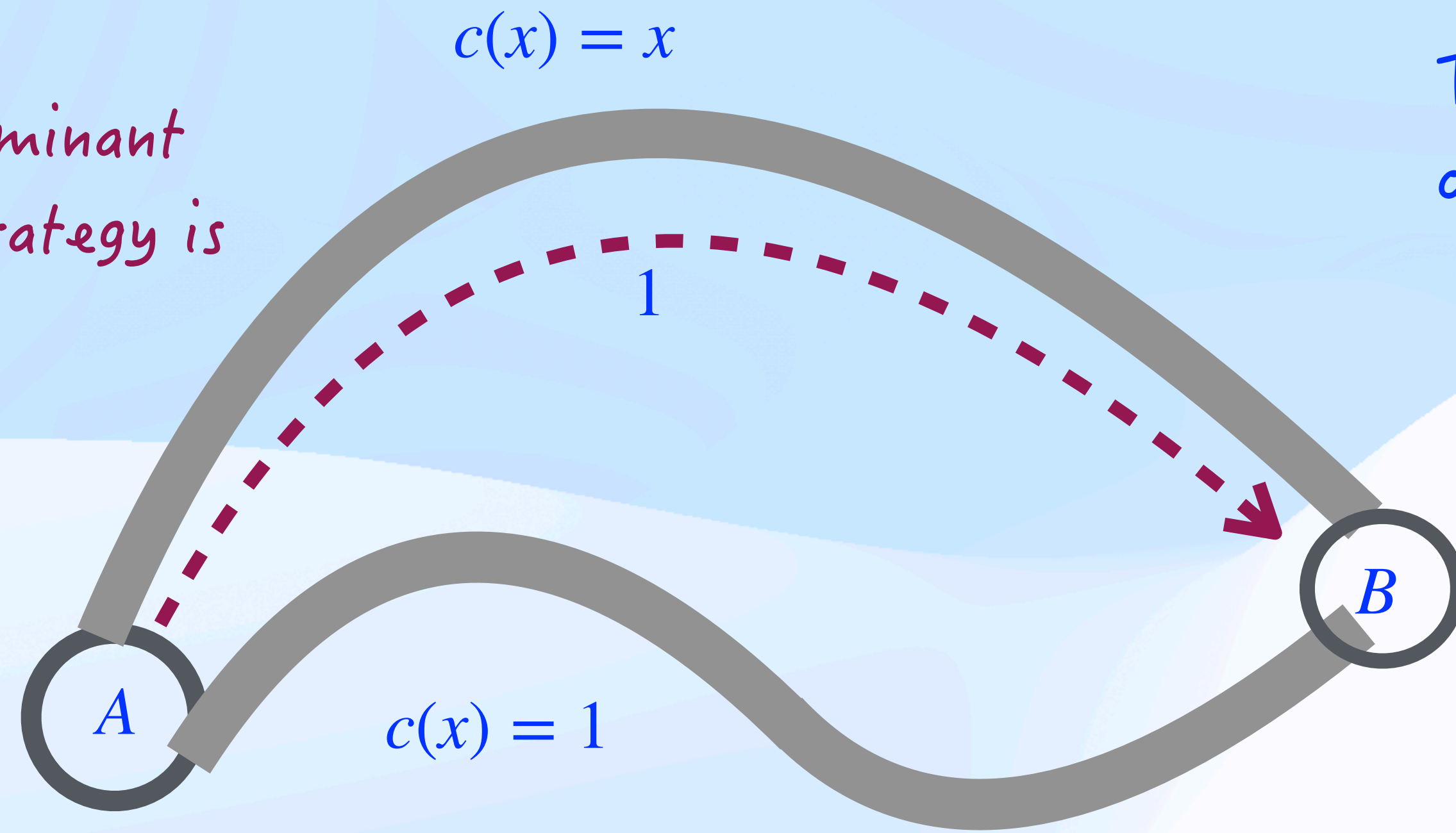
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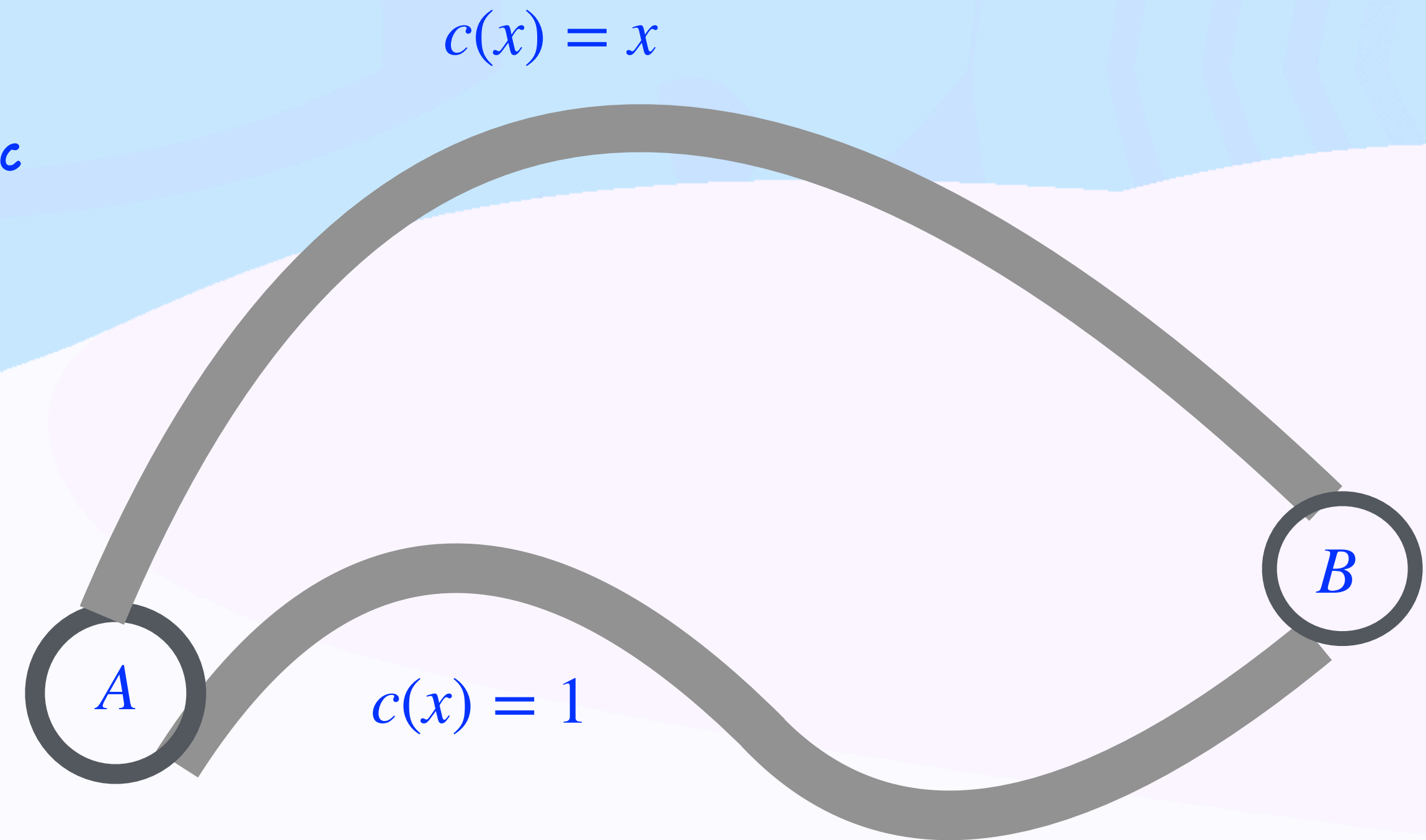
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Dominant Strategy is



Expected travel time in DS equilibria
 $= 1 \cdot 1 = 1$

Traffic control



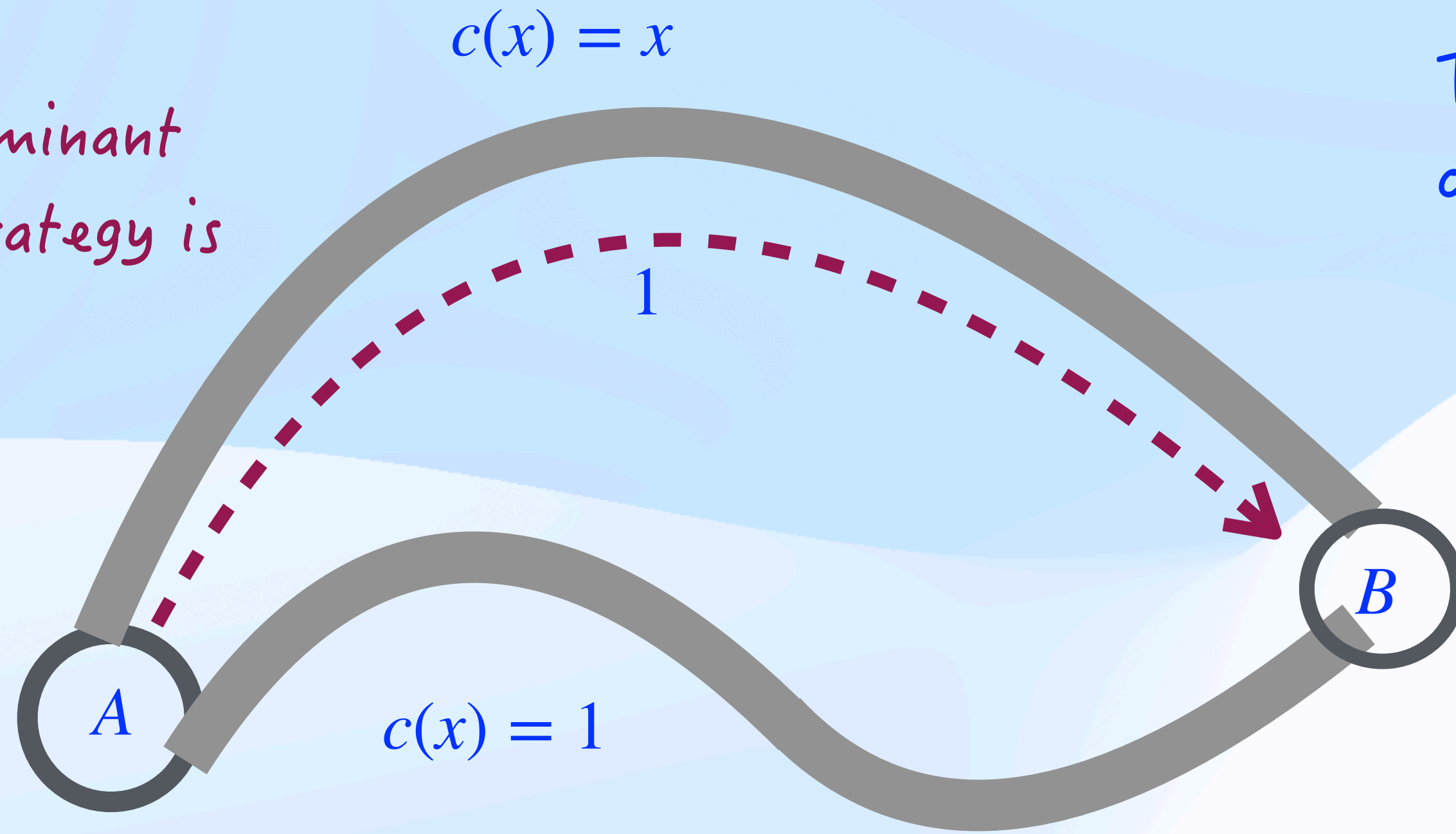
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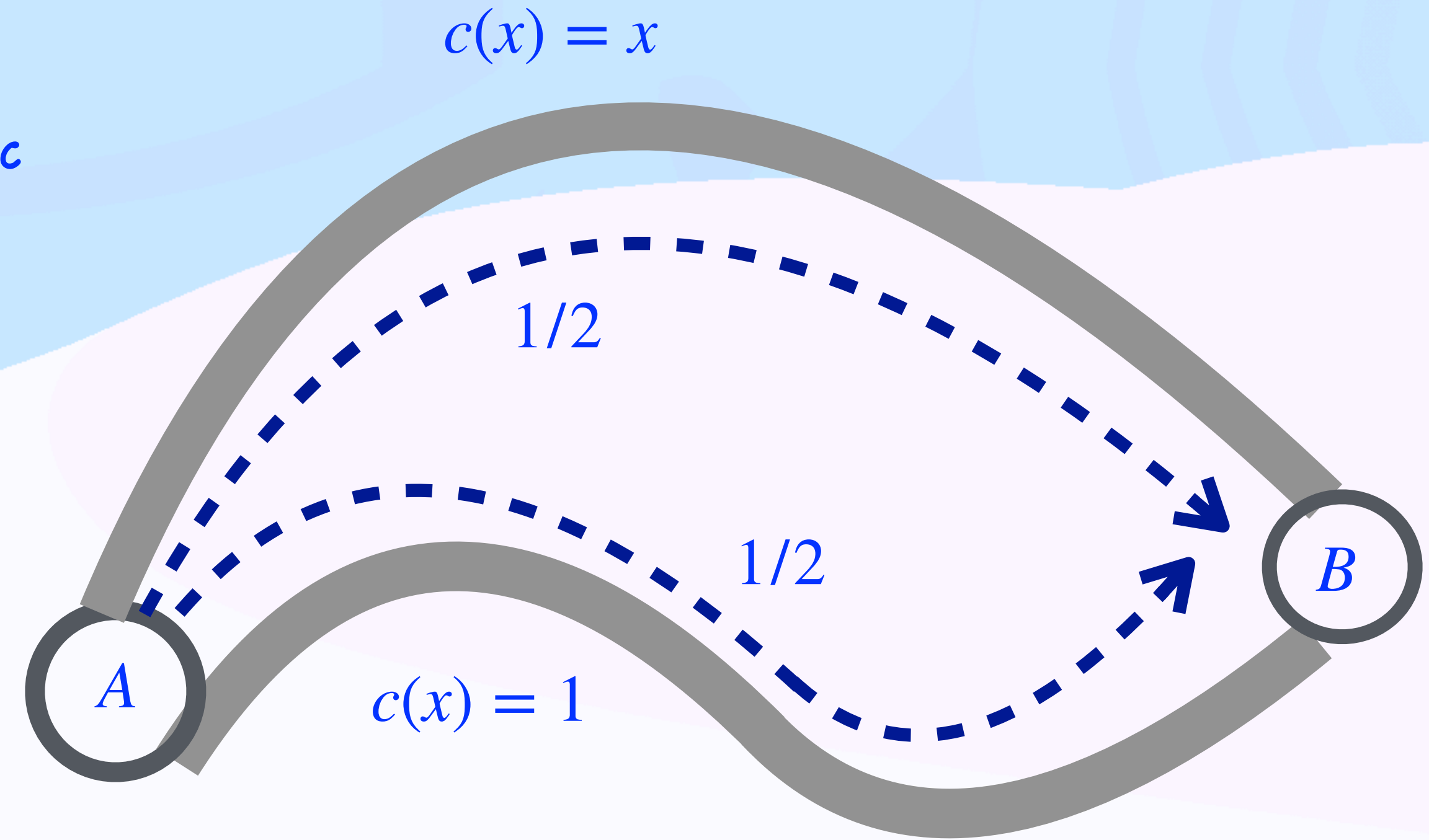
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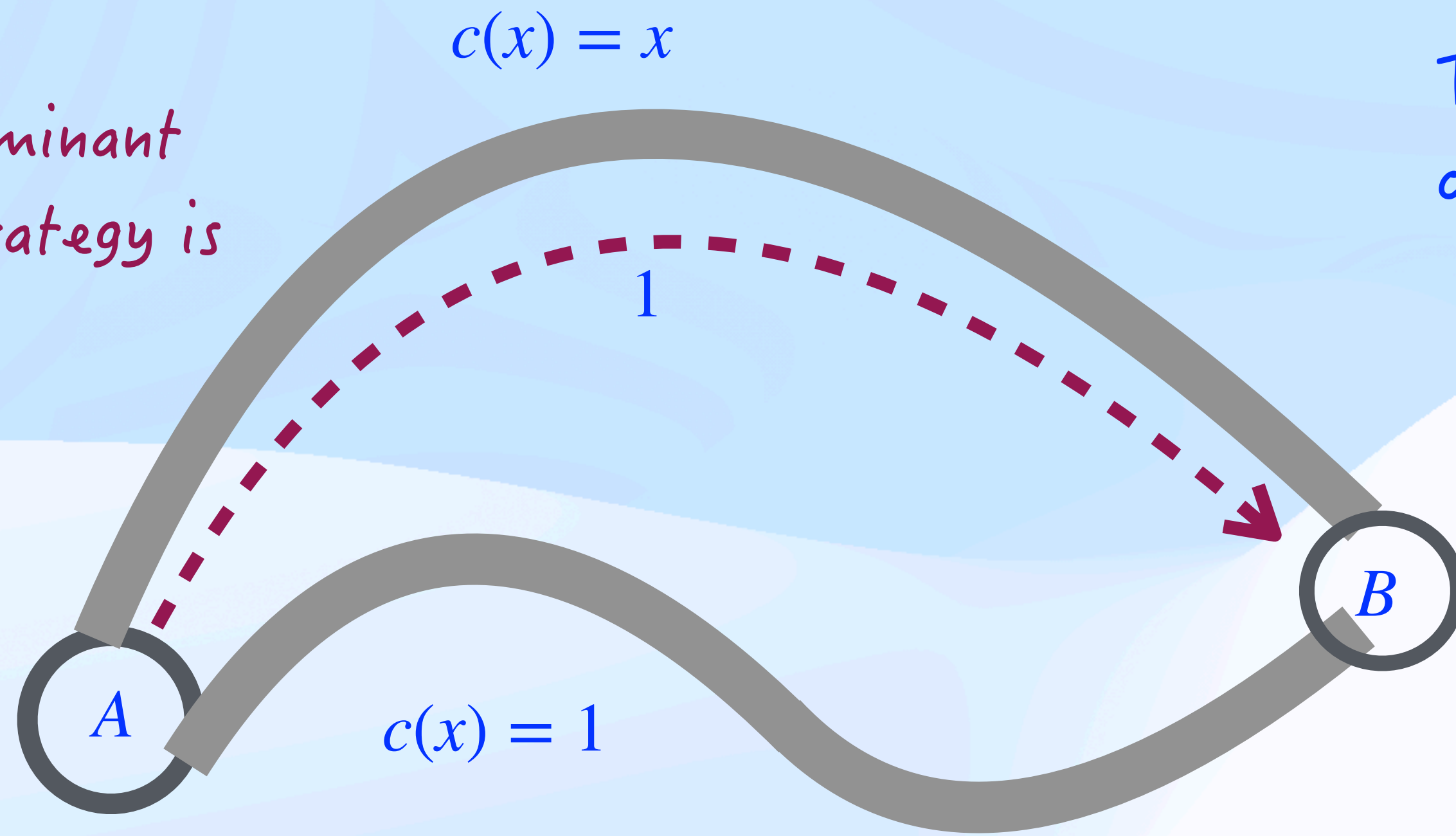
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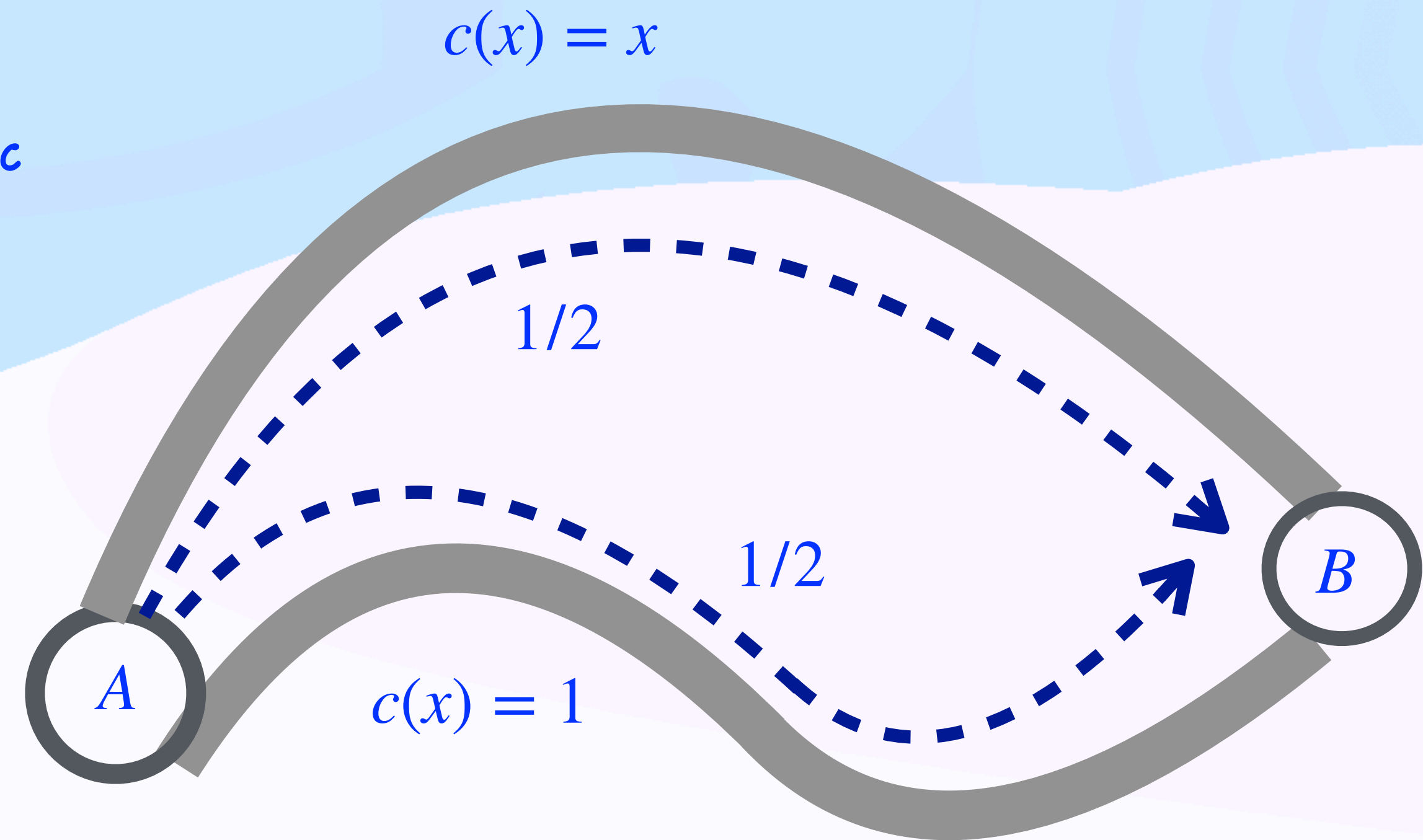
1 unit of traffic

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Expected travel time in DS equilibria $= 1 \cdot 1 = 1$

Traffic control



Expected travel time $= \frac{1}{2} \cdot 1 + \frac{1}{2} \cdot \frac{1}{2} = \frac{3}{4}$

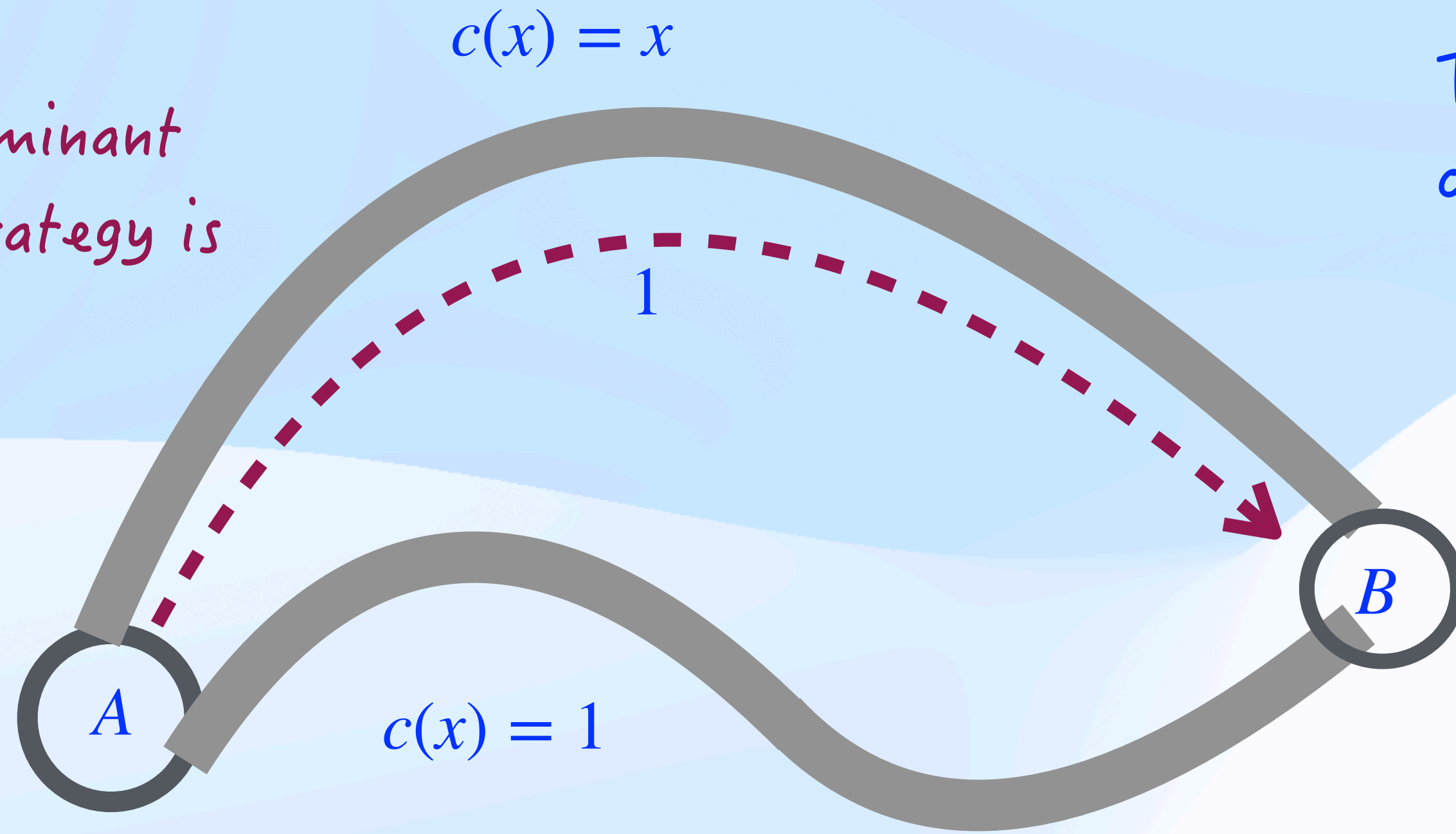
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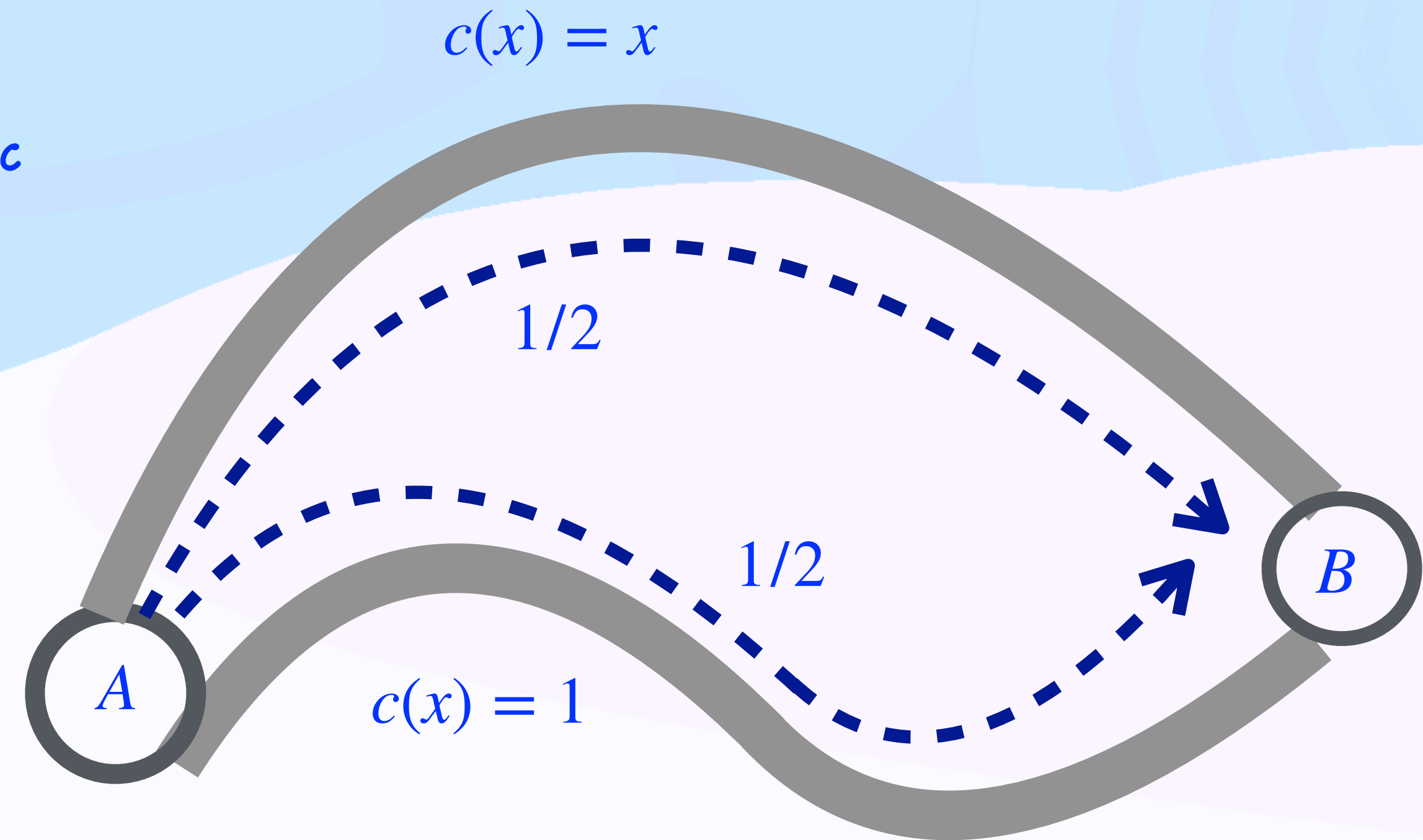
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Expected travel time in DS equilibria $= 1 \cdot 1 = 1$

Q: Is this the ideal outcome ?

Traffic control



$$\text{Expected travel time} = \frac{1}{2} \cdot 1 + \frac{1}{2} \cdot \frac{1}{2} = \frac{3}{4}$$

$$\frac{\text{Travel time in DS equilibrium}}{\text{Min average travel time}} = \frac{1}{3/4} = \frac{4}{3}$$

Q: What should be our social objective ?

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Ans: Minimize average travel time

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Price of Anarchy (POA)

Q: What should be our social objective ?

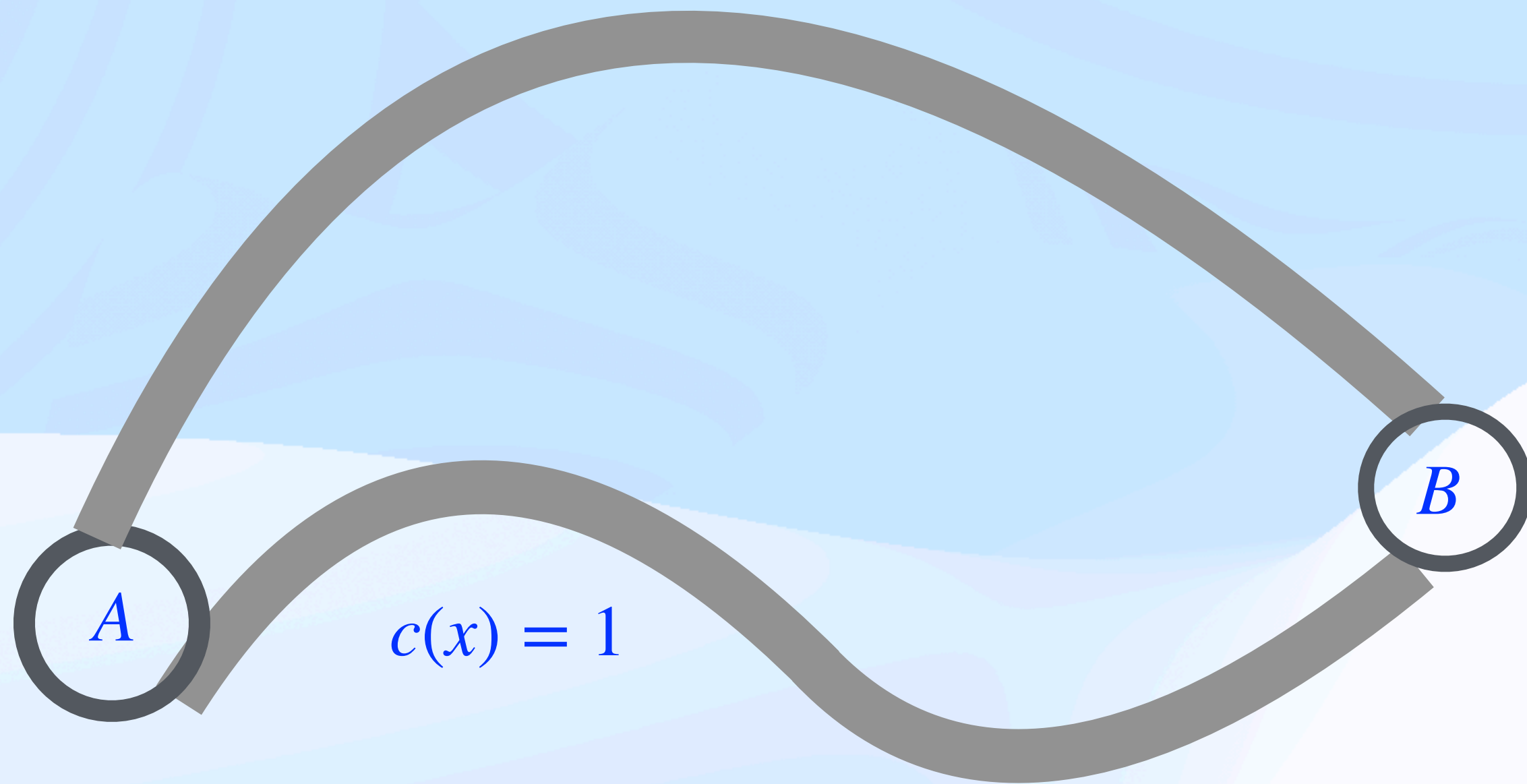
Ans: Minimize average travel time

Q: How far can we be from this objective ?

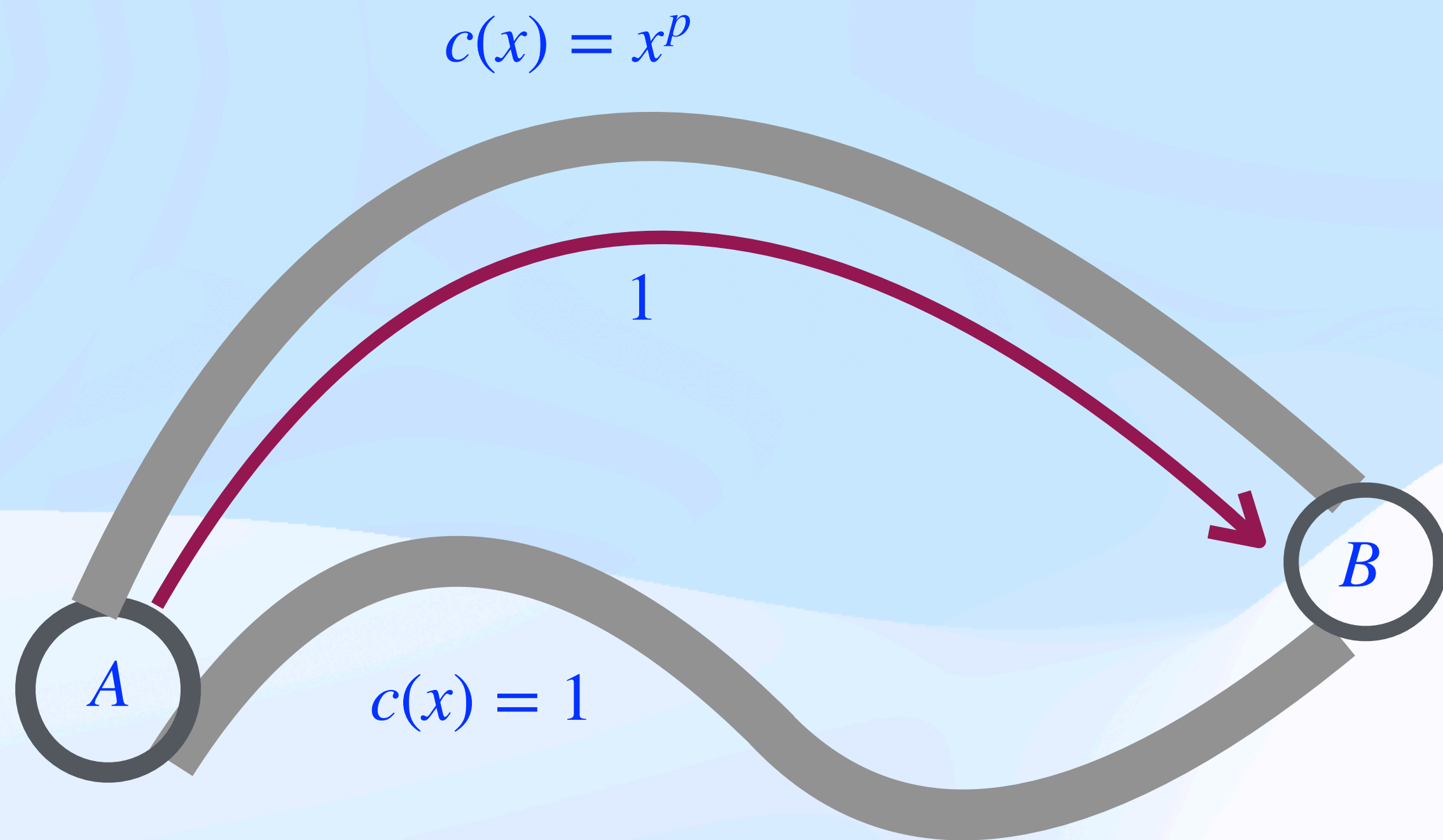
$$\text{Price of Anarchy (POA)} = \frac{\text{Travel time in DS equilibrium}}{\text{Min possible average travel time}}$$

What if the cost is non-linear?

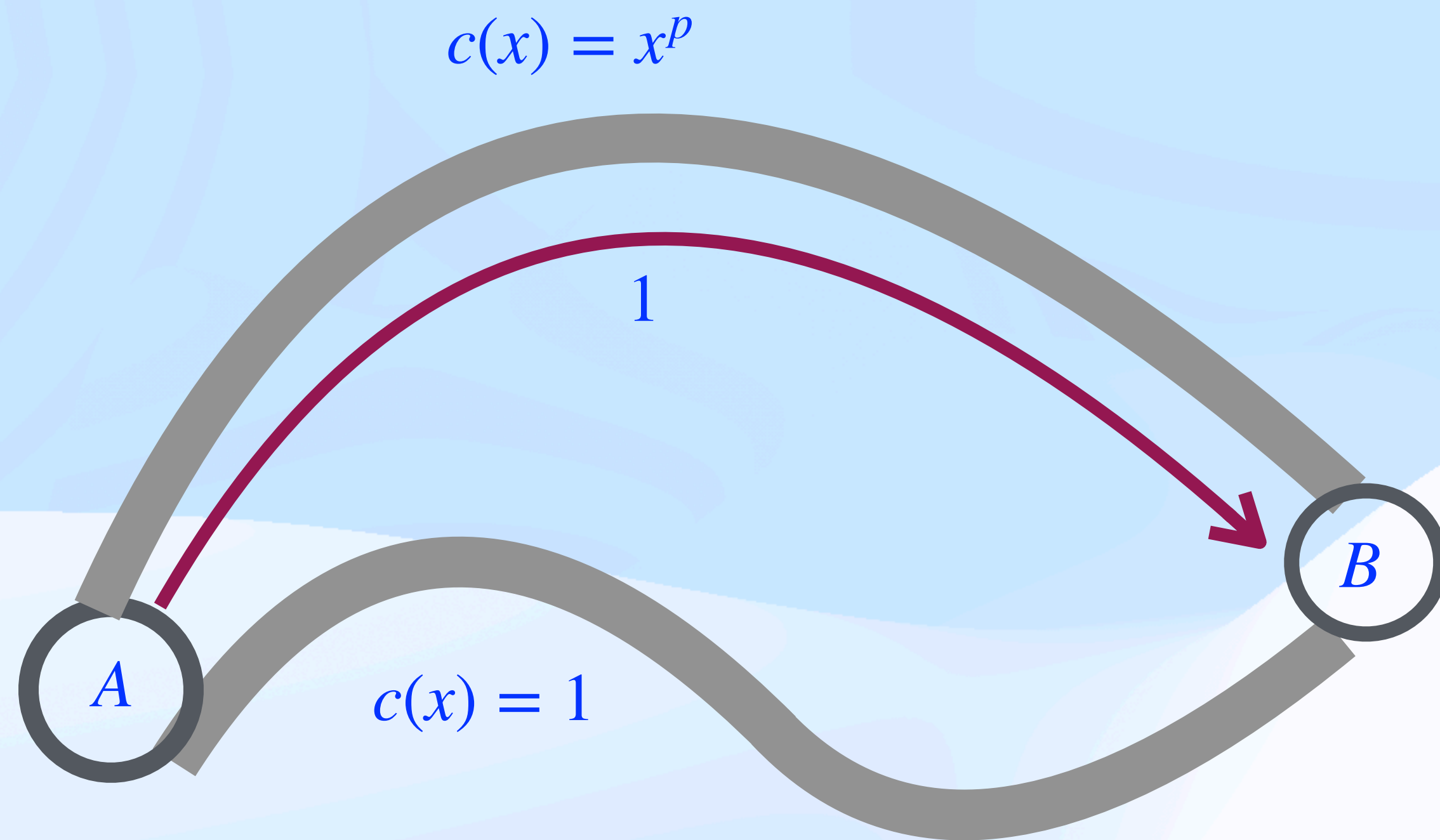
$$c(x) = x^p$$



What if the cost is non-linear?

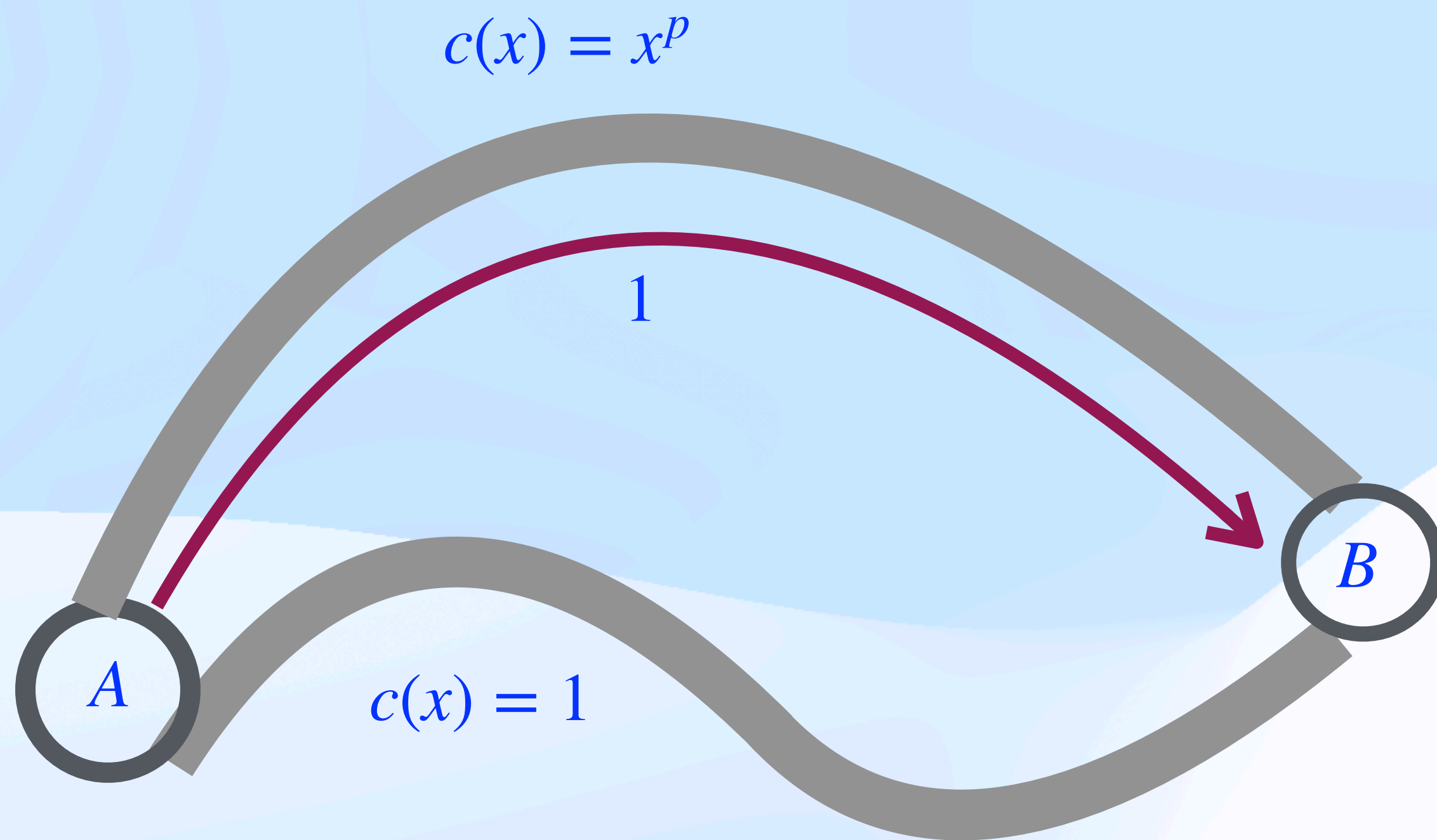


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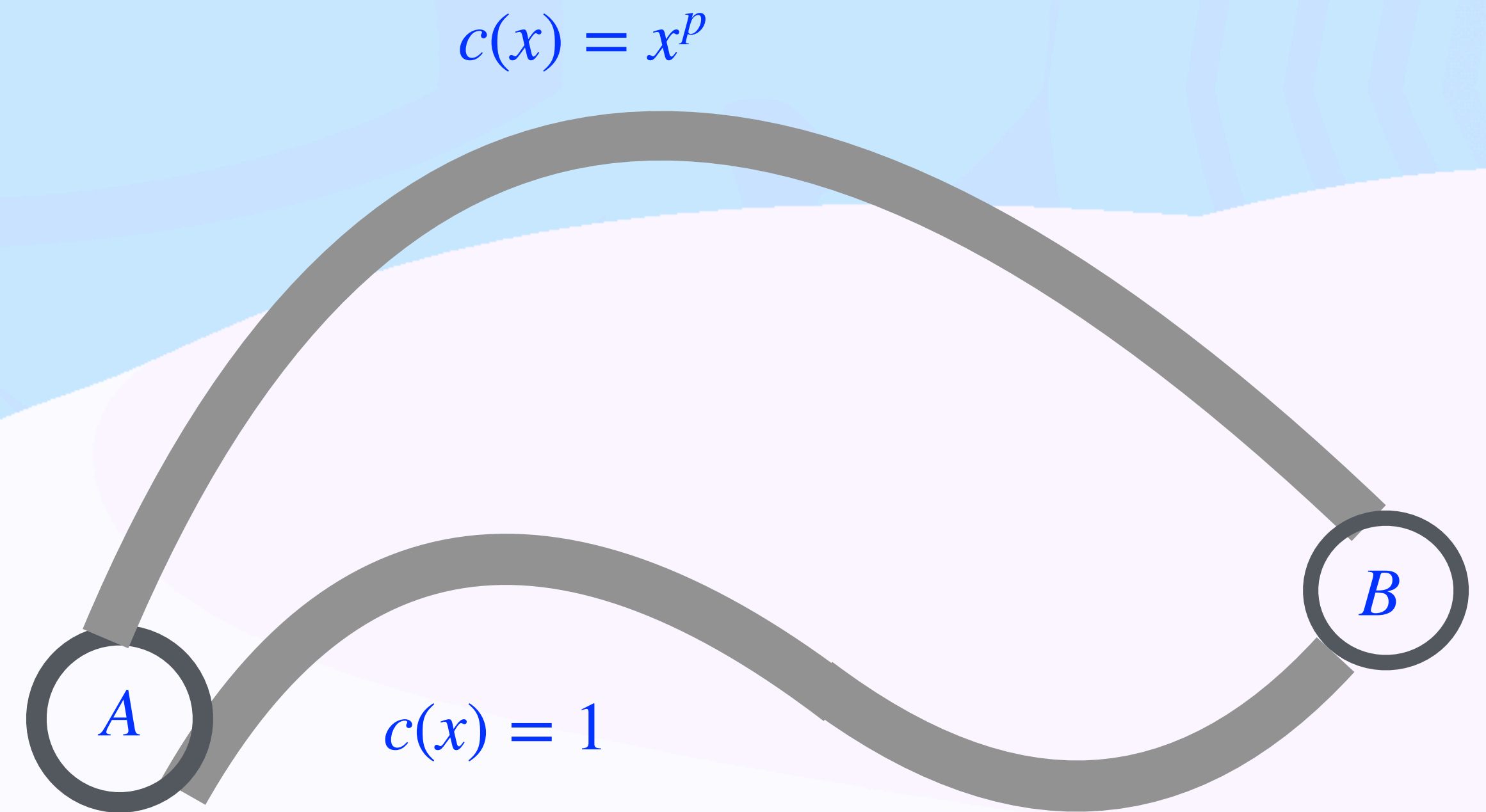


Travel time in DS
equilibria = 1

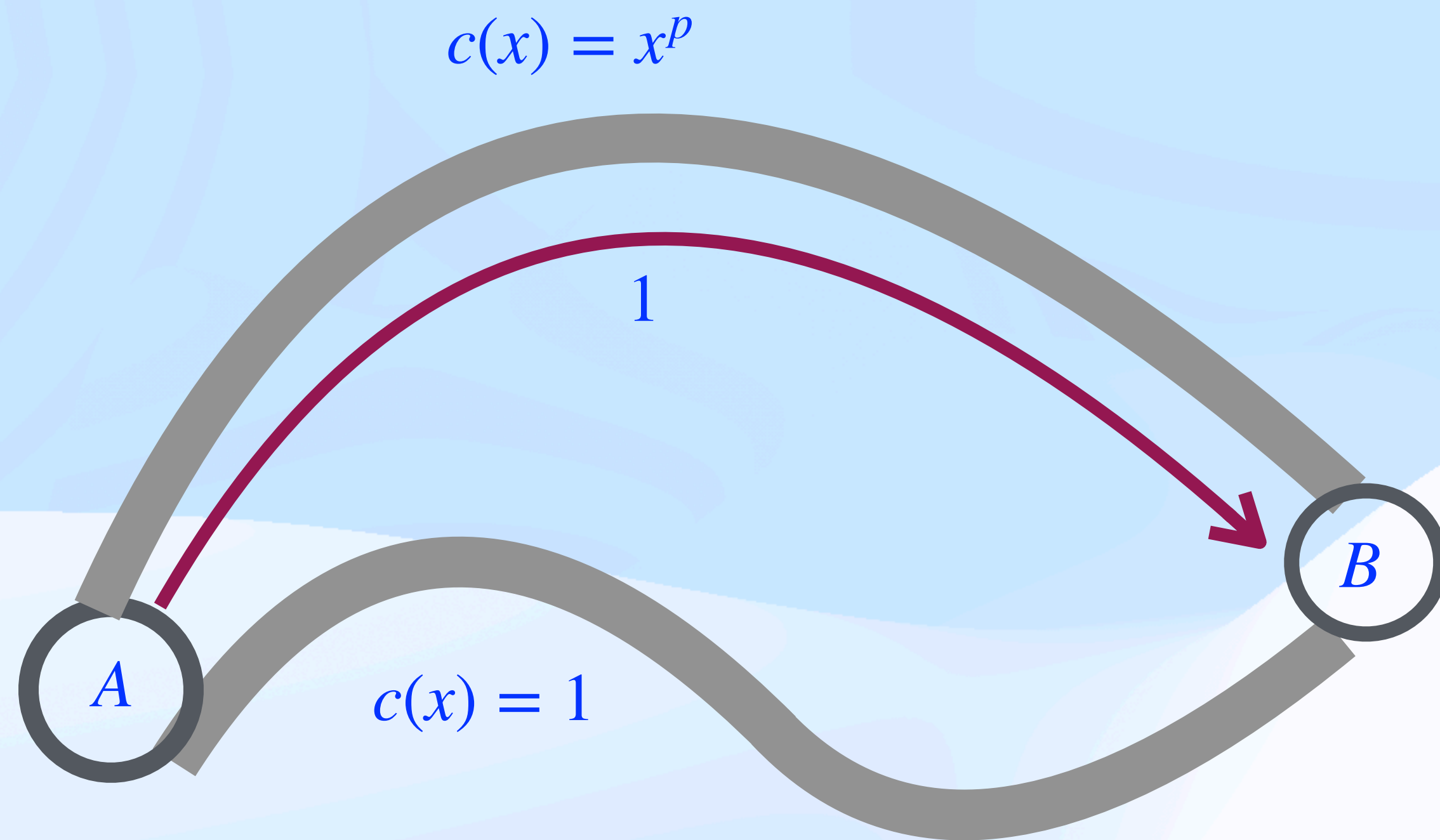
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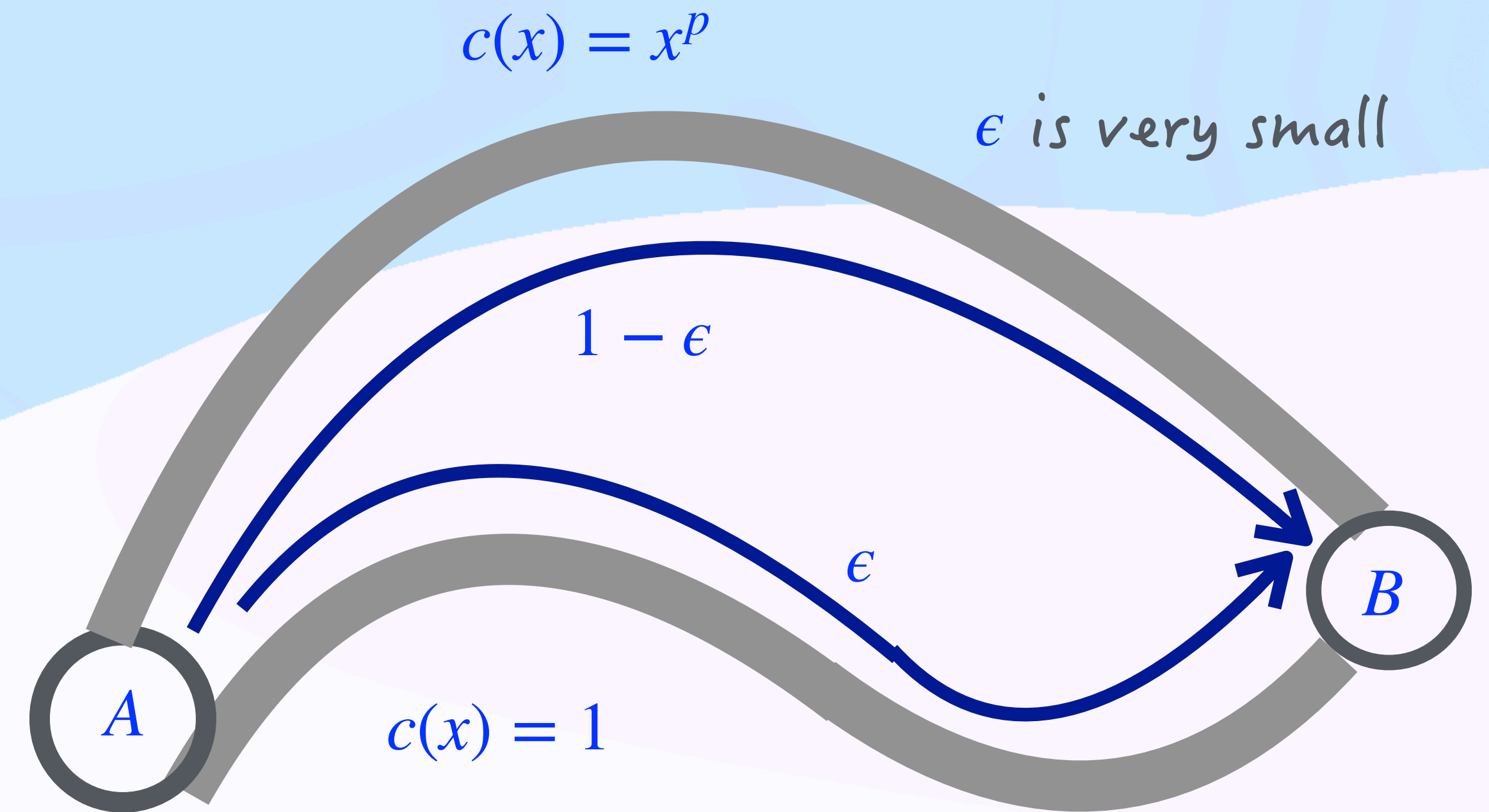
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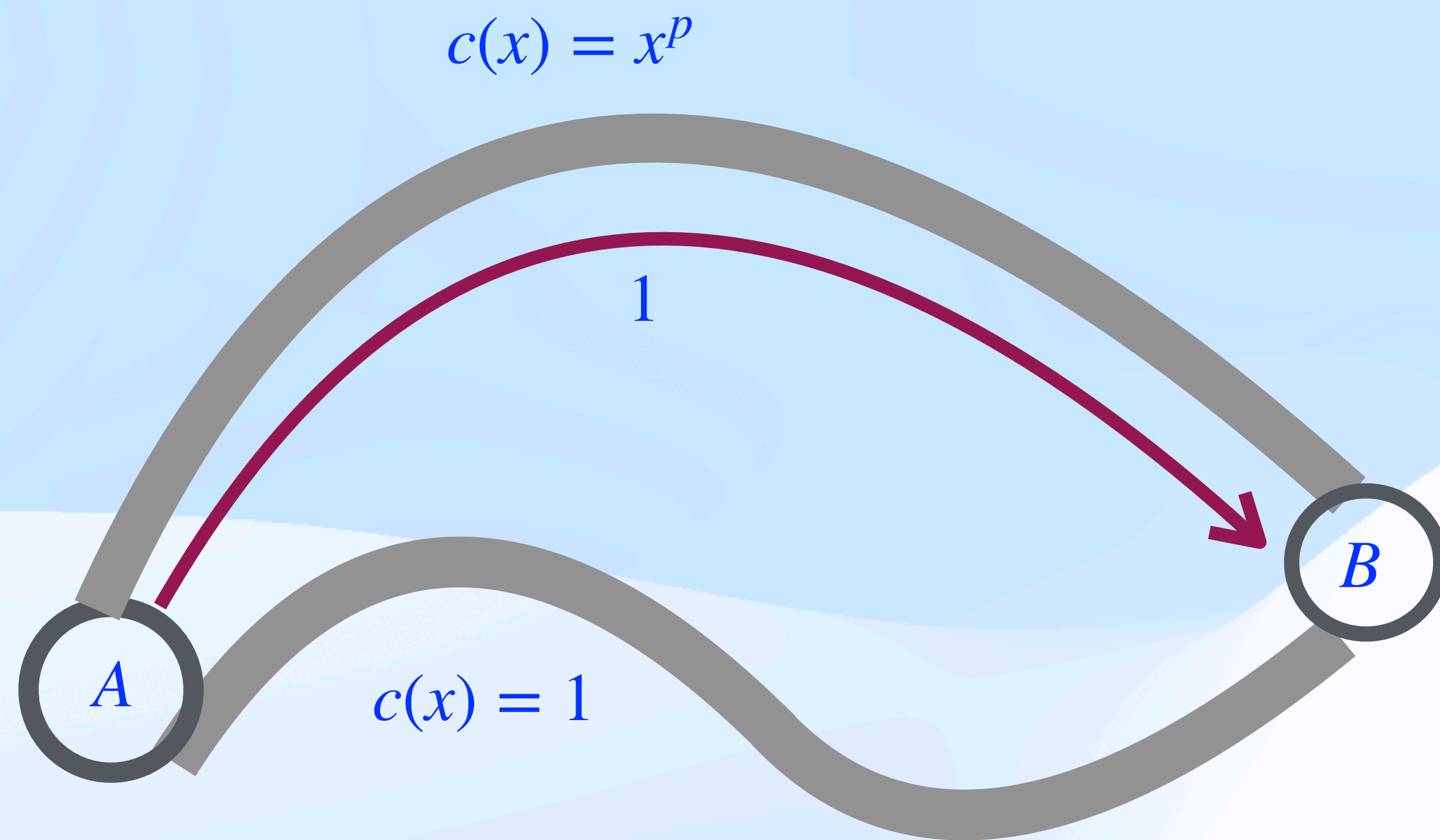
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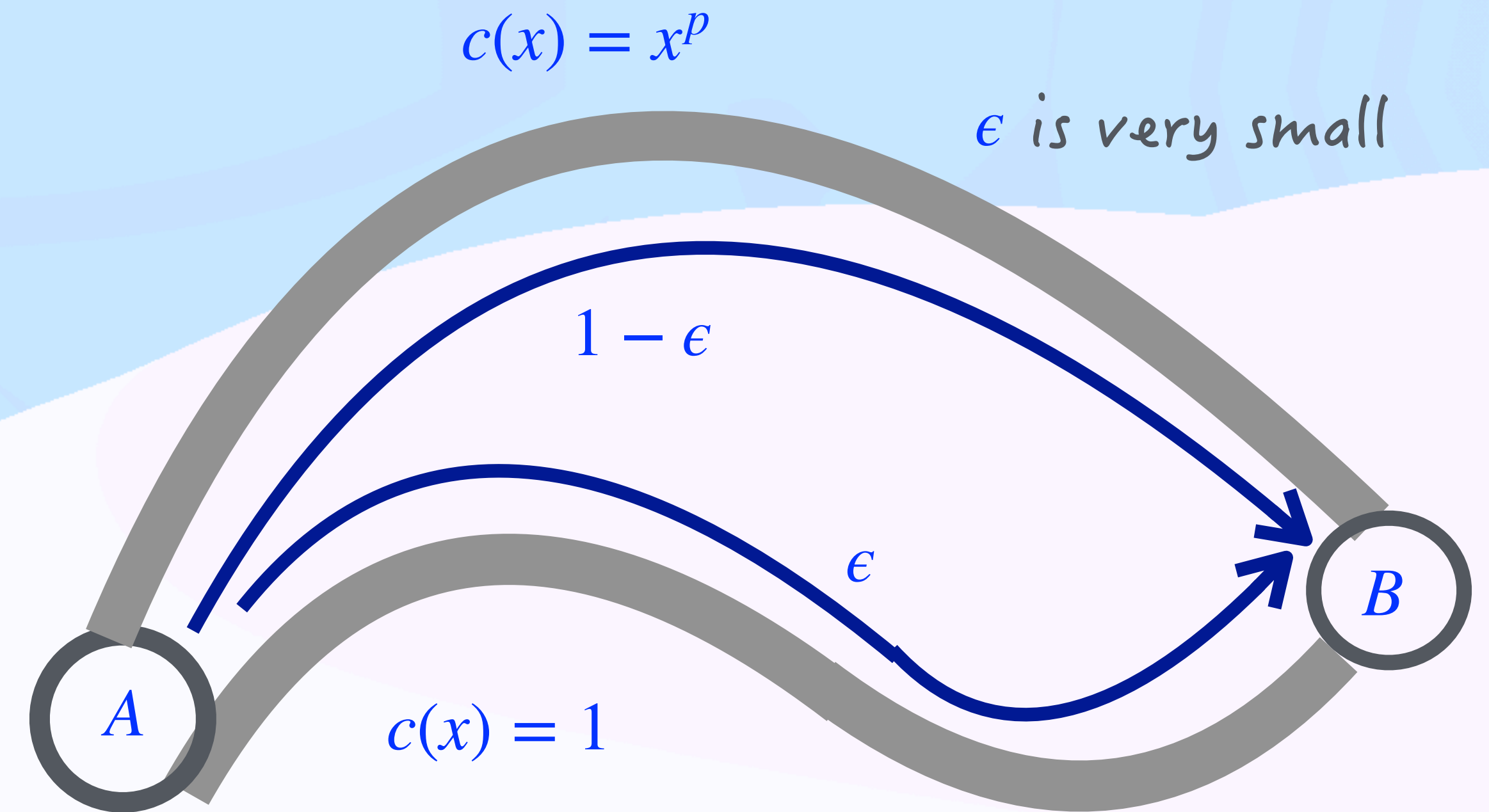
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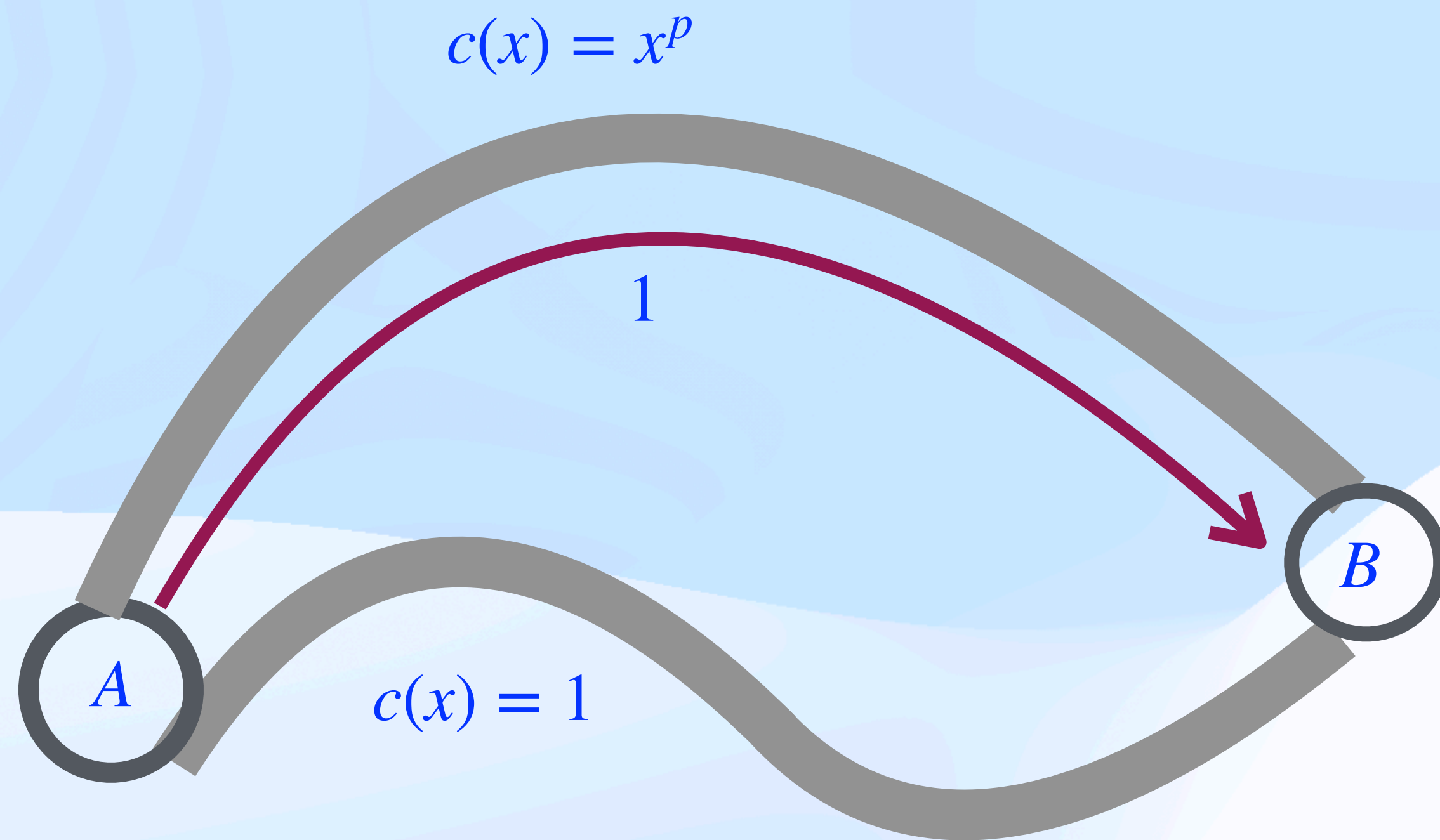


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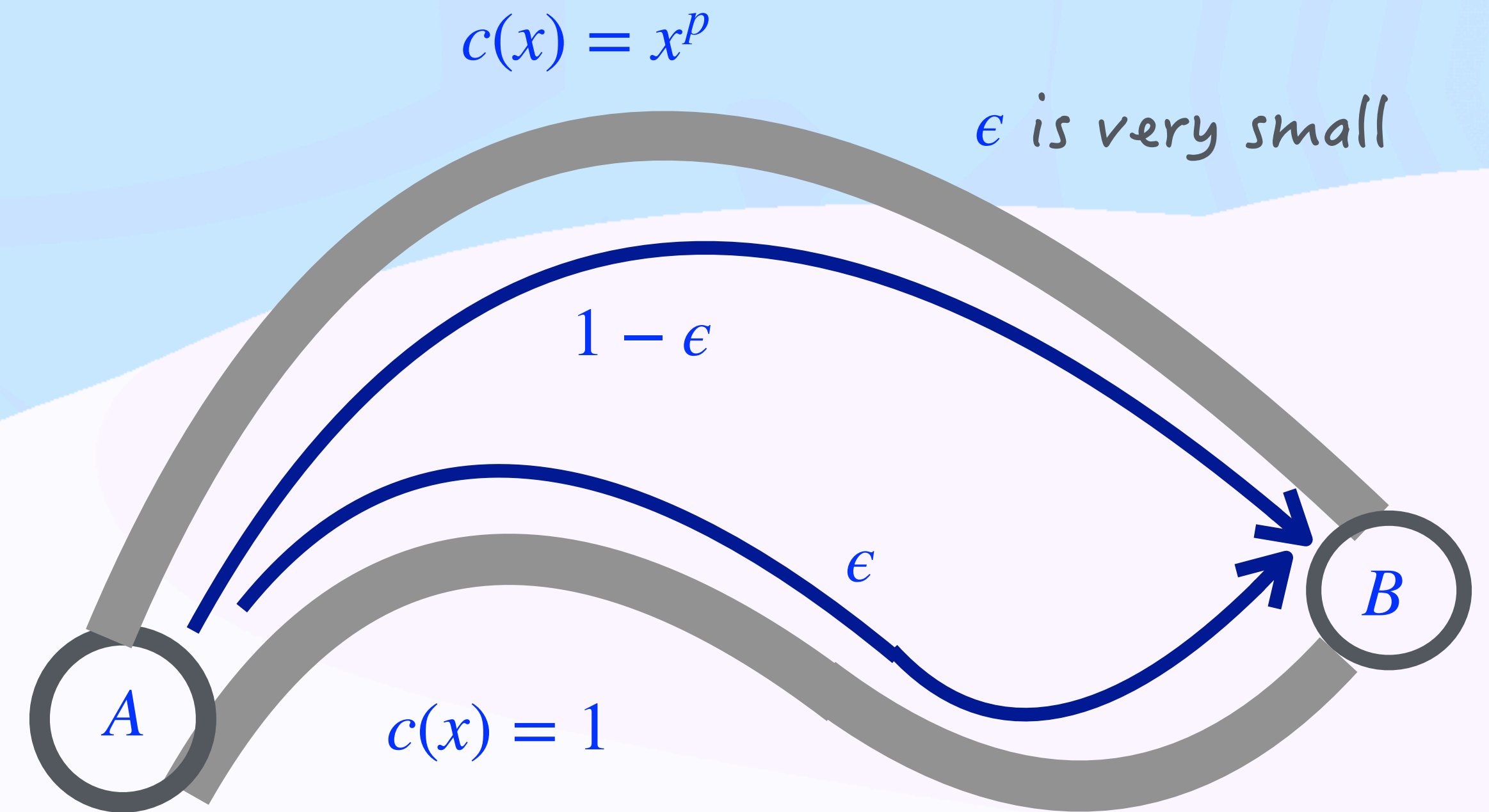


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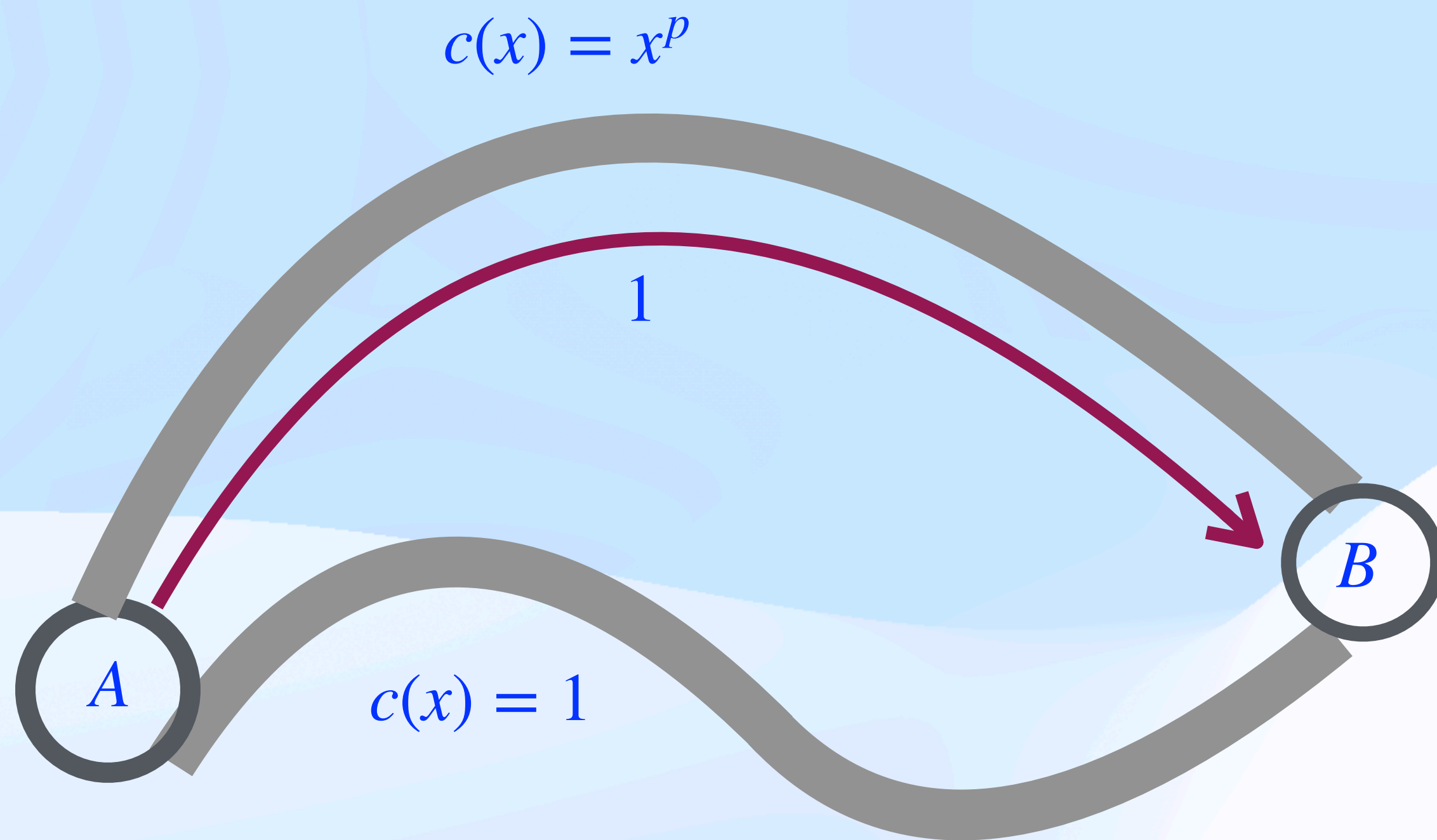
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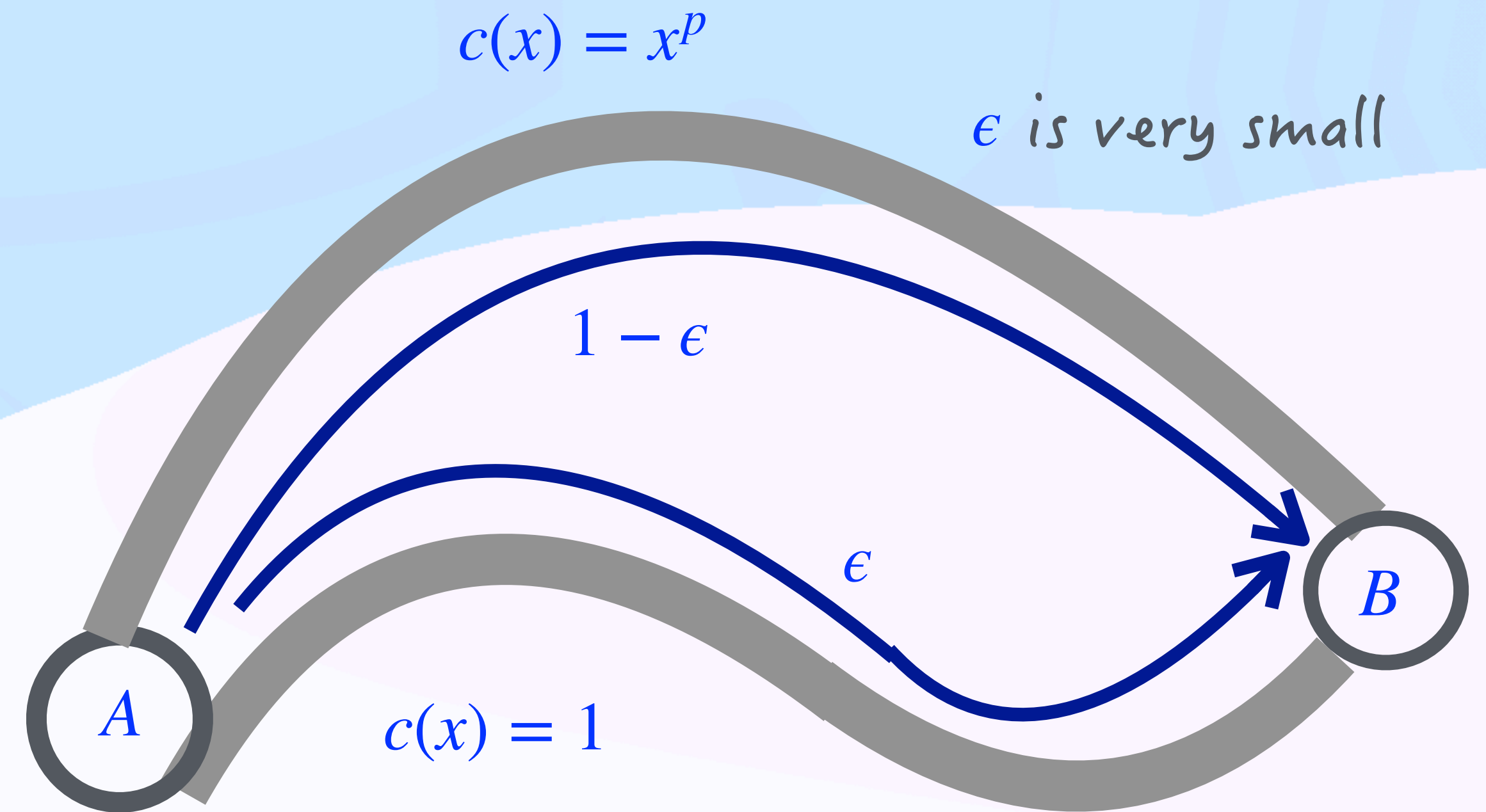
Travel time

$$= \epsilon \cdot 1 + (1 - \epsilon) \cdot (1 - \epsilon)^p = \epsilon + (1 - \epsilon)^{p+1}$$

What if the cost is non-linear?



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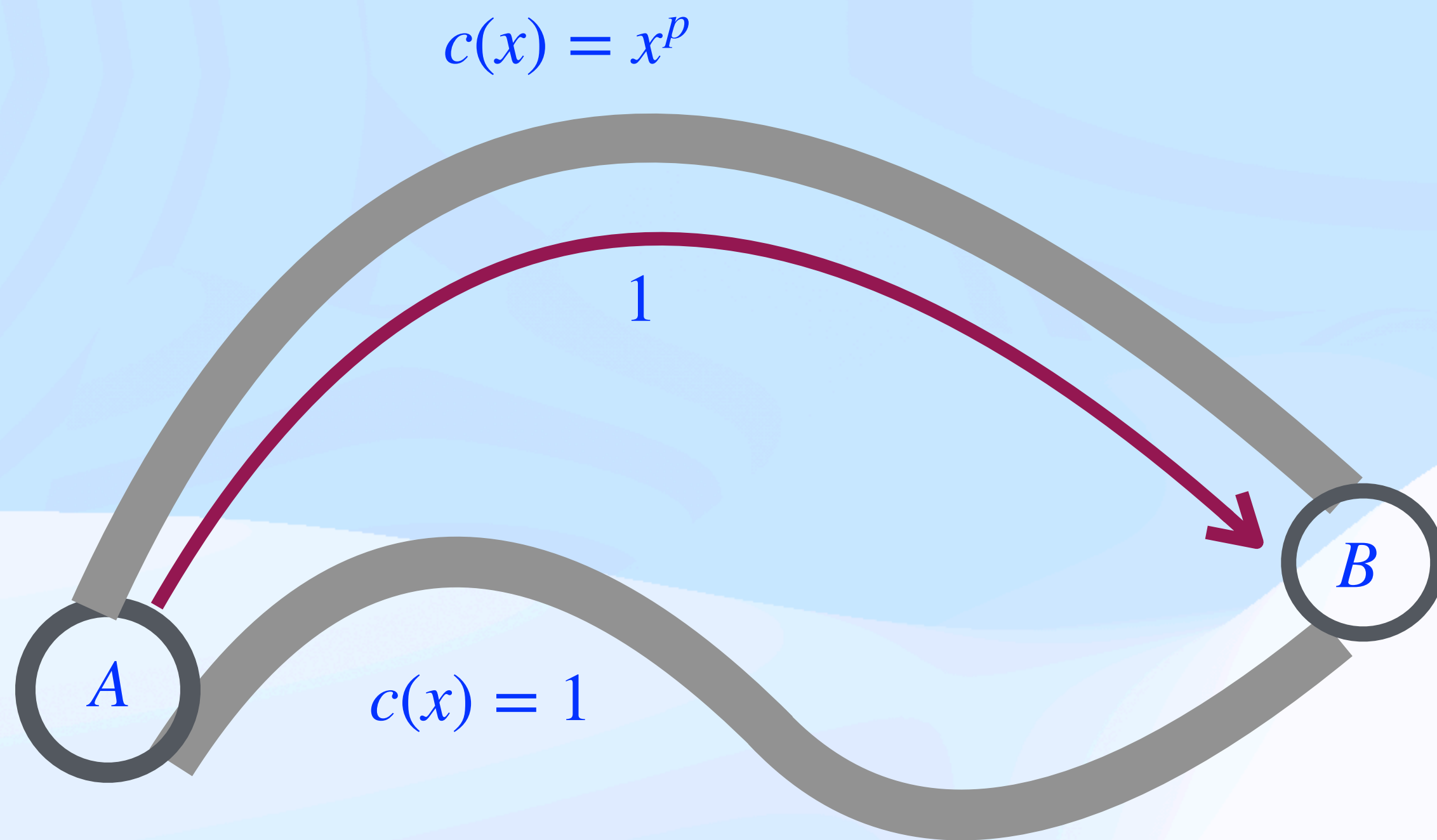


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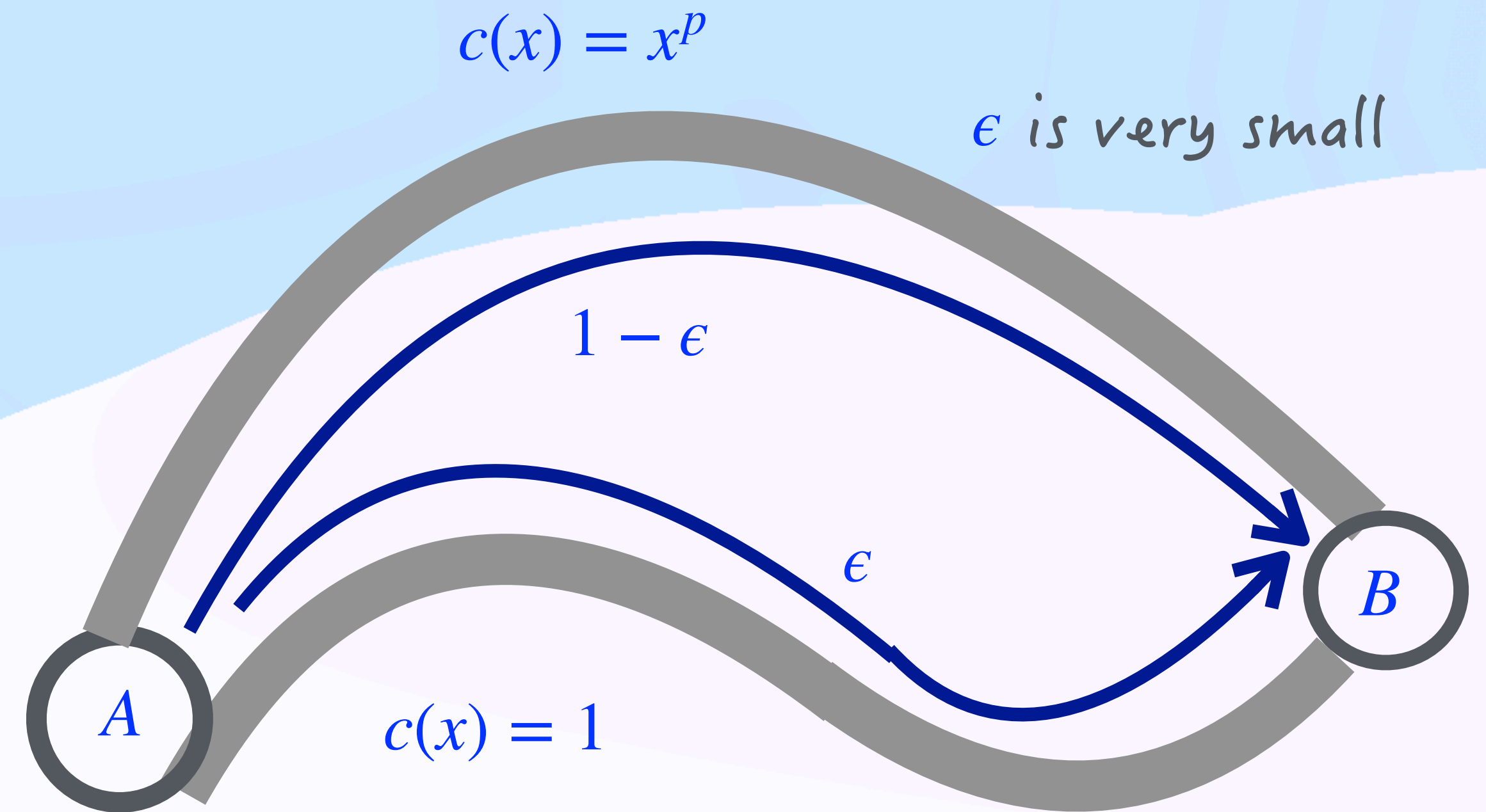
$\rightarrow 0$ when p is large enough

What if the cost is non-linear?



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$$POA = \frac{\text{Travel time in DSE}}{\text{Min possible travel time}}$$

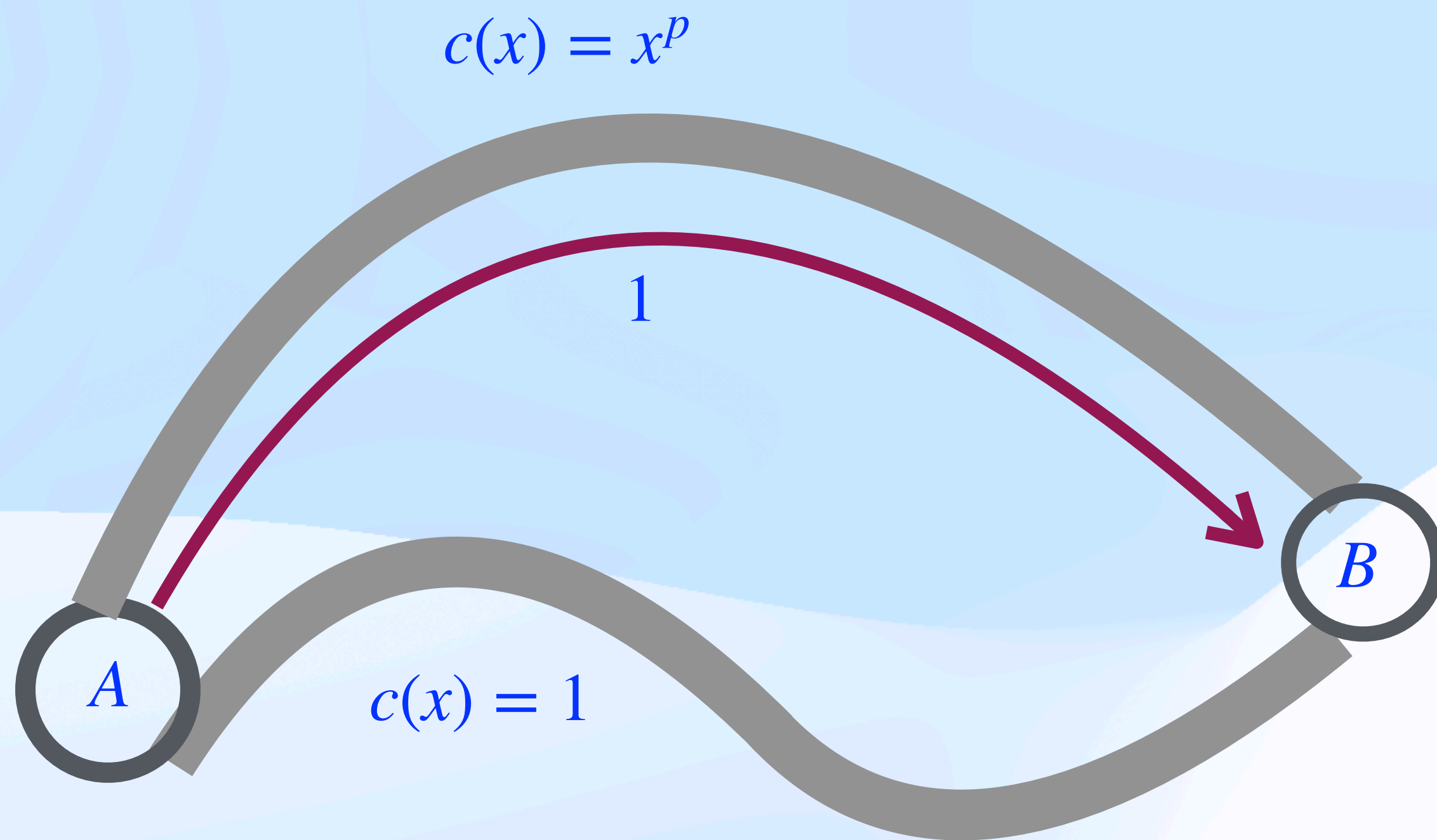


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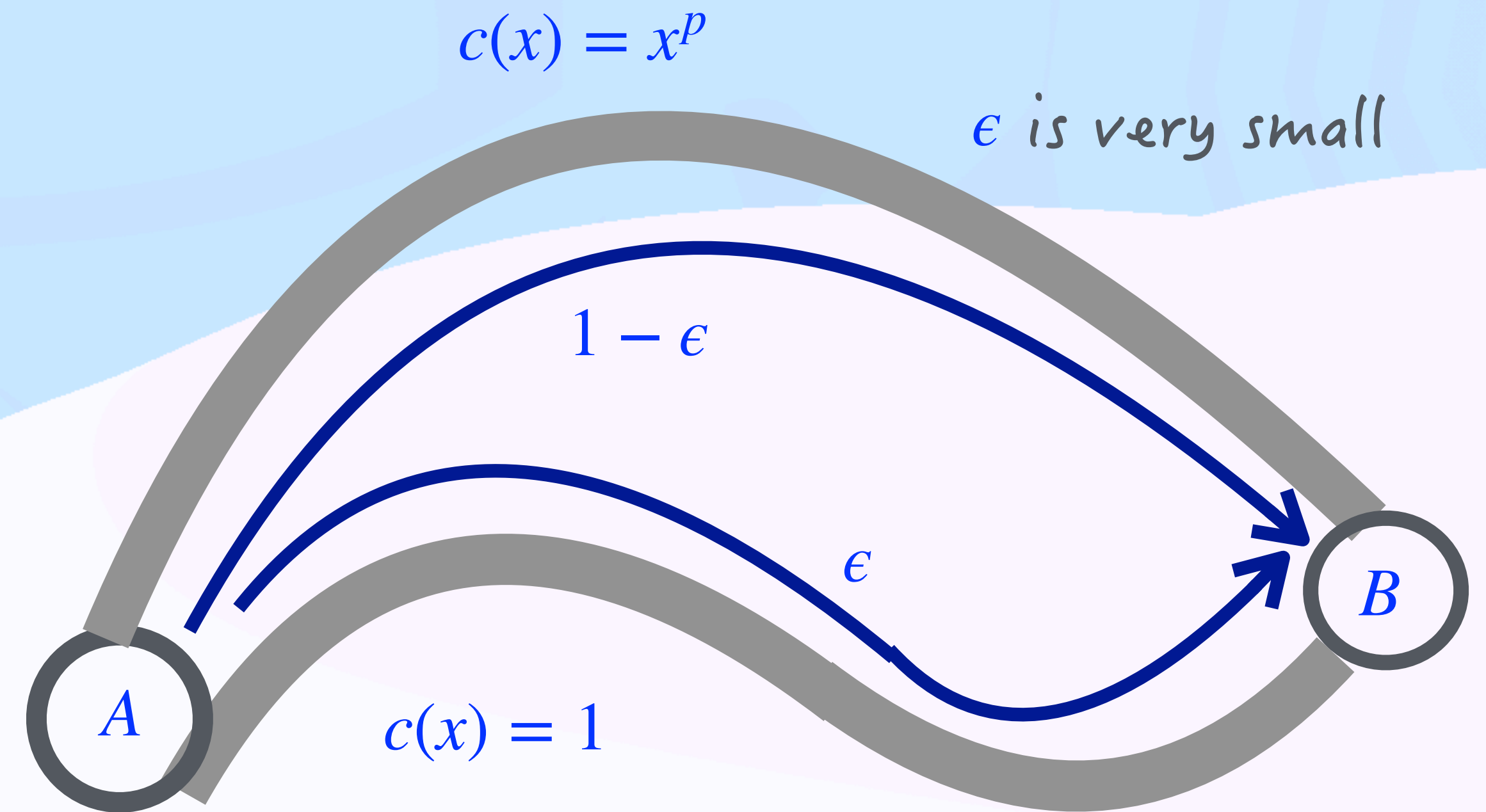
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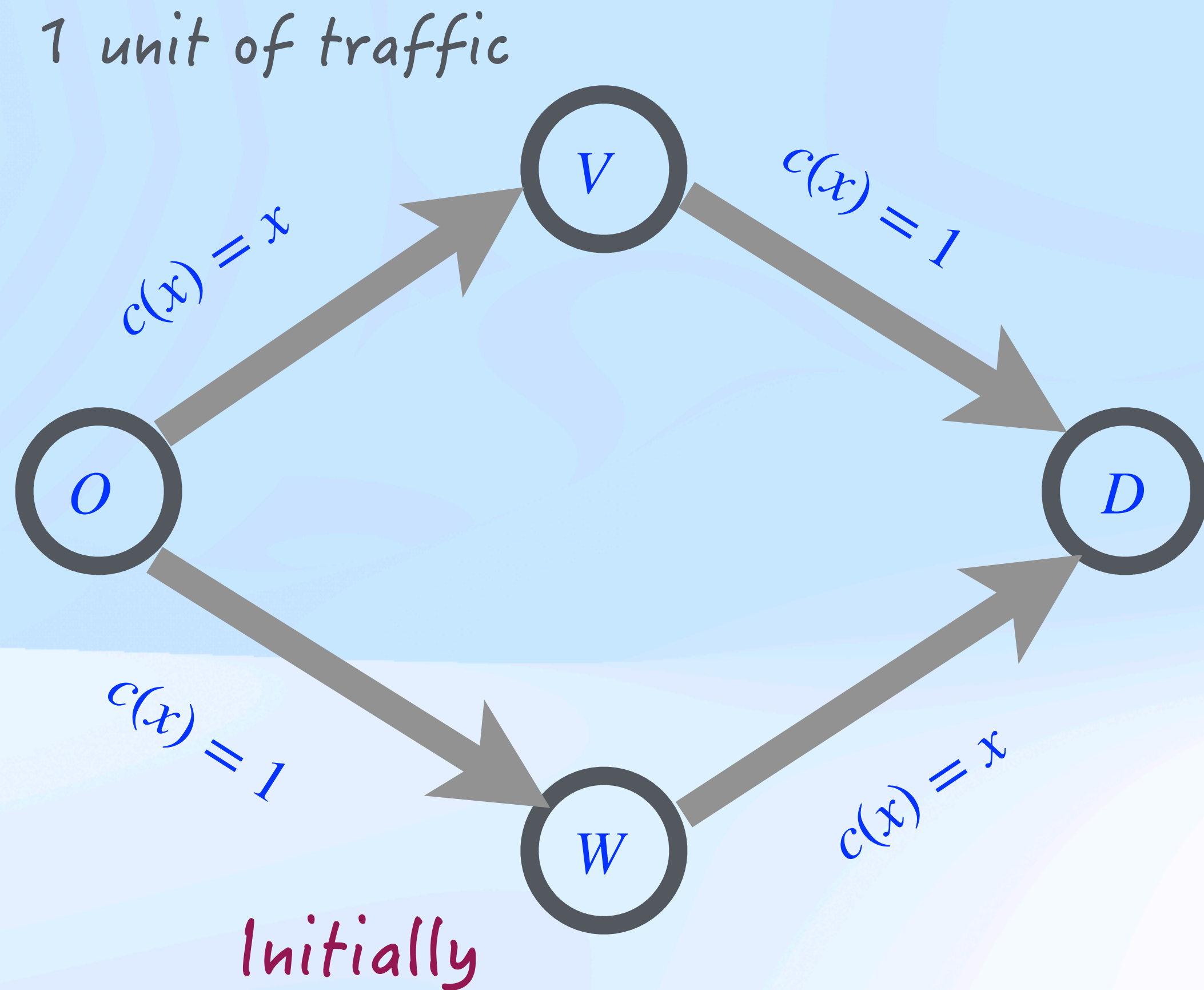
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Is unbounded!

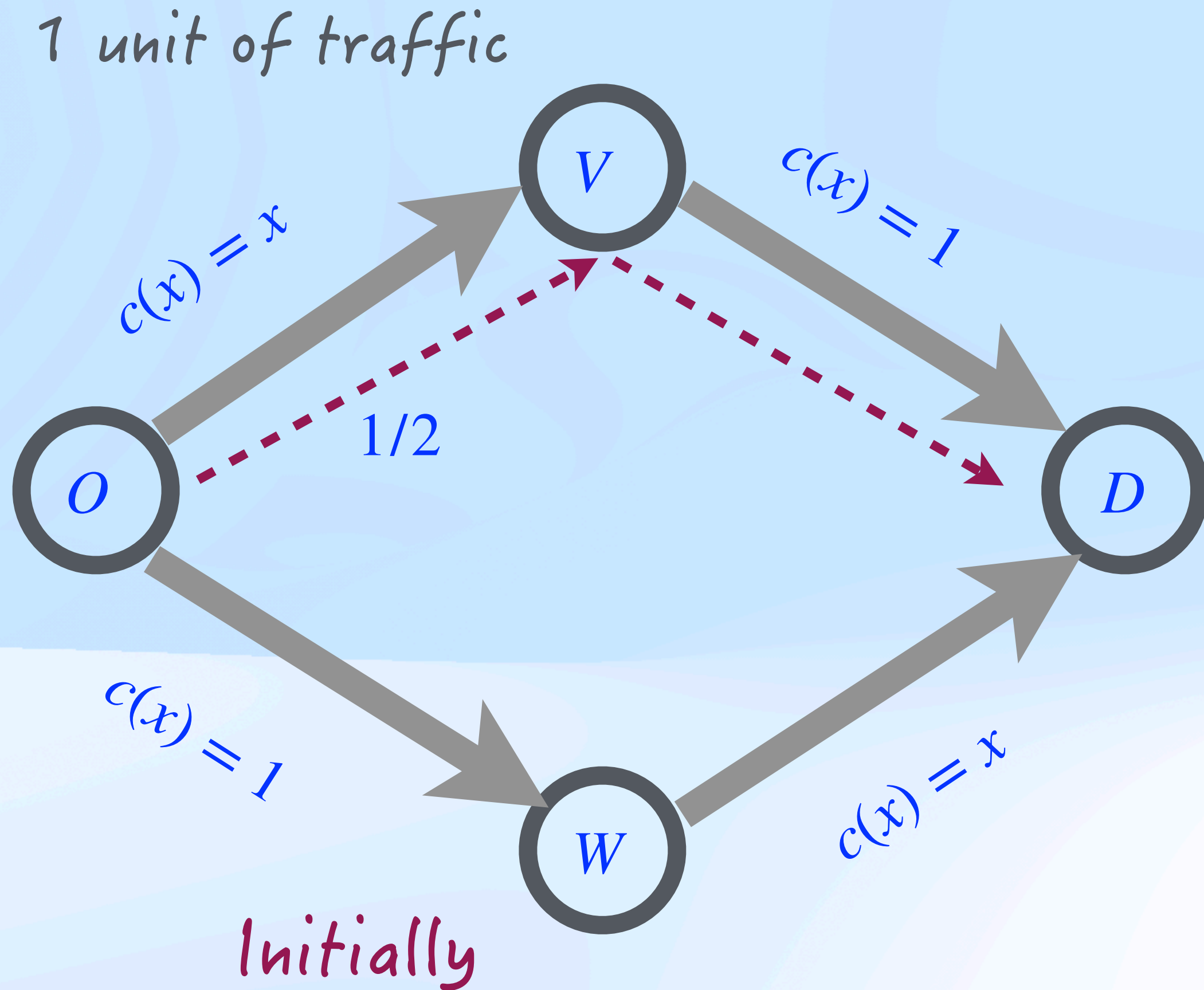
Braess Network, 1965

Initially

Braess Network, 1965

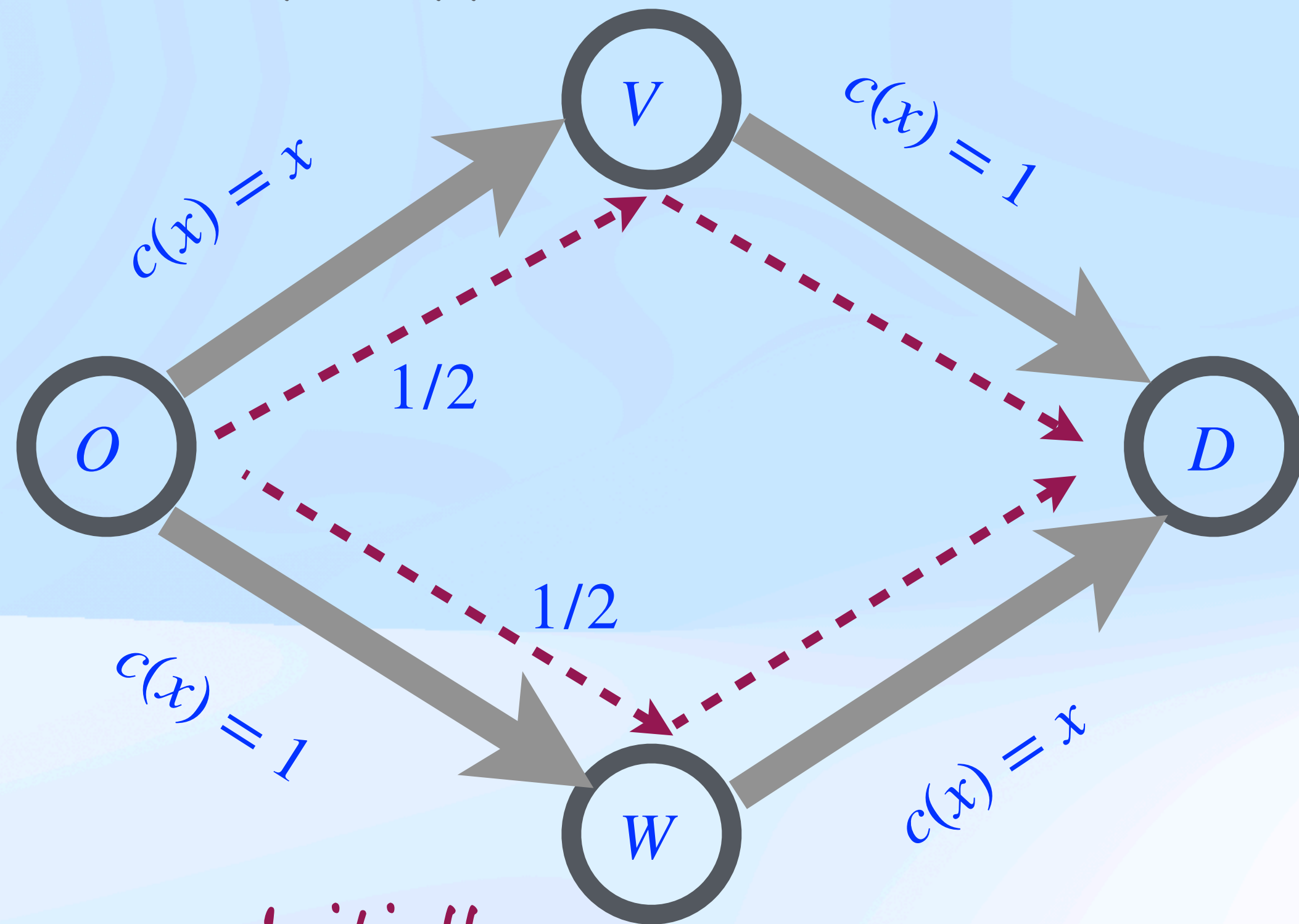


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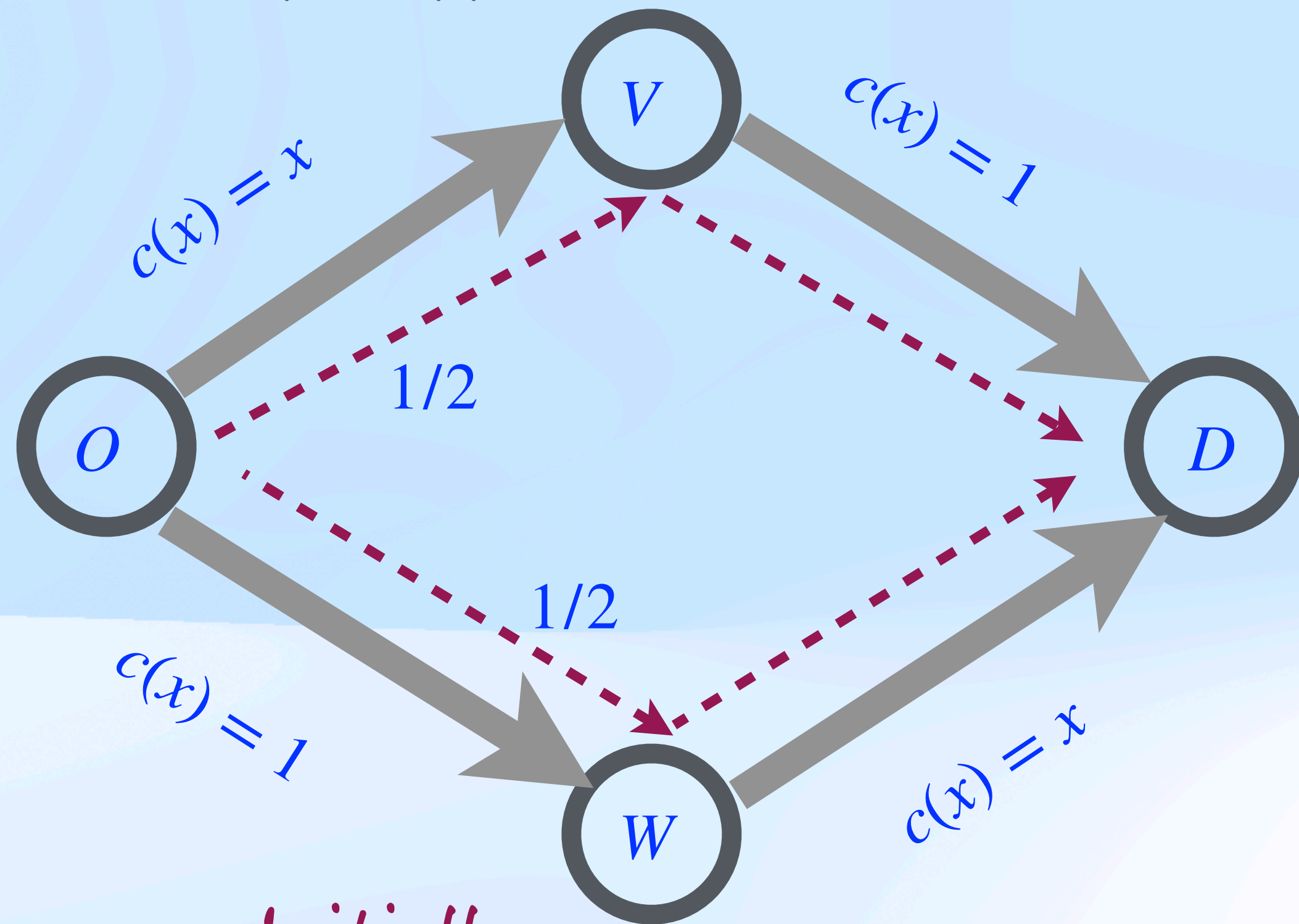
1 unit of traffic



Initially

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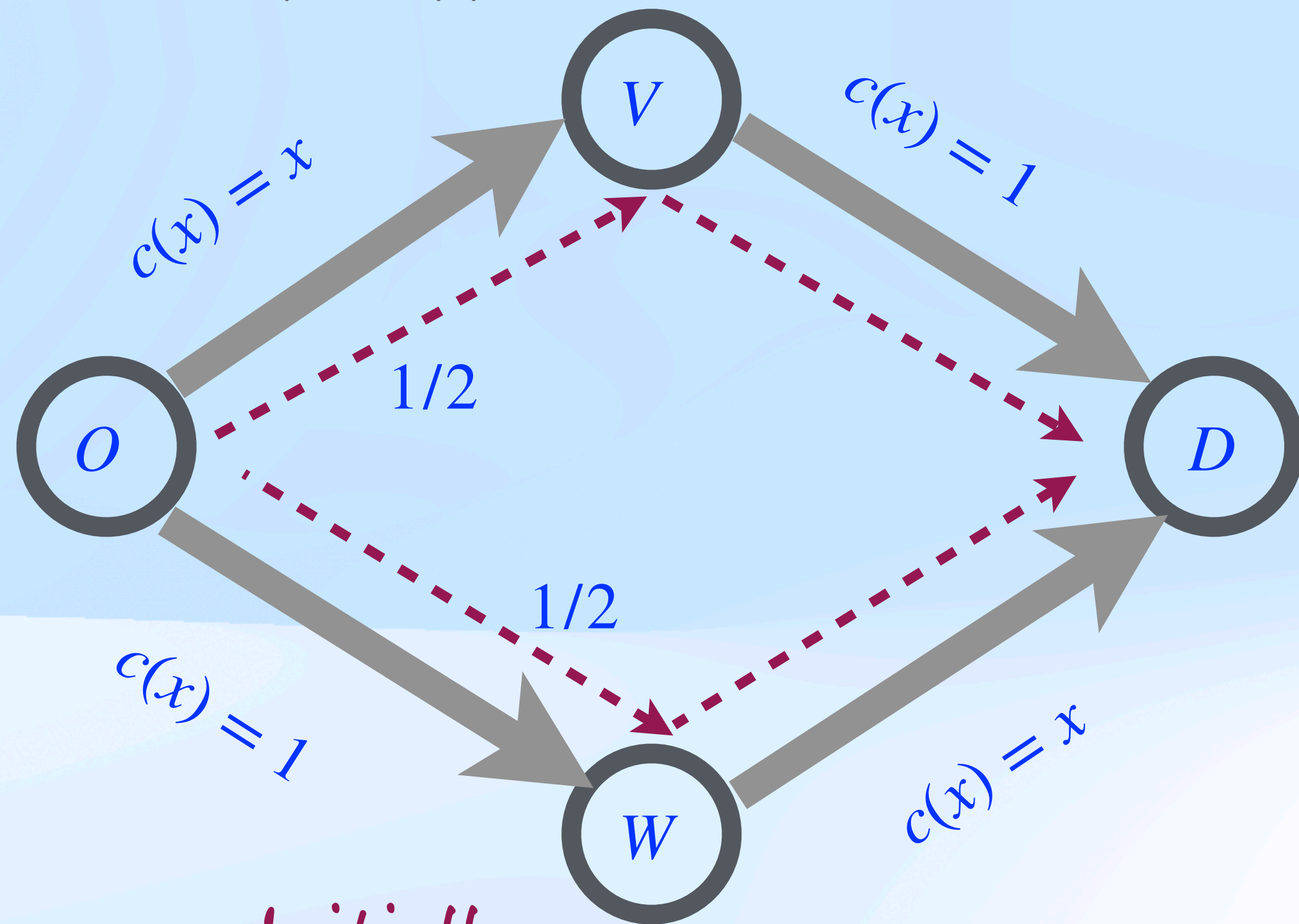


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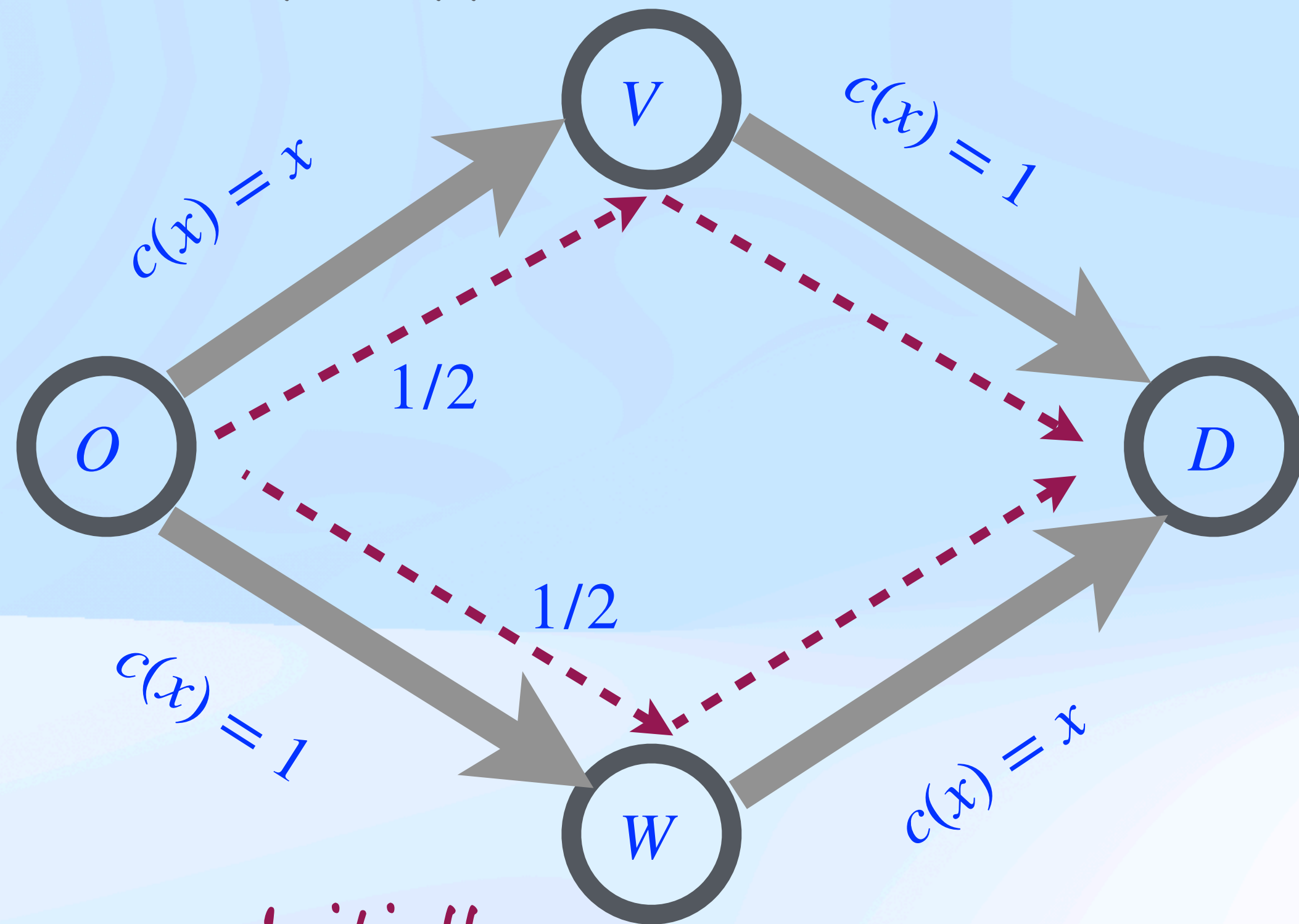


Initially

Travel time $= 2 \left(\frac{1}{2} \cdot \frac{1}{2} + \frac{1}{2} \cdot 1 \right) = \frac{3}{2}$

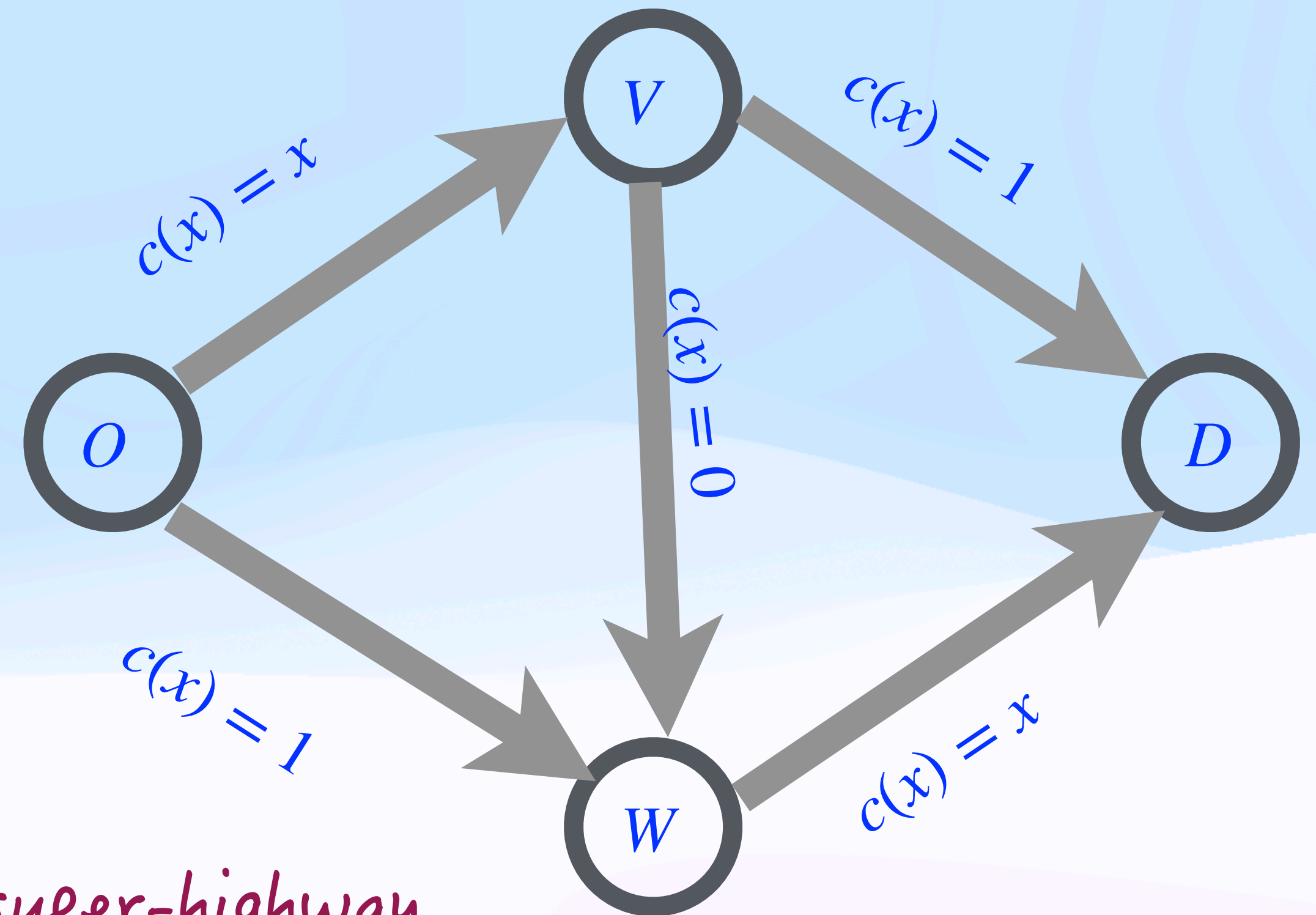
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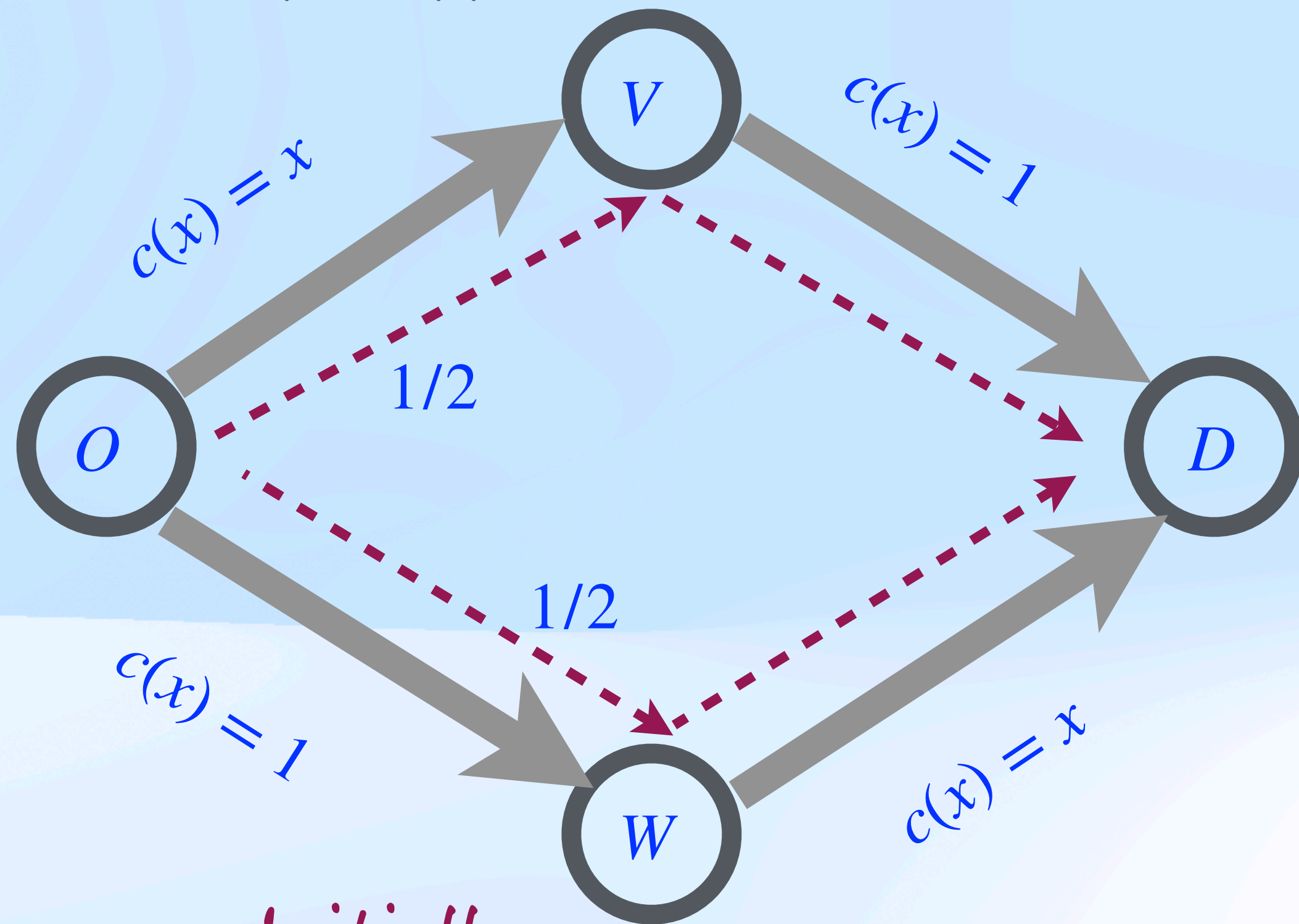
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After super-highway

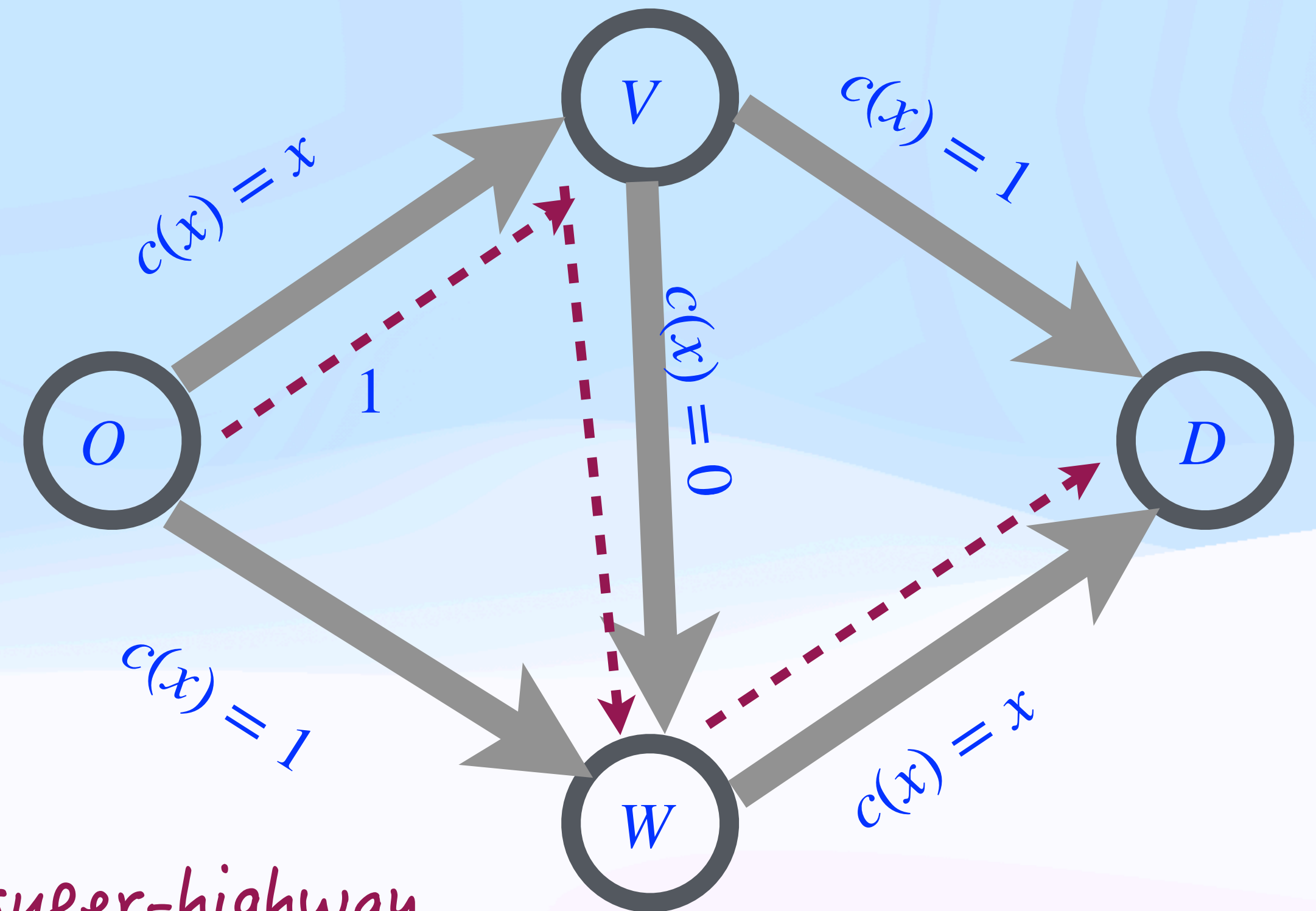
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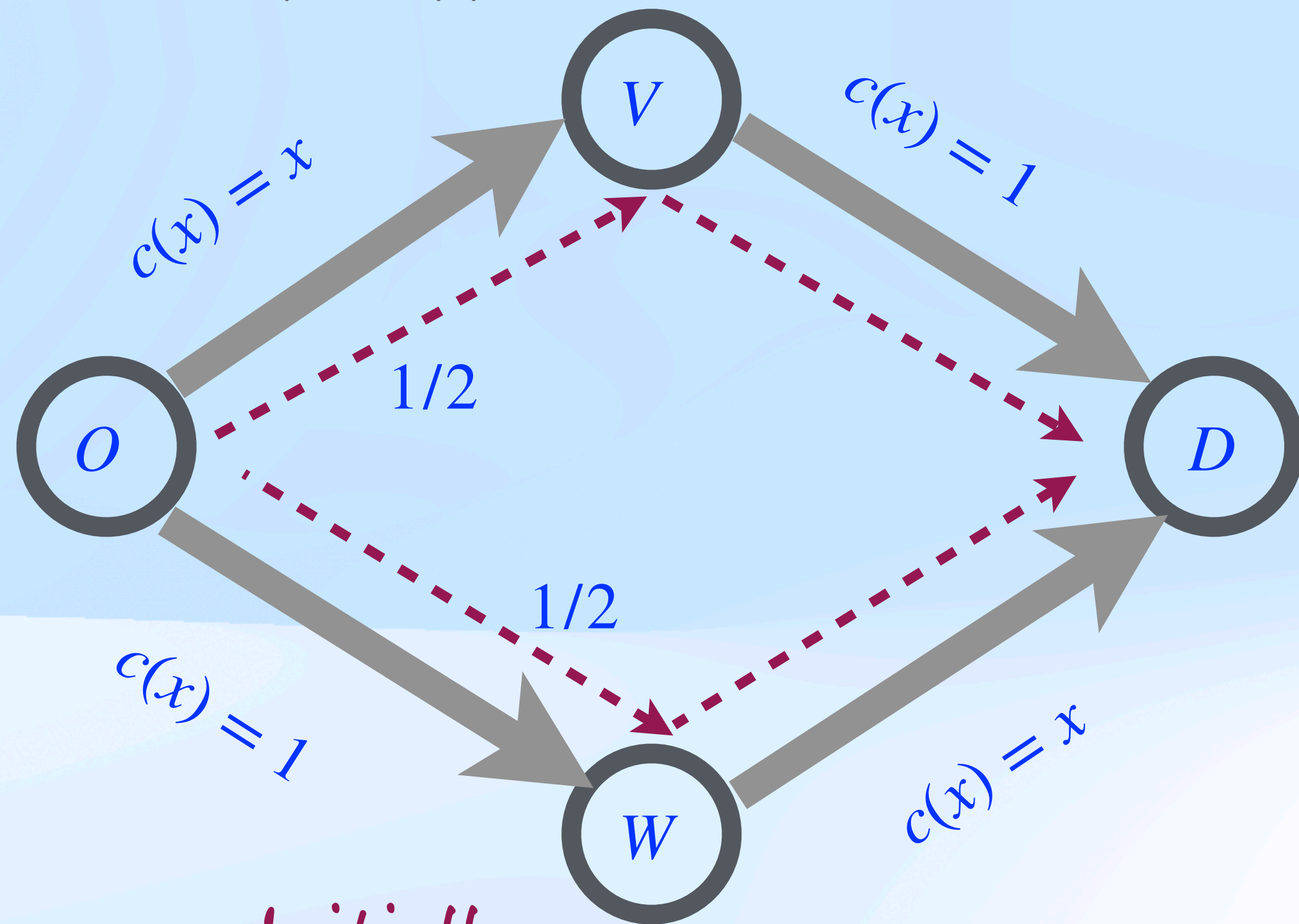
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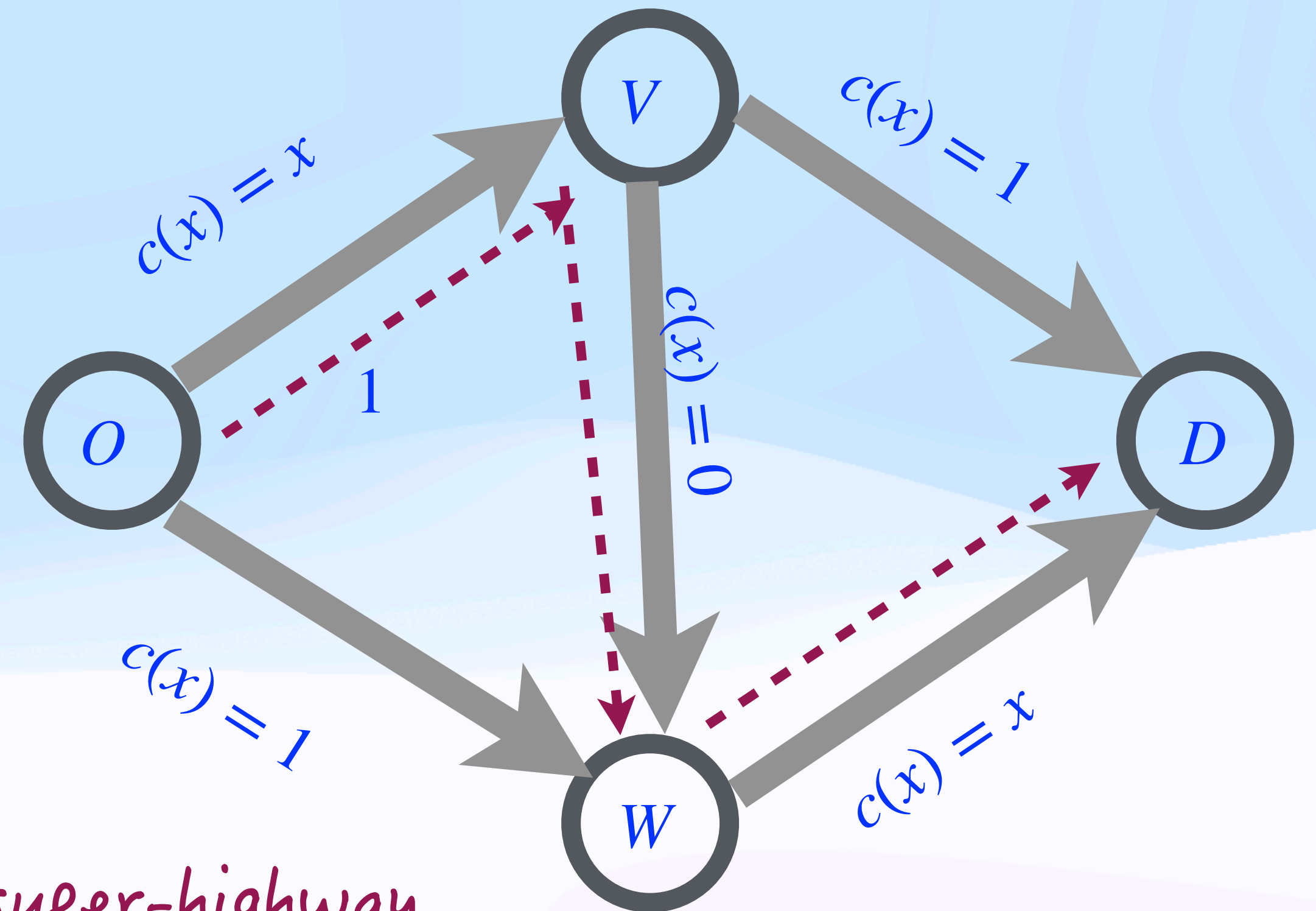
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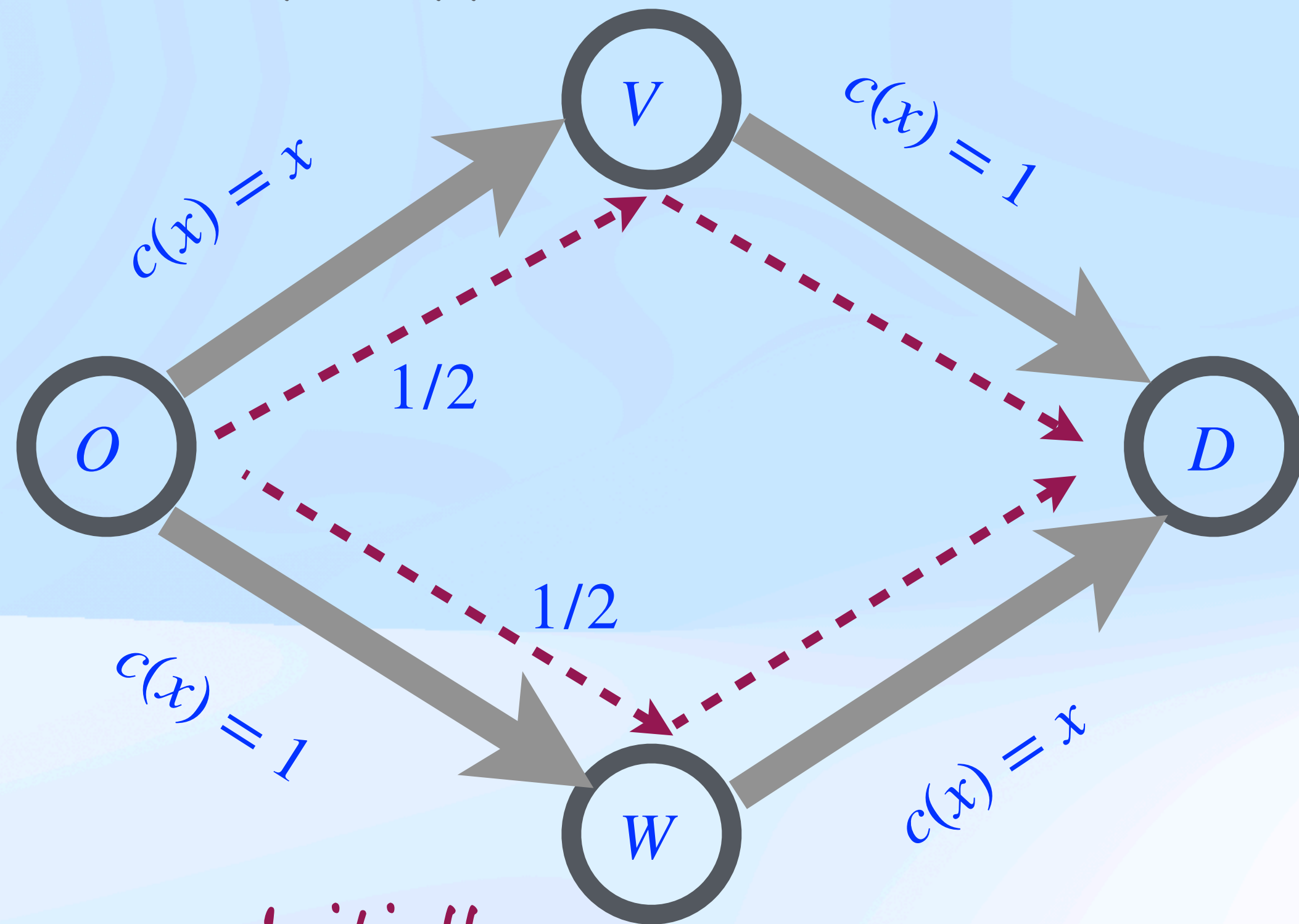
After super-highway



Travel time in DS

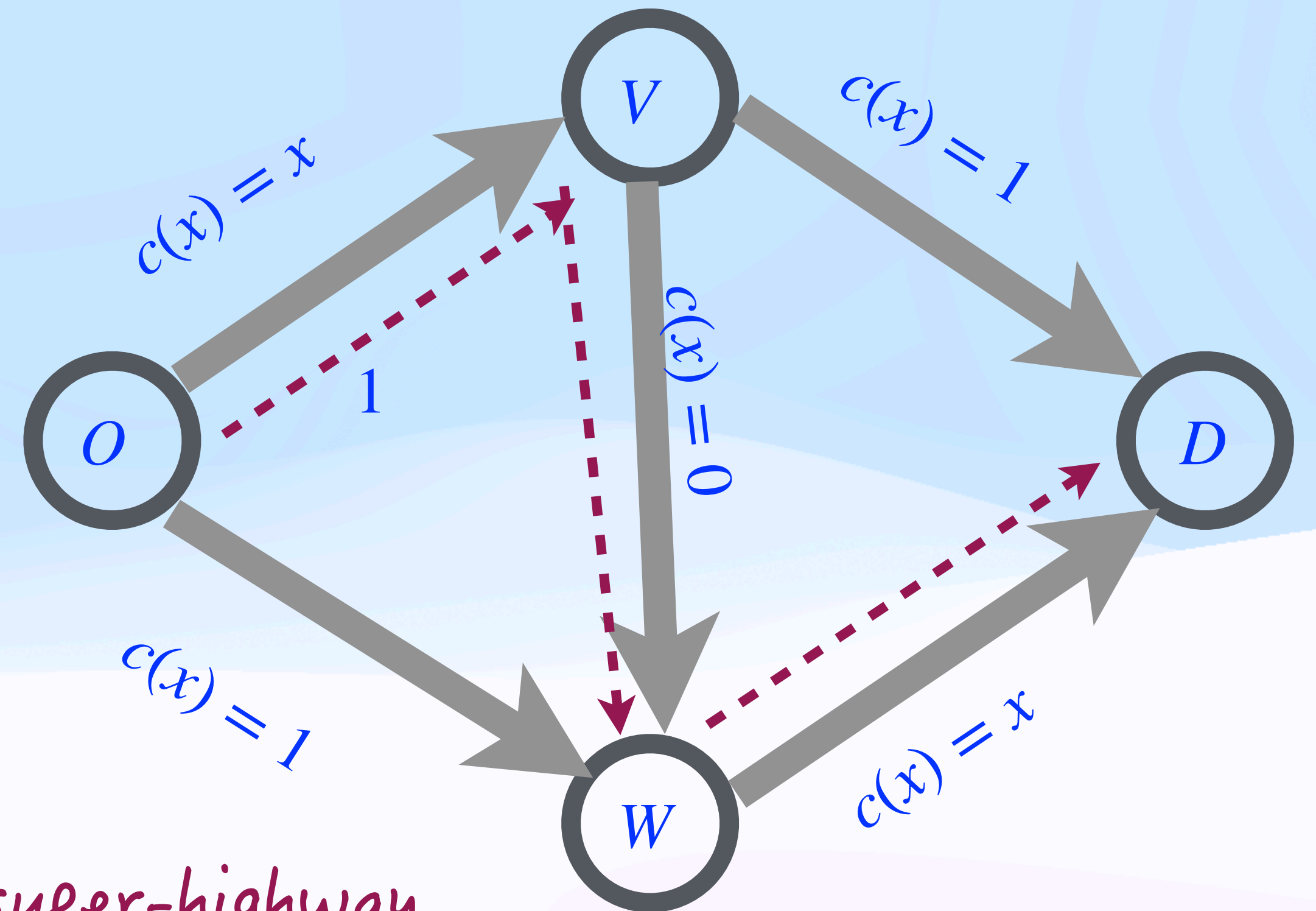
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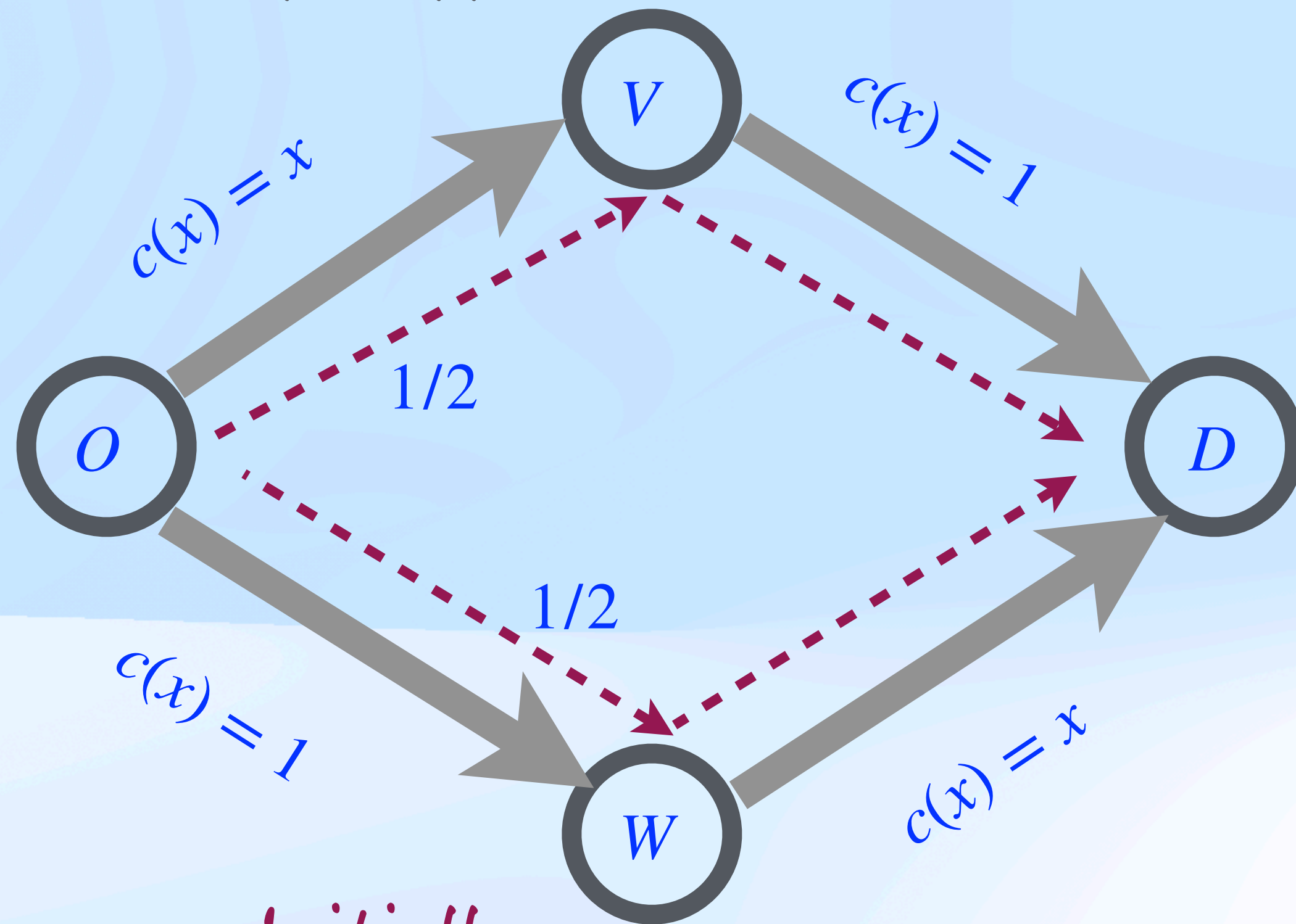


After super-highway

Travel time in DS $= 1 \cdot 1 + 0 + 1 \cdot 1 = 2$

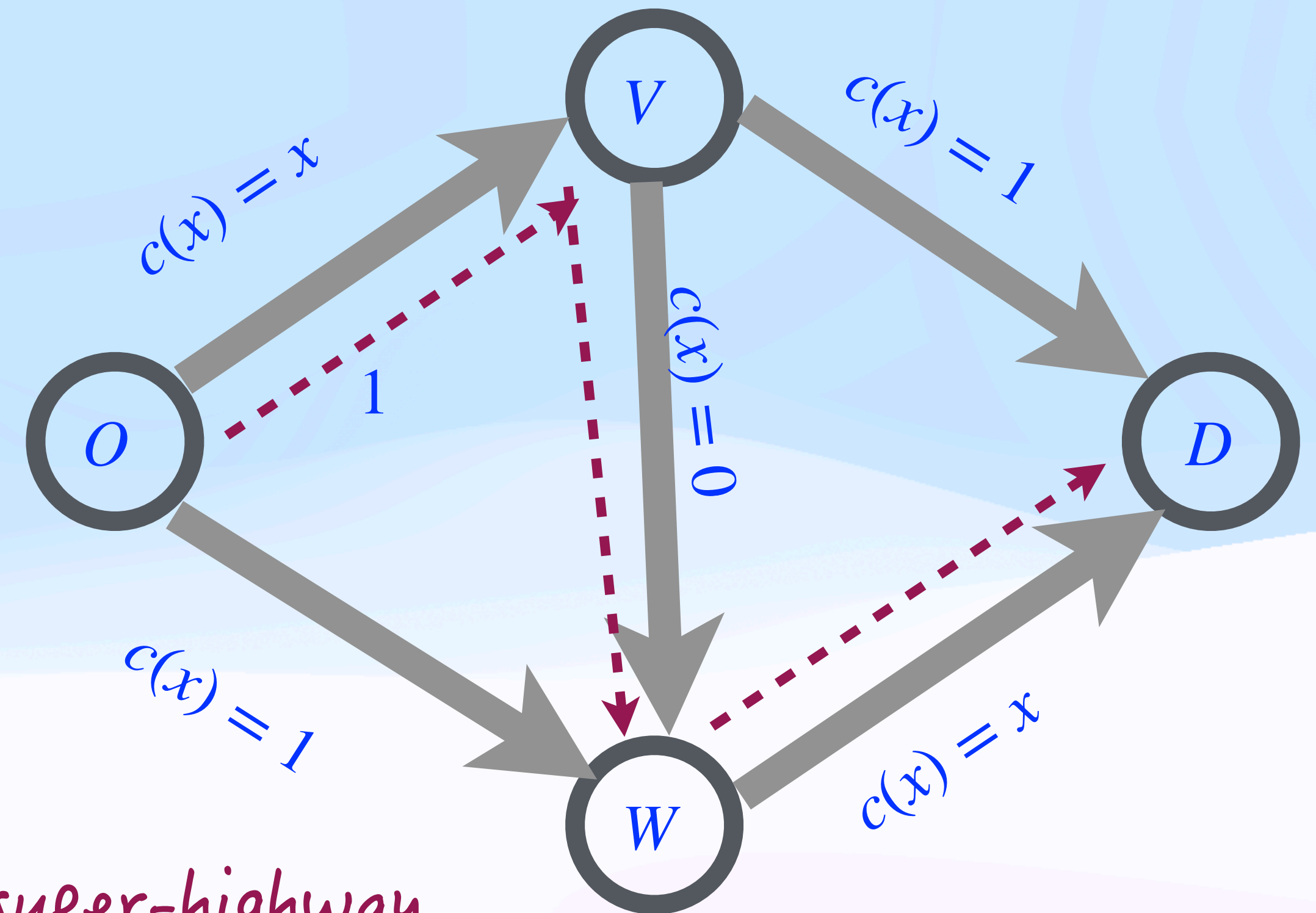
Braess Network, 1965

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Travel time $= 2 \left(\frac{1}{2} \cdot \frac{1}{2} + \frac{1}{2} \cdot 1 \right) = \frac{3}{2}$

After super-highway

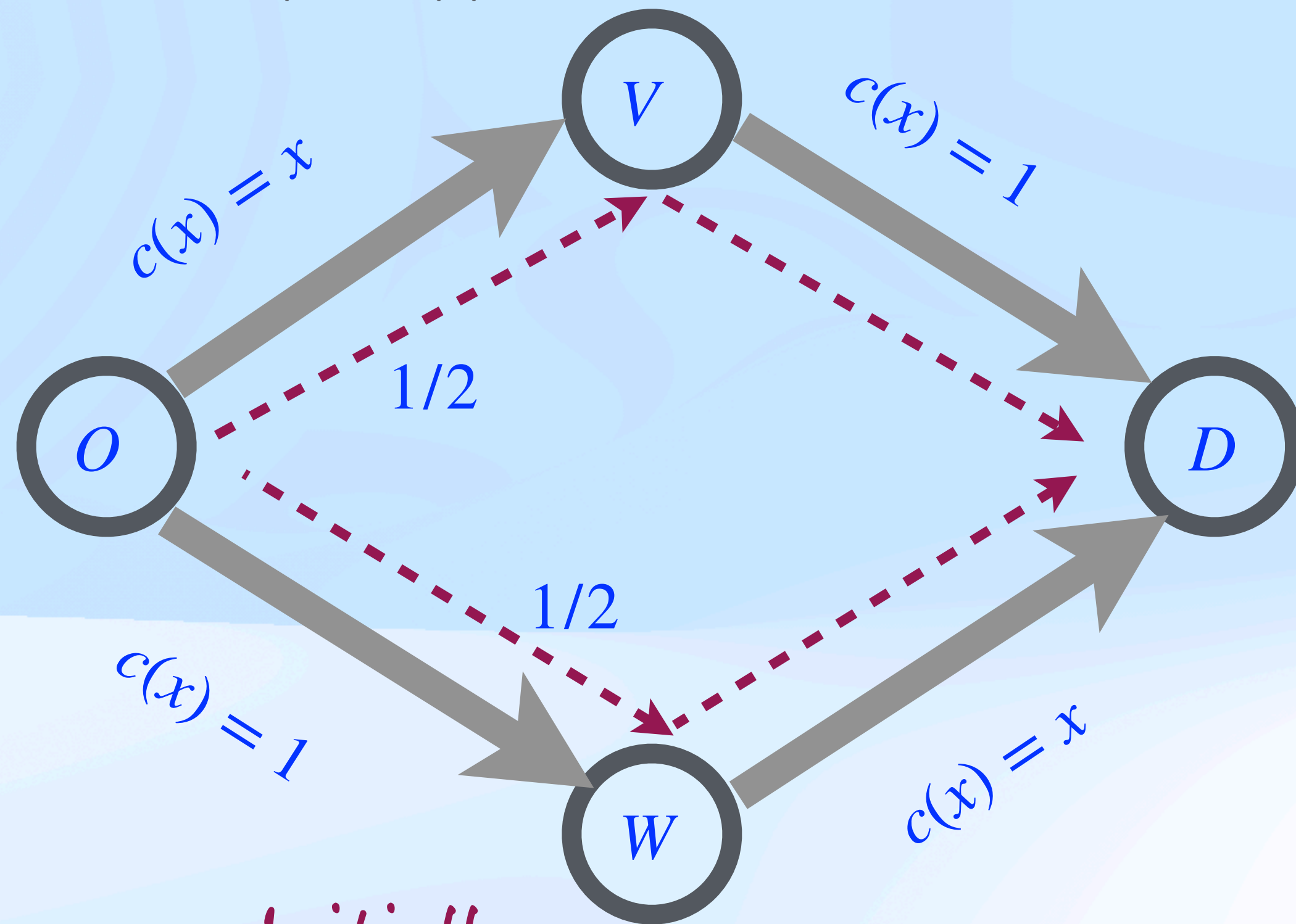


Travel time in DS $= 1 \cdot 1 + 0 + 1 \cdot 1 = 2$

It is taking more time!!

Braess Network, 1965

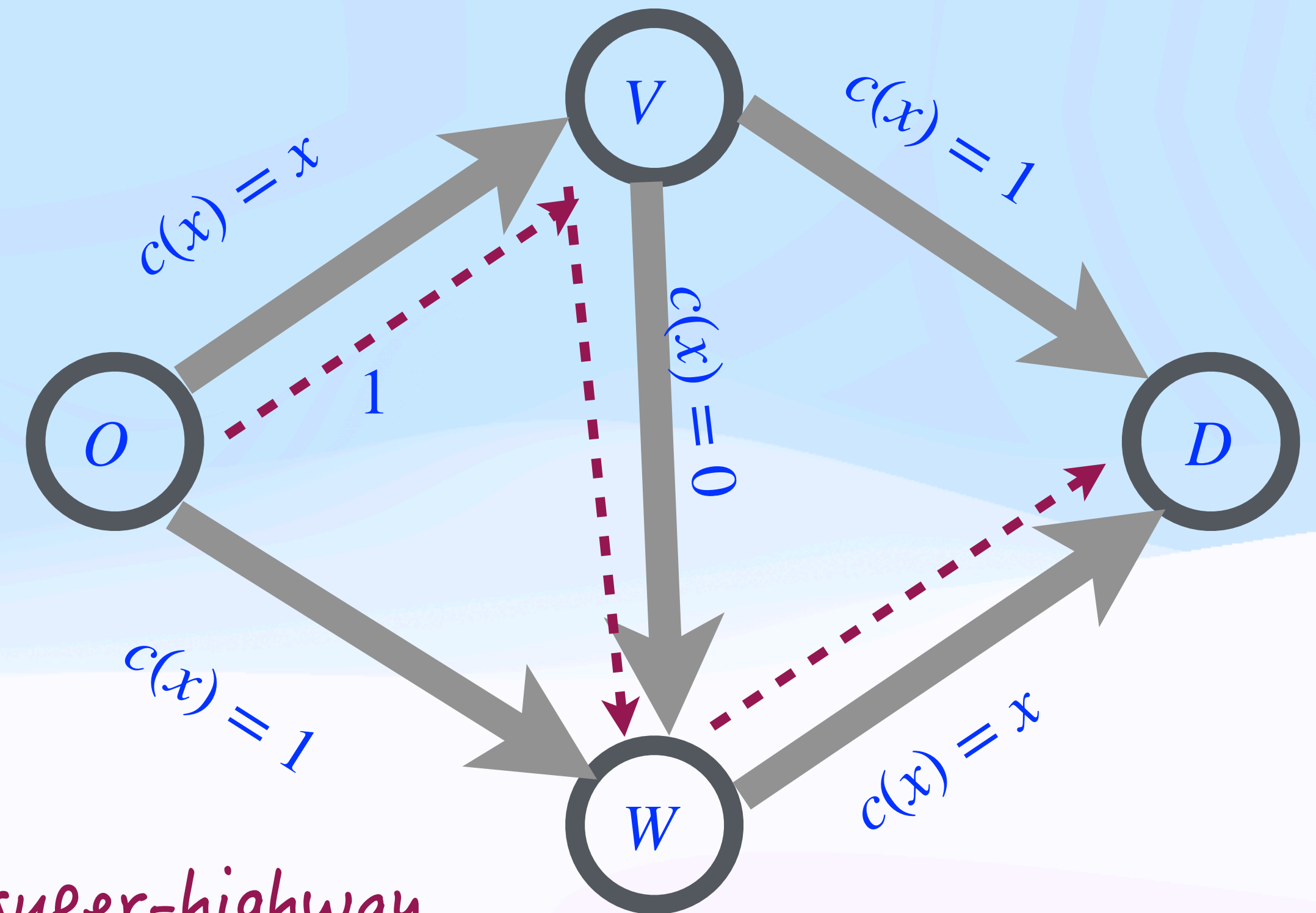
1 unit of traffic



Travel time $= 2 \left(\frac{1}{2} \cdot \frac{1}{2} + \frac{1}{2} \cdot 1 \right) = \frac{3}{2}$

Price Of Selfish behavior $= \frac{2}{3/2} = \frac{4}{3}$

After super-highway



Travel time in DS $= 1 \cdot 1 + 0 + 1 \cdot 1 = 2$

It is taking more time!!

What is the price of selfish behaviour?

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In Pigou network loss due to selfish behaviour is
33 %

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What if the network structure is more complex?

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...many more vertices, roads, different source-destination pairs etc

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What if the cost functions are more complex ?

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In Pigou network loss due to selfish behaviour is
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What if the network structure is more complex ?

...many more vertices, roads, different source-destination pairs etc

What if the cost functions are more complex ?

Can this get worse ?

What if the network is more complicated ??

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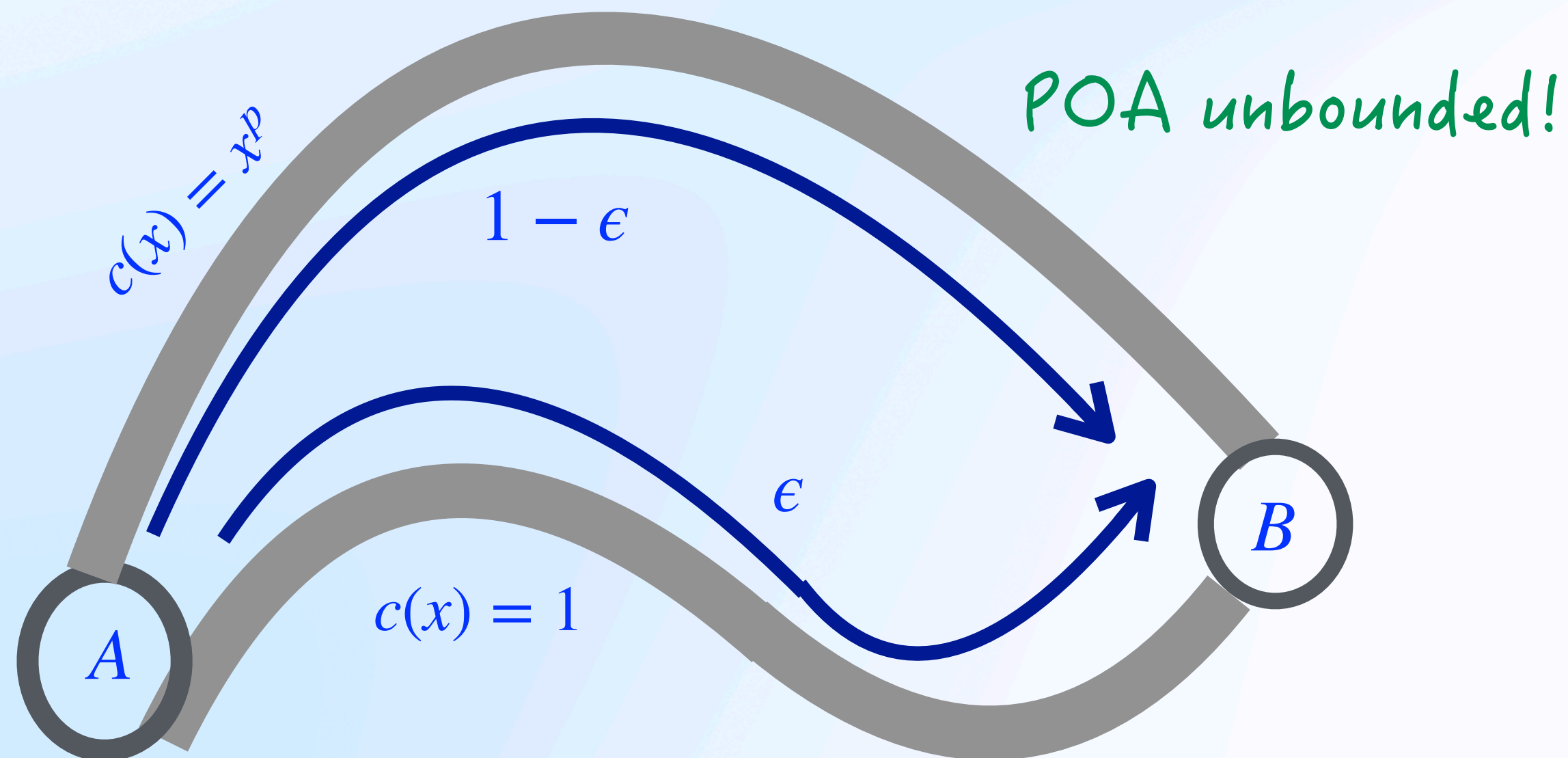
Roughgarden and Tardos 2002

In every network routing game with linear (or affine) cost function the price of selfishness is $\frac{4}{3}$

What if the network is more complicated ??

Roughgarden and Tardos 2002

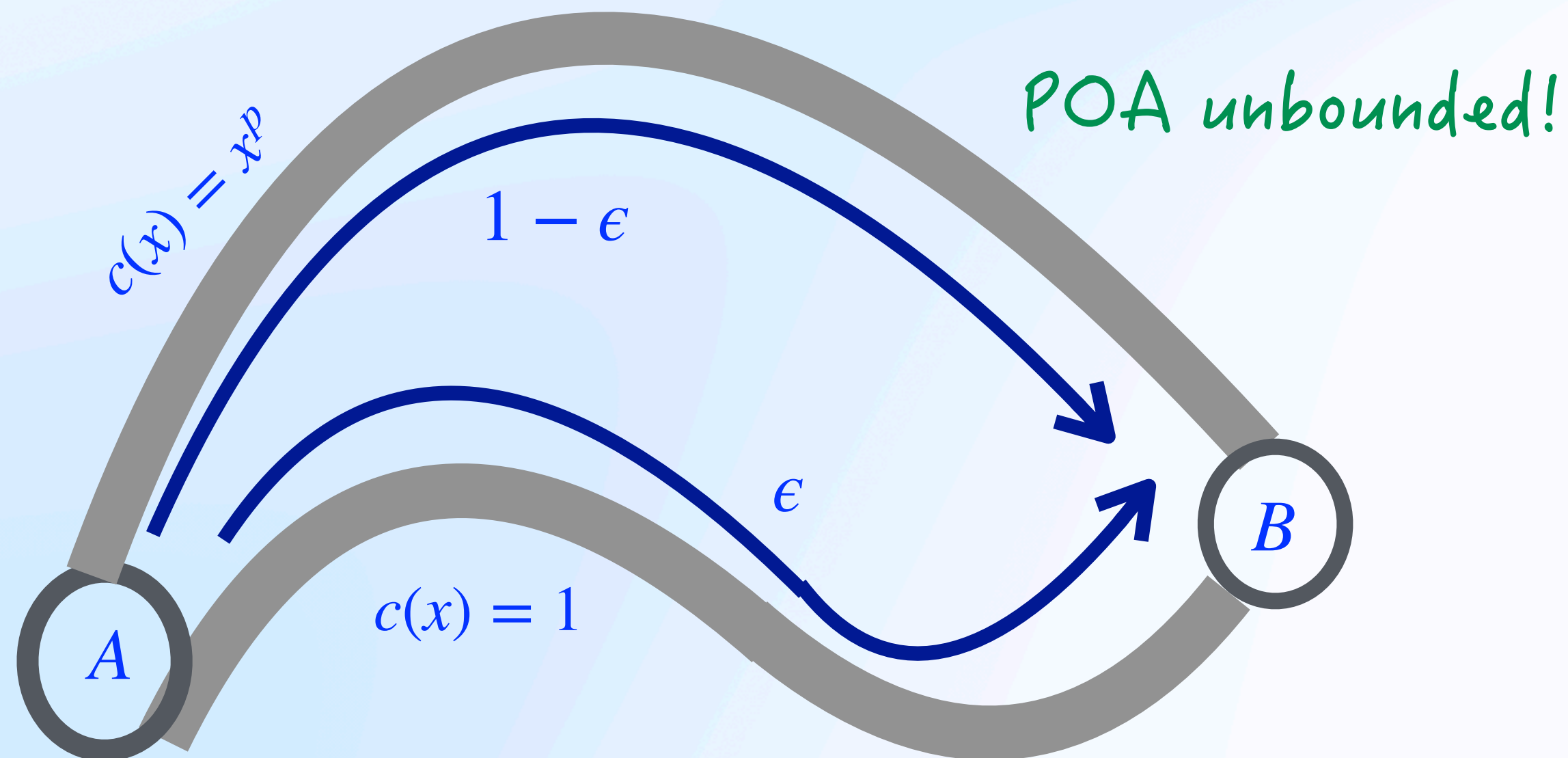
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What if the network is more complicated ??

Roughgarden and Tardos 2002


In every network routing game with linear (or affine) cost function the price of selfishness is $\frac{4}{3}$



Journey of 80 years!

Moral of the story: Culprits are non-linear cost functions!

Different kinds of selfish routing

The background features a light blue upper section with faint, concentric circular patterns. Below this, there are large, flowing, white and light blue shapes that resemble stylized waves or clouds. A prominent, soft pink oval shape is positioned in the middle-right area, partially overlapping the white and blue forms.

Different kinds of selfish routing

Nonatomic Selfish Routing

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Agents have negligible size and individuals have negligible impact on the network

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Eg: road traffic, private users of communication network

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Atomic Selfish Routing

Each agent controls a significant fraction of the overall traffic.

Different kinds of selfish routing

Nonatomic Selfish Routing

Agents have negligible size and individuals have negligible impact on the network

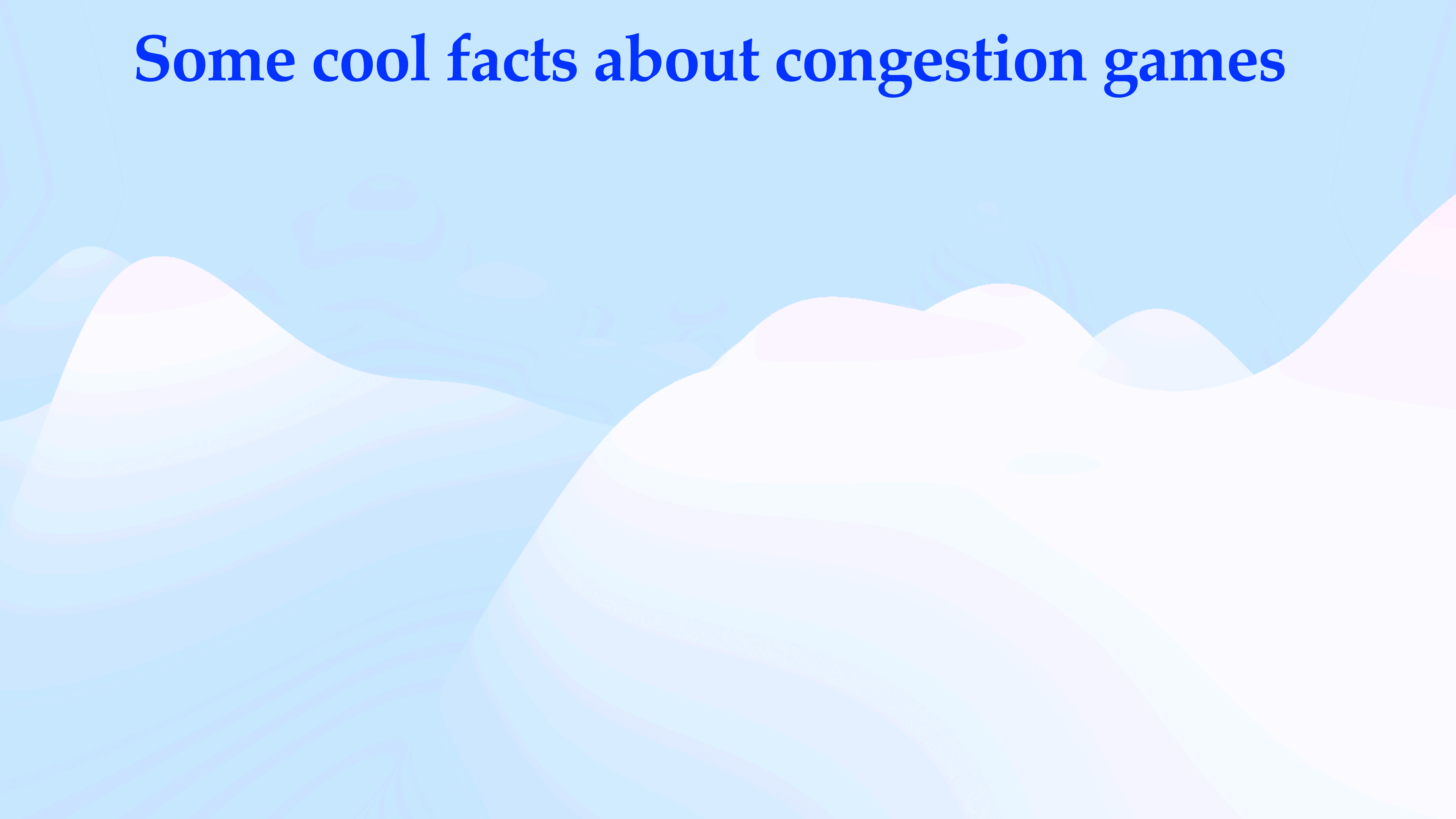
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Each agent controls a significant fraction of the overall traffic.

Eg: an agent could represent an ISP responsible for routing the data of a large number of end users

Some cool facts about congestion games



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What is the rate of convergence?

What is the computational complexity of finding an equilibrium?

The background features a soft, abstract landscape. In the foreground, there are rolling hills or mountains rendered in pastel shades of pink, light blue, and white, with subtle horizontal banding. The sky is a solid light blue, containing a faint, thin-lined semi-circle at the top center. The overall aesthetic is clean, modern, and gentle.

Thank You!

Proof Details

We will prove

Among all networks with cost function \mathcal{C} , the largest *POA* is achieved in a Pigou-like network.

More formally

For every set \mathcal{C} of cost function and every selfish routing network with cost function in \mathcal{C} , the

$$POA = \frac{\text{Flow in DSE}}{\text{Optimum flow}} \text{ is at most } \alpha(\mathcal{C}), \text{ where}$$

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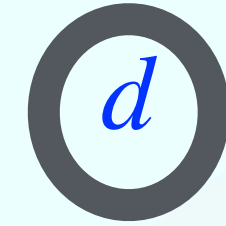
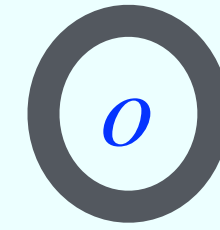
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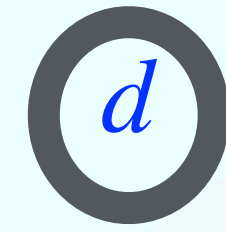
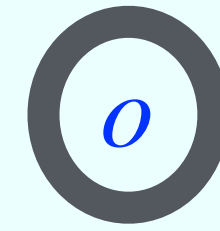
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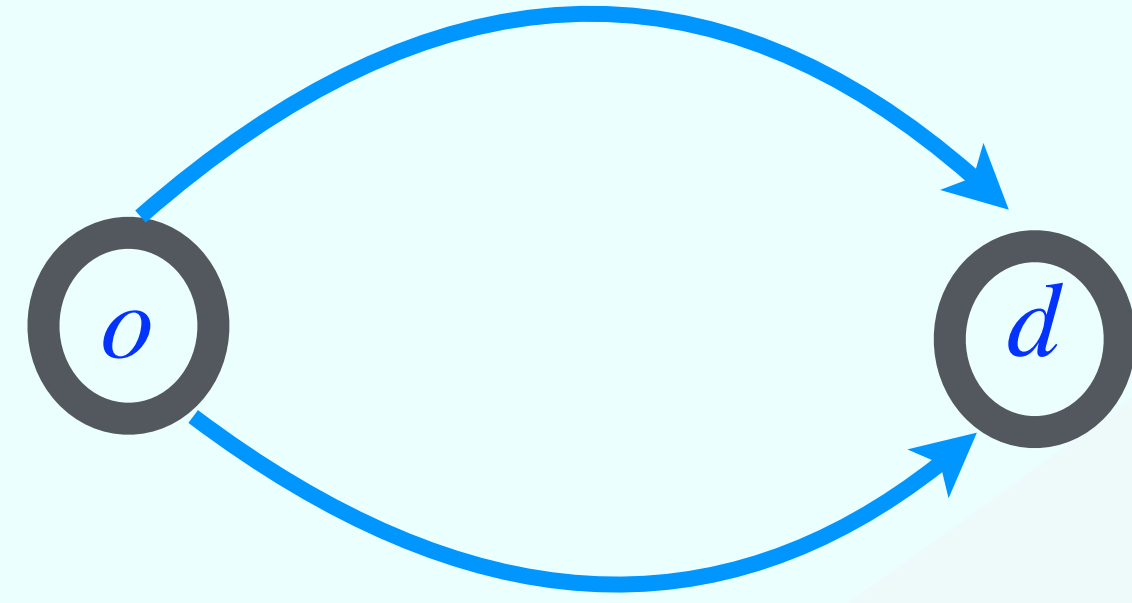
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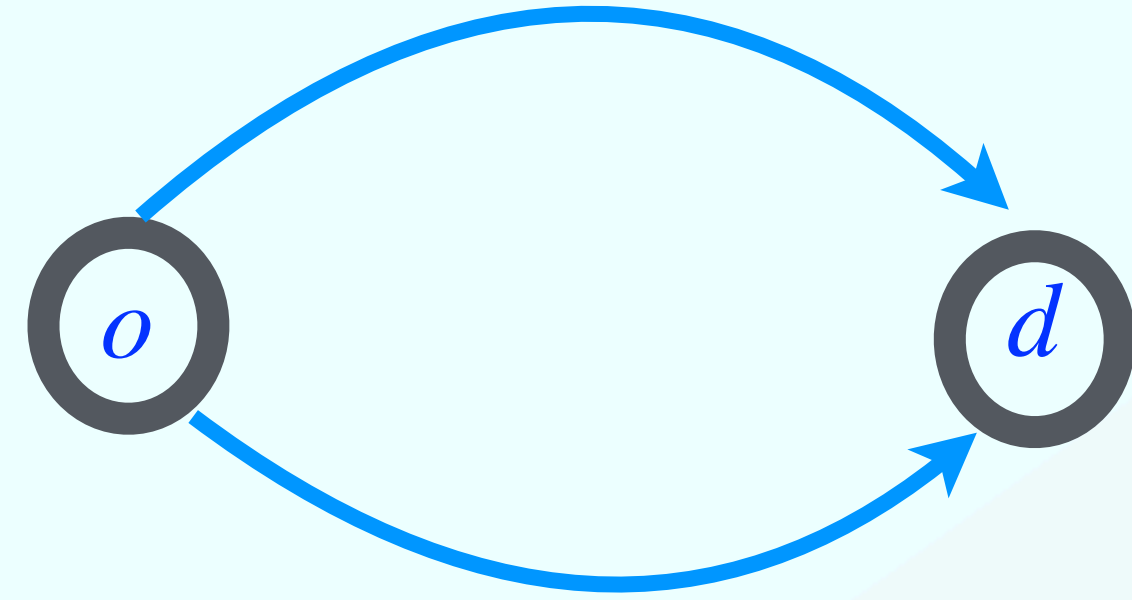
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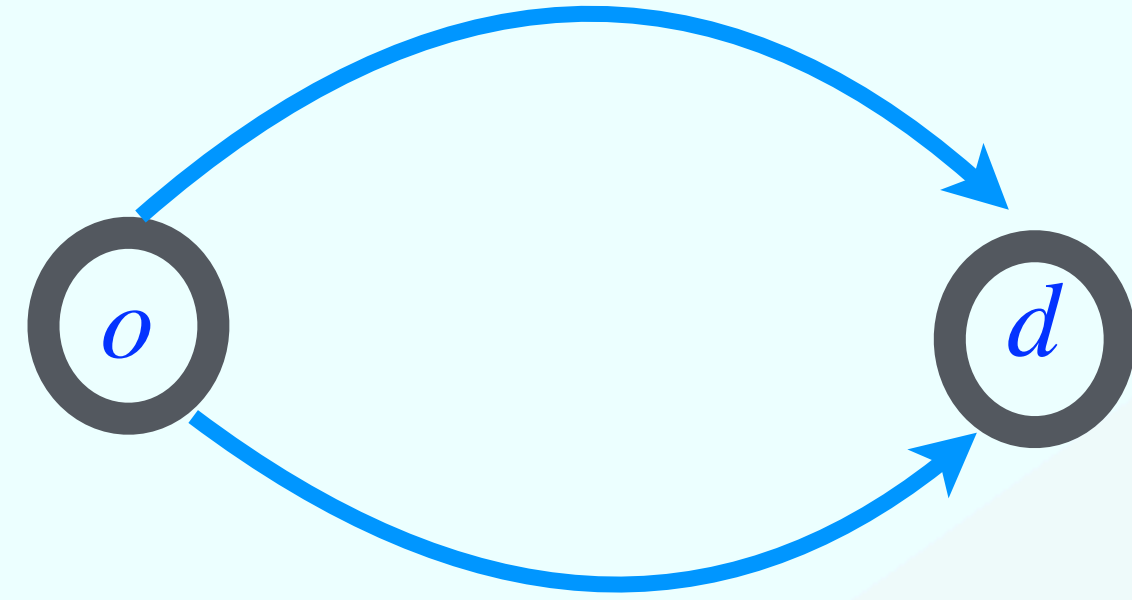
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3. A non-negative traffic rate r



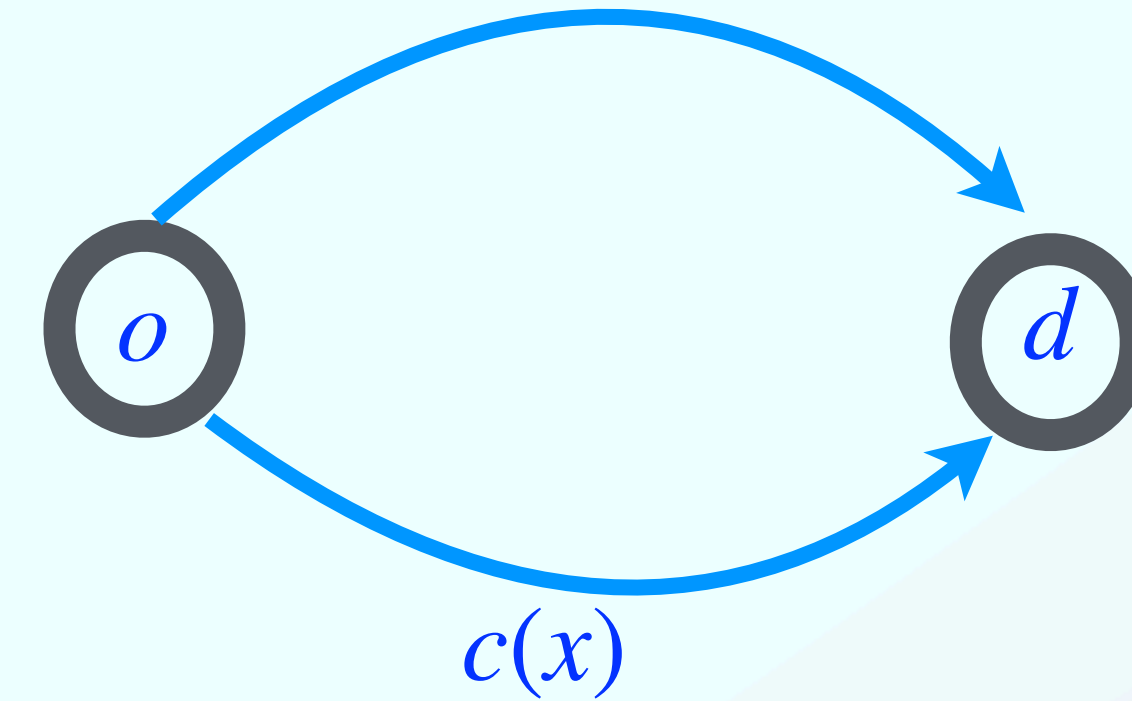
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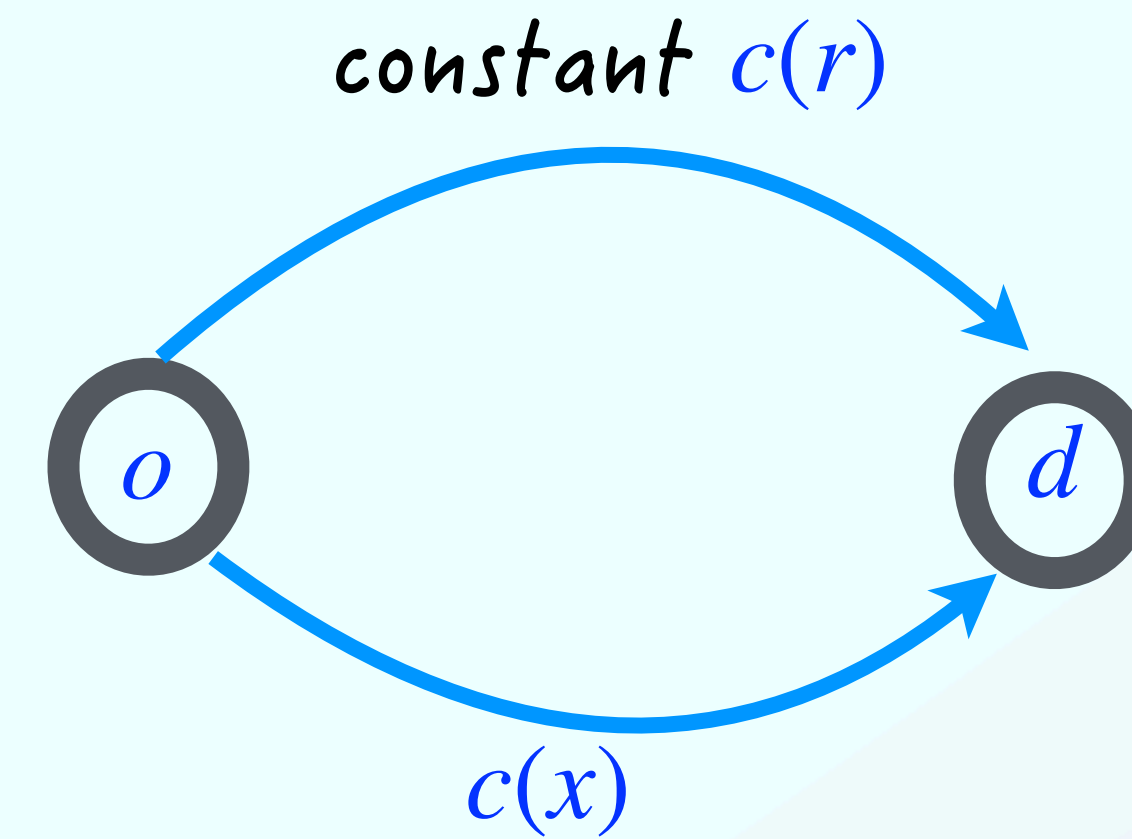
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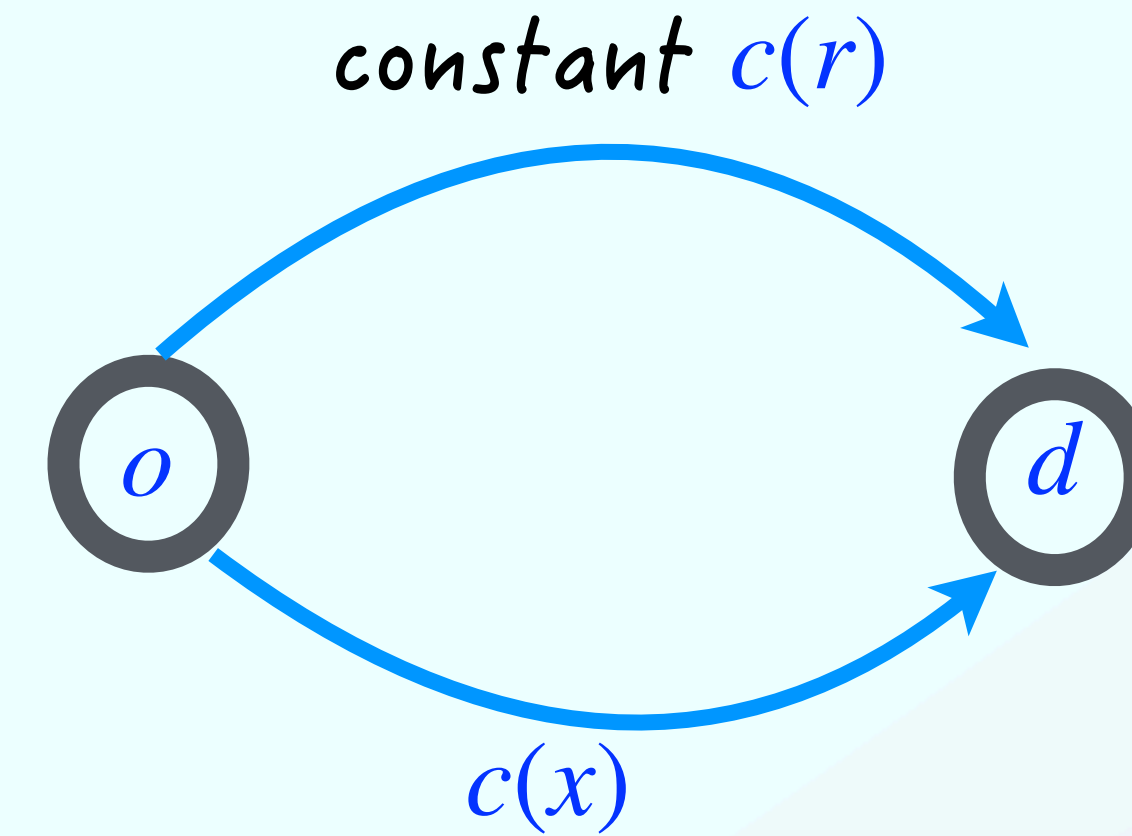
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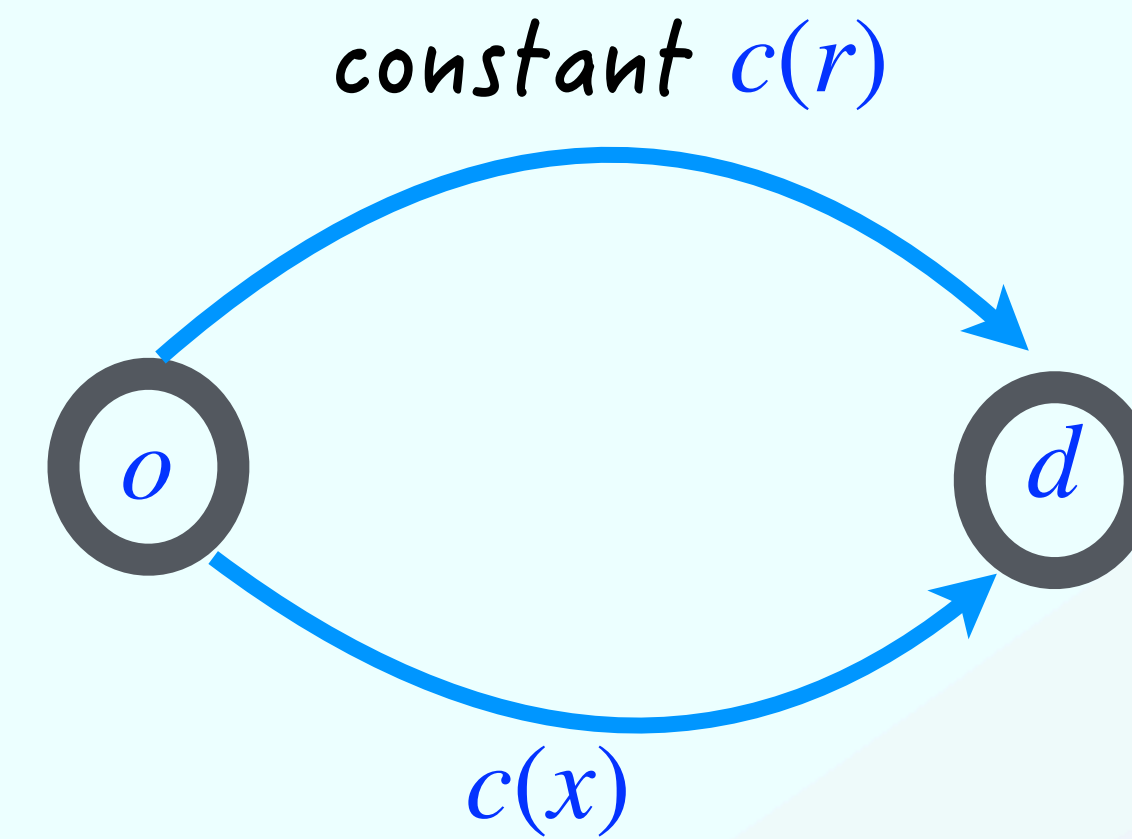
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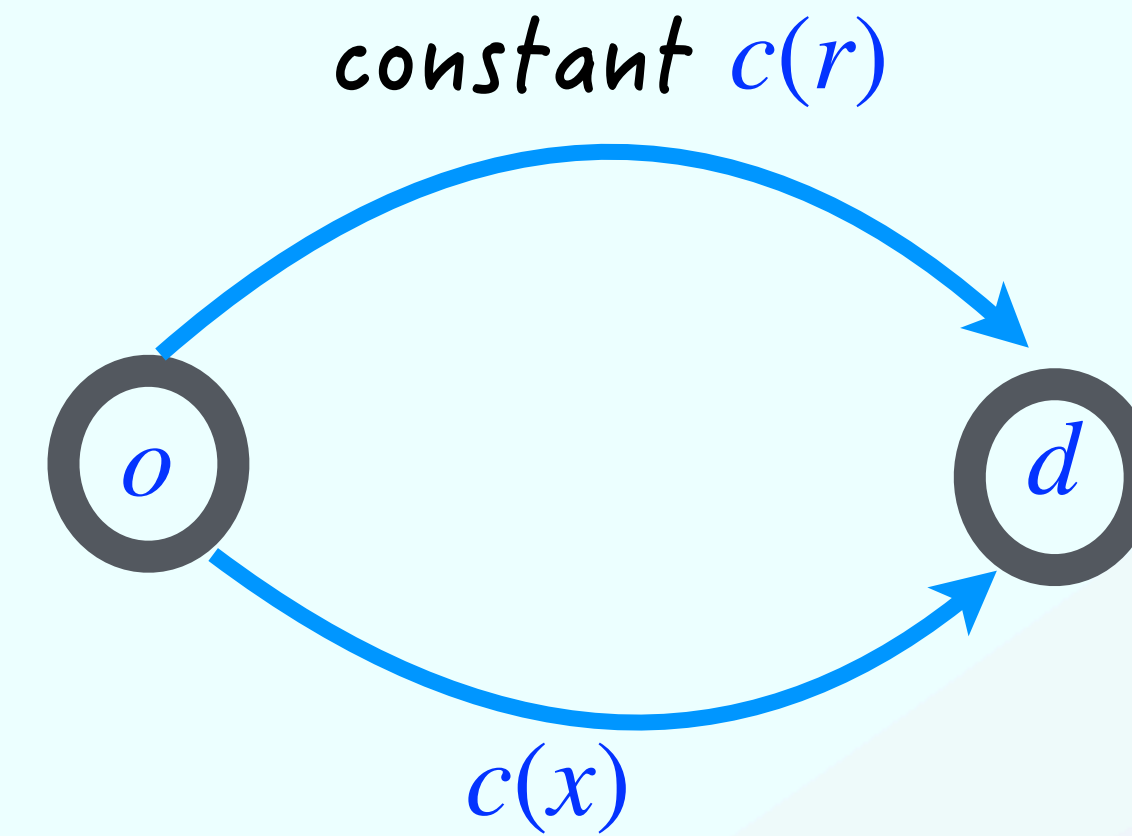
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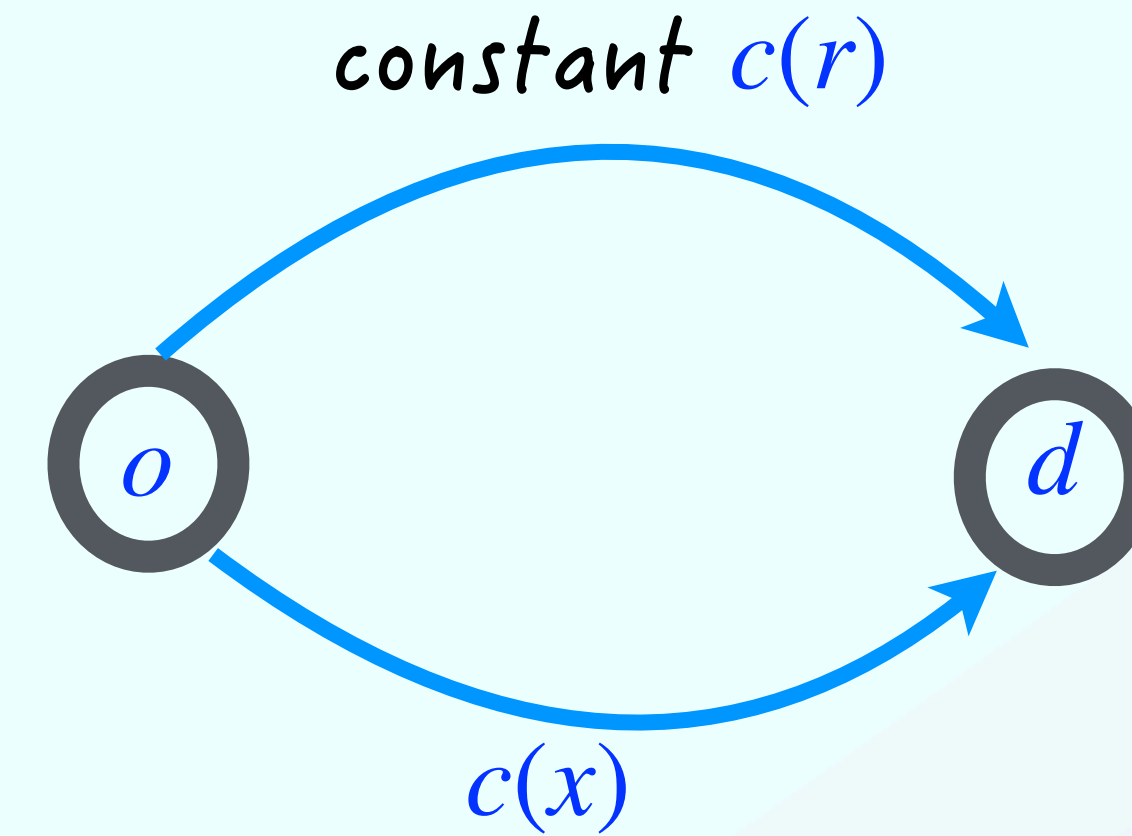


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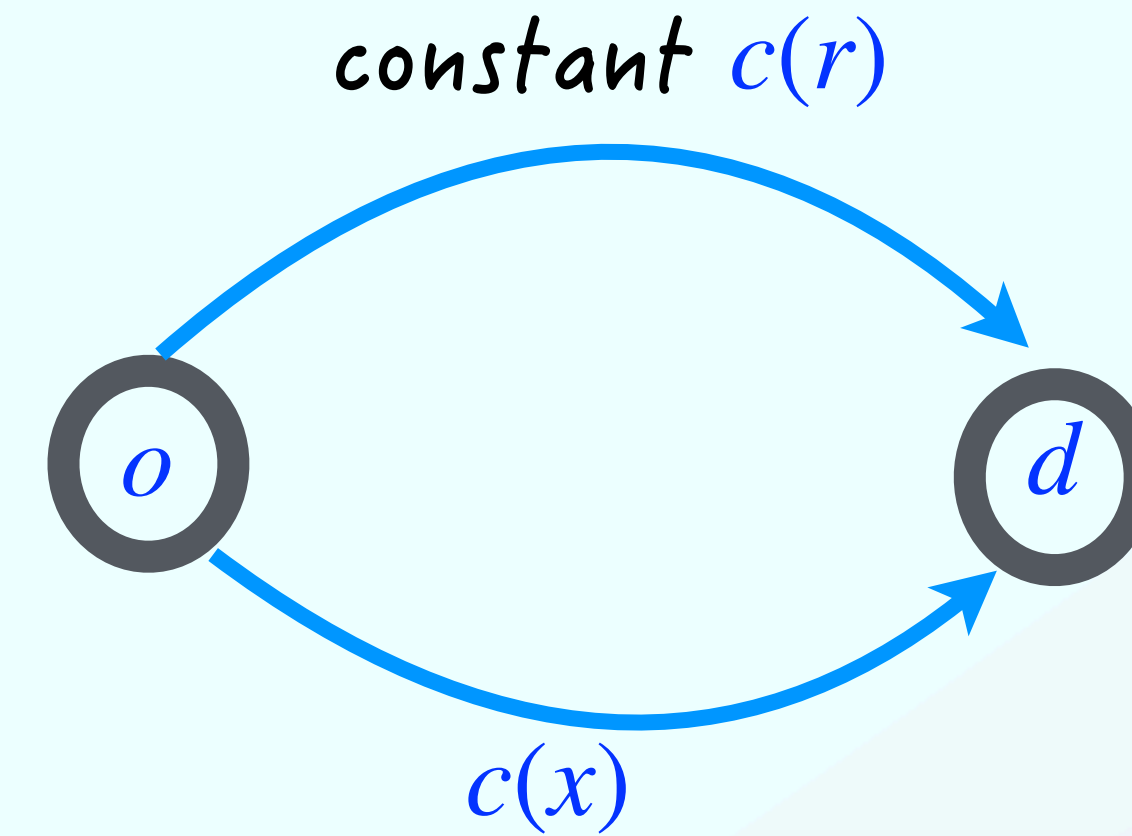
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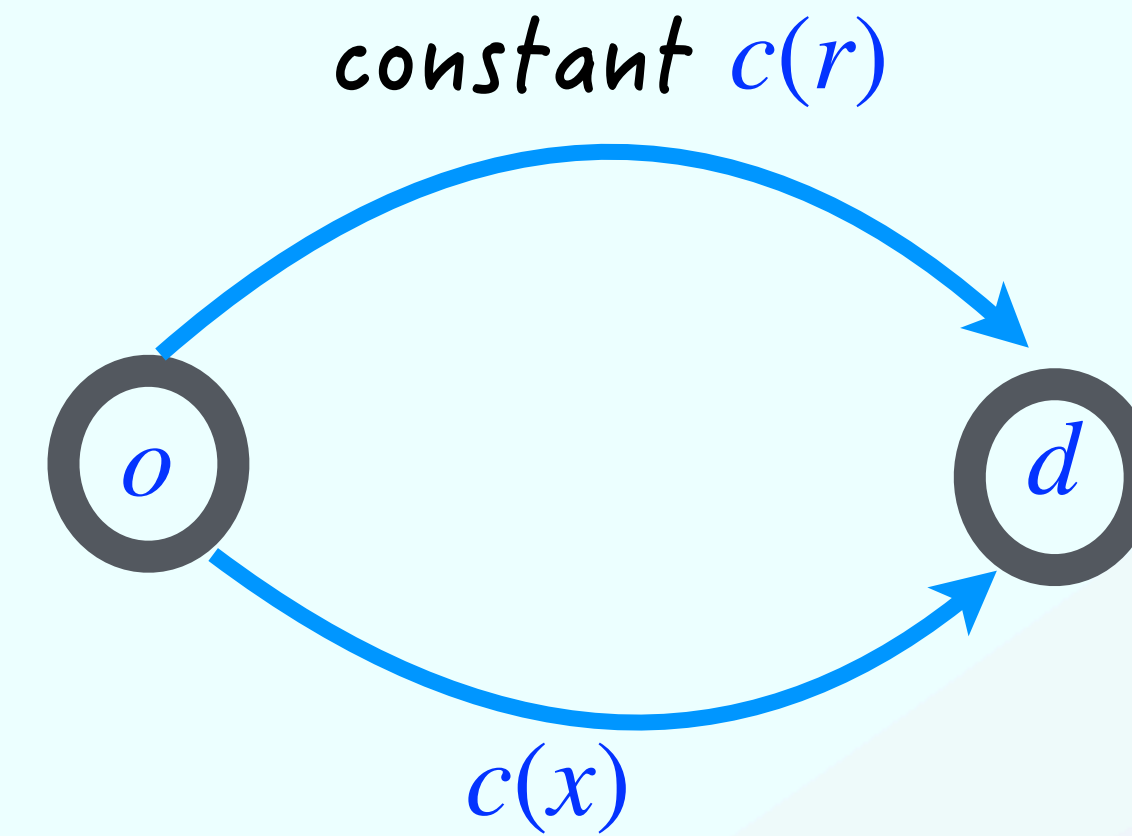
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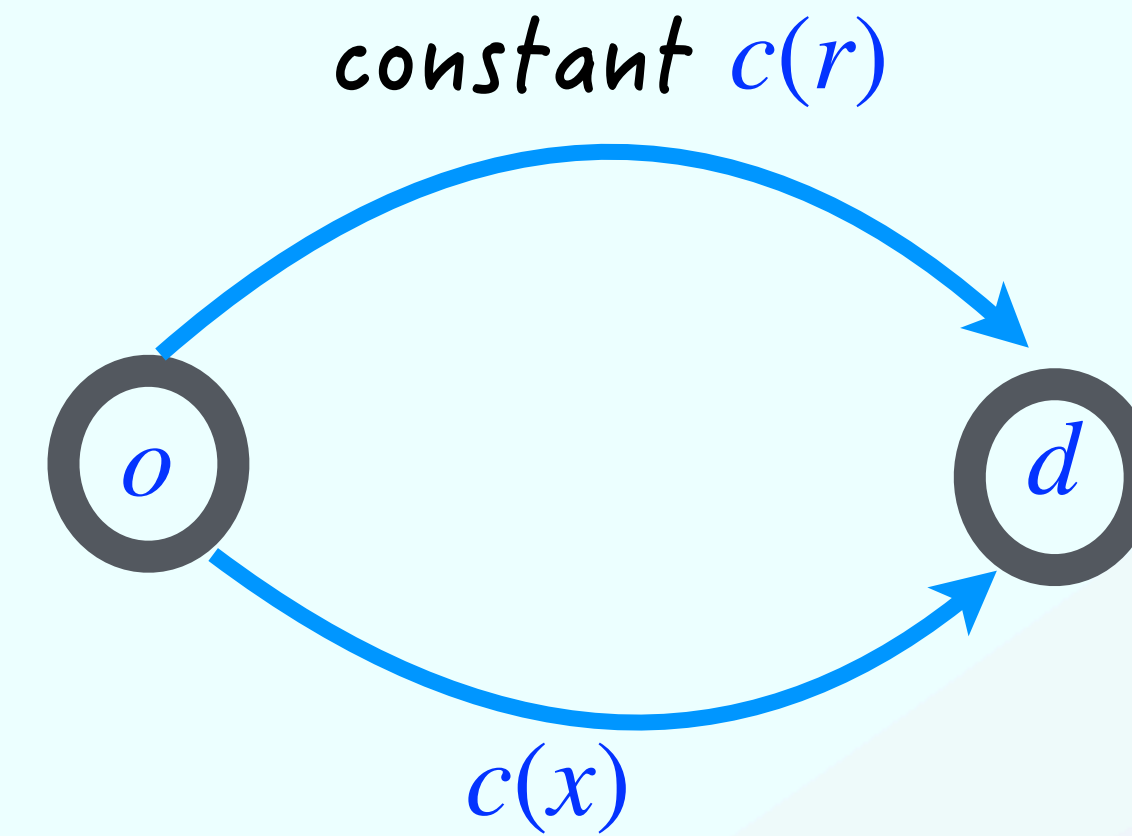
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Worst POA with
polynomial cost
functions with
positive coefficient

Description	Typical Representative	Price of Anarchy
Linear	$ax + b$	$4/3$
Quadratic	$ax^2 + bx + c$	$\frac{3\sqrt{3}}{3\sqrt{3}-2} \approx 1.6$
Cubic	$ax^3 + bx^2 + cx + d$	$\frac{4\sqrt[3]{4}}{4\sqrt[3]{4}-3} \approx 1.9$
Quartic	$ax^4 + bx^3 + cx^2 + dx + e$	$\frac{5\sqrt[4]{5}}{5\sqrt[4]{5}-4} \approx 2.2$
Degree $\leq p$	$\sum_{i=0}^p a_i x^i$	$\frac{(p+1)^{\frac{p}{p+1}}}{(p+1)^{\frac{p}{p+1}} - p} \approx \frac{p}{\ln p}$

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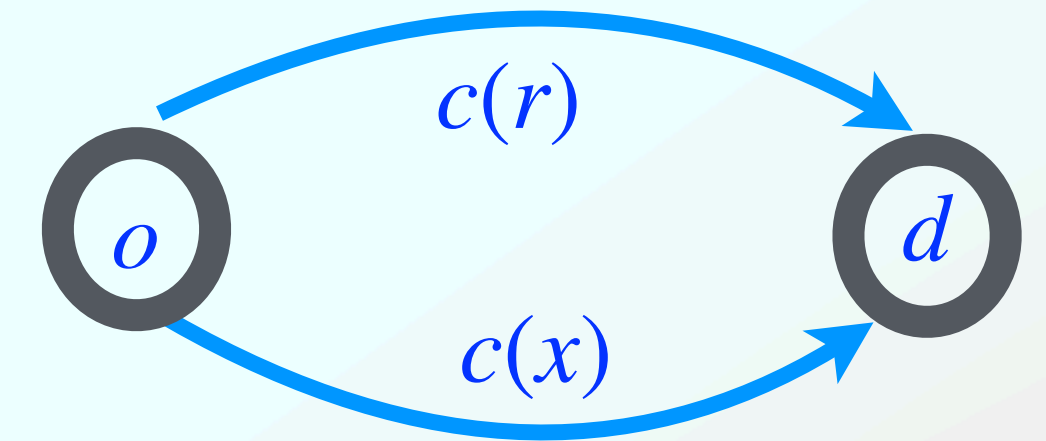
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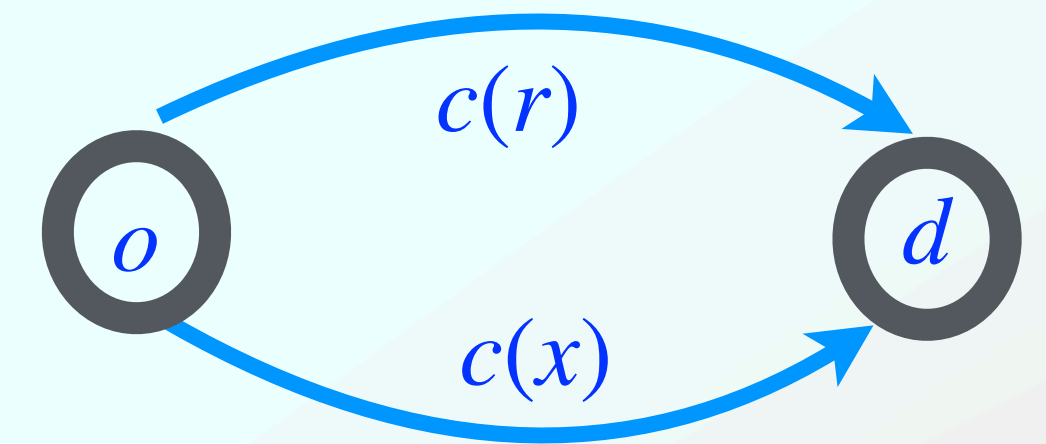
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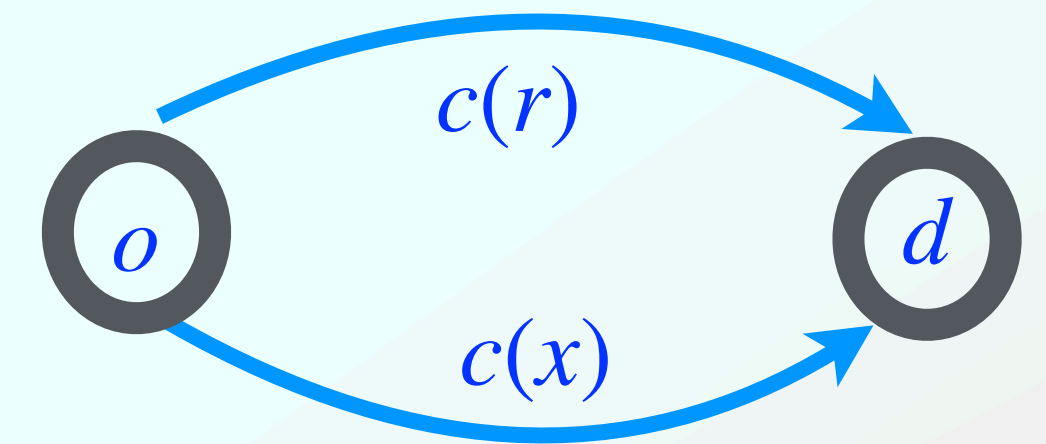


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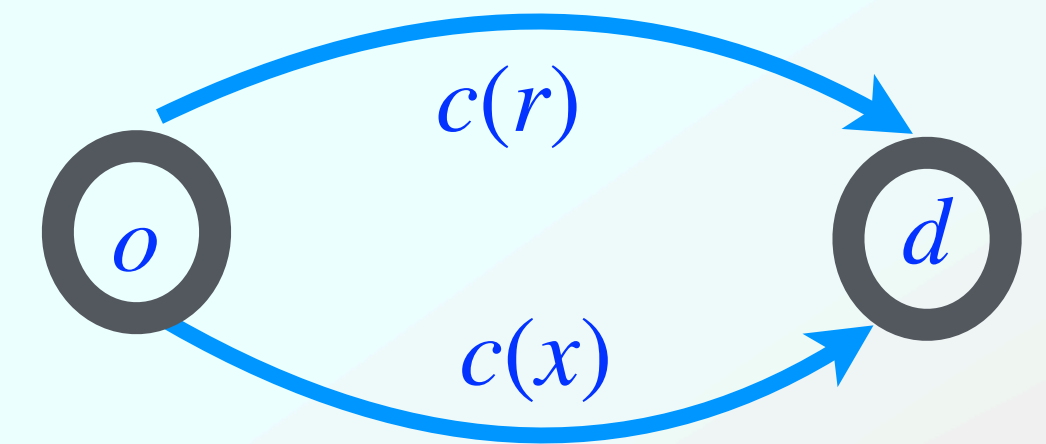
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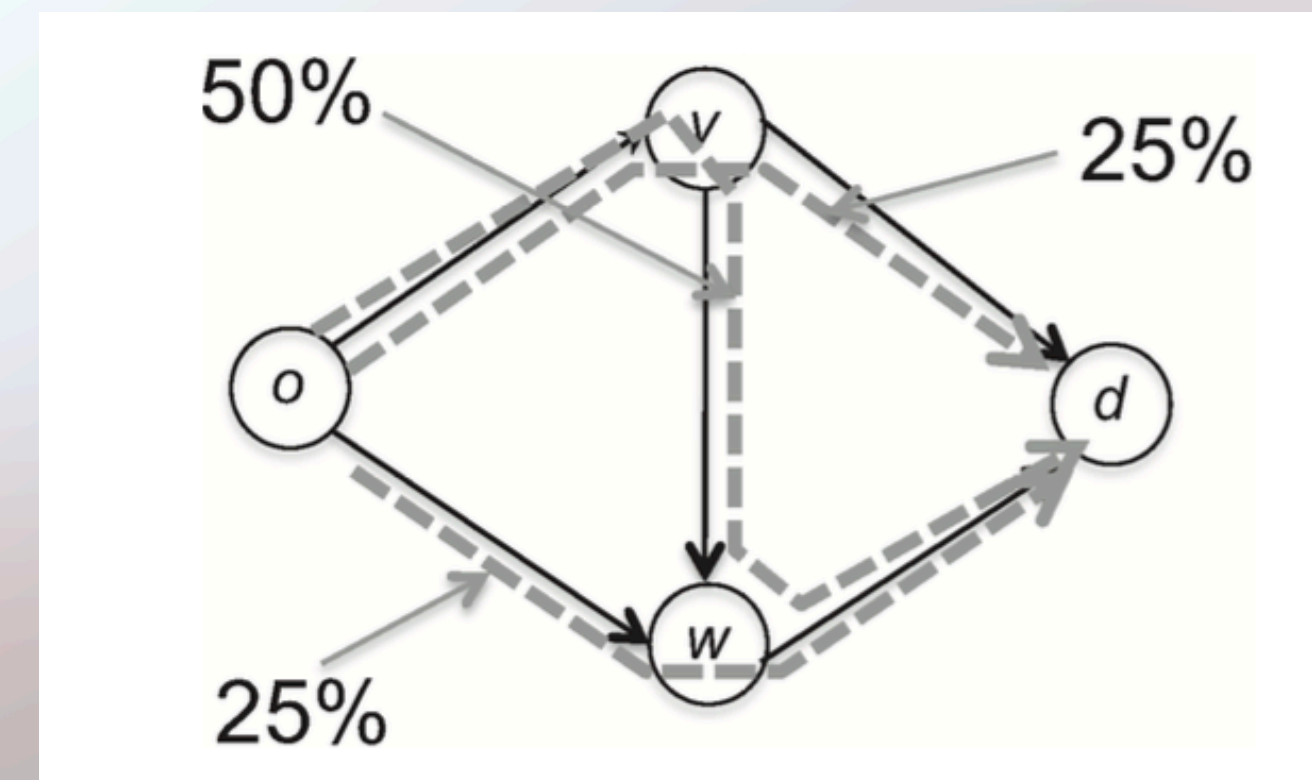
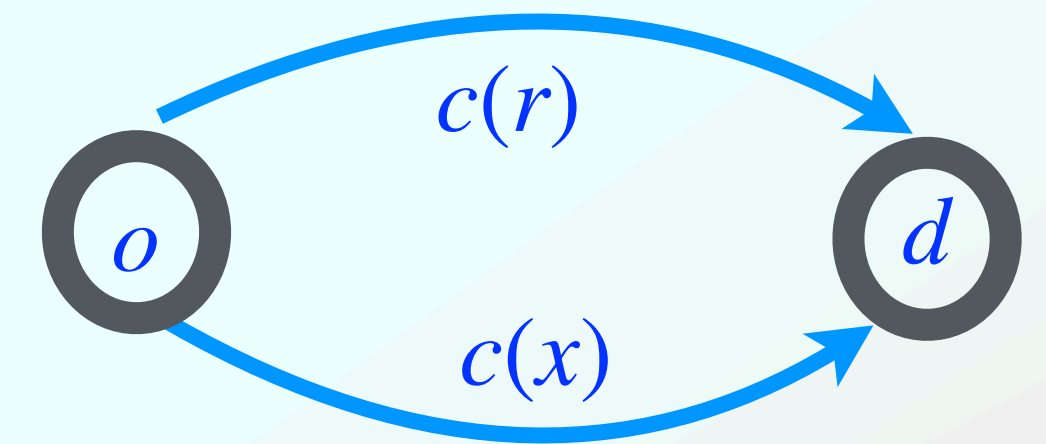
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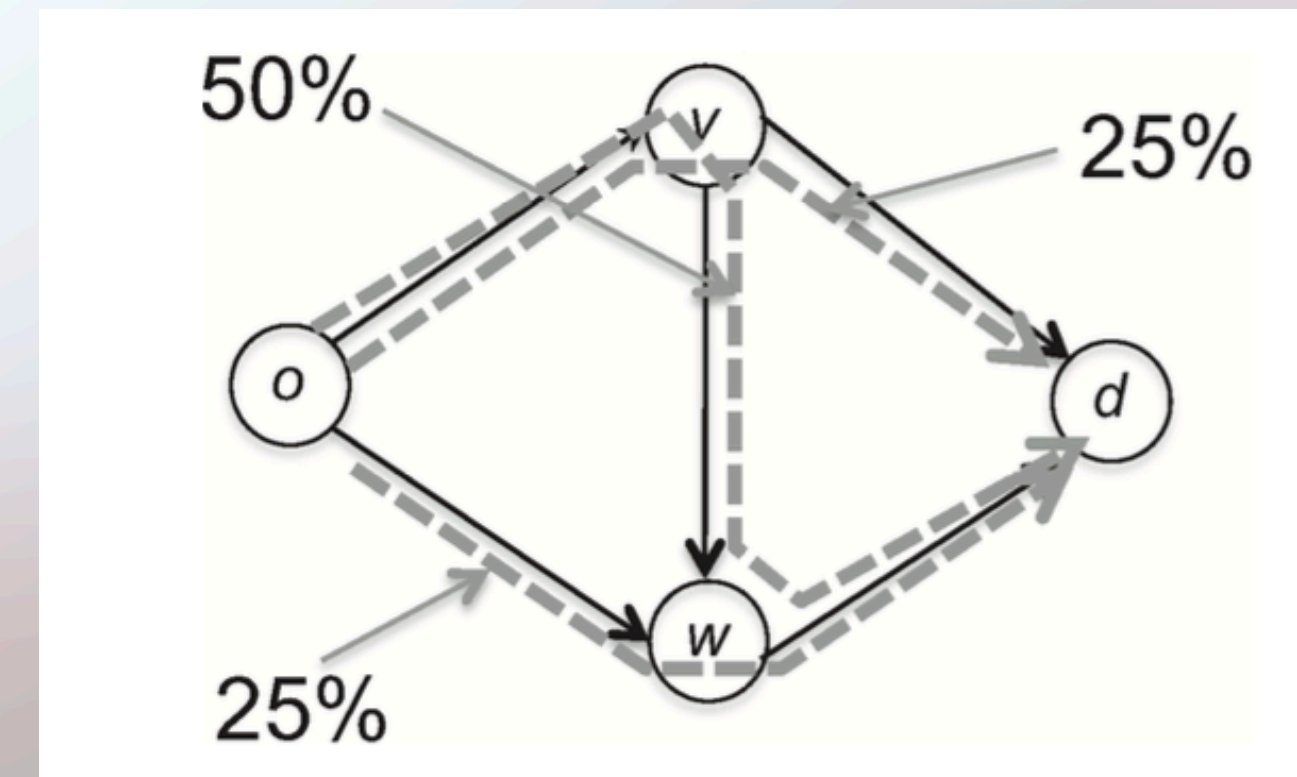
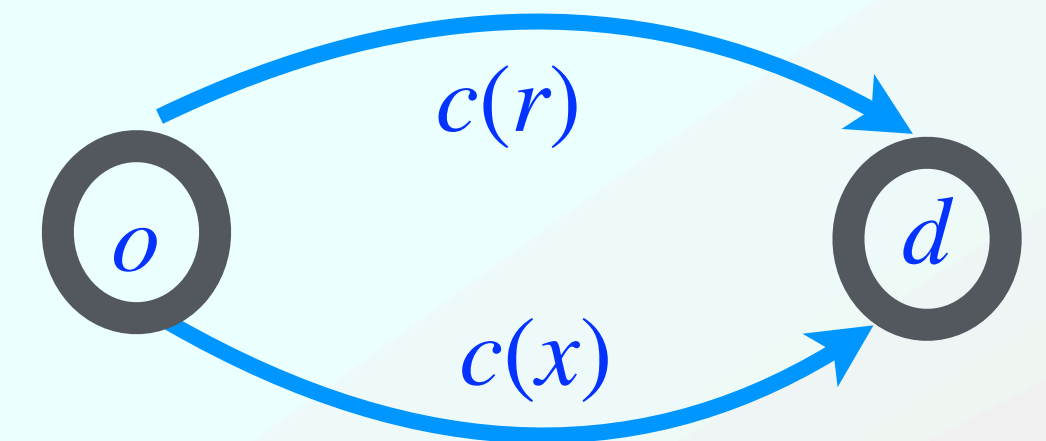


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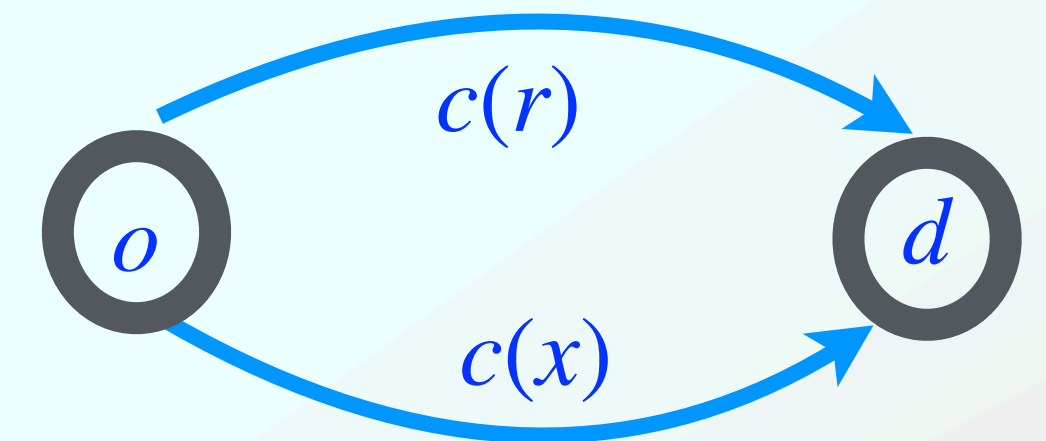


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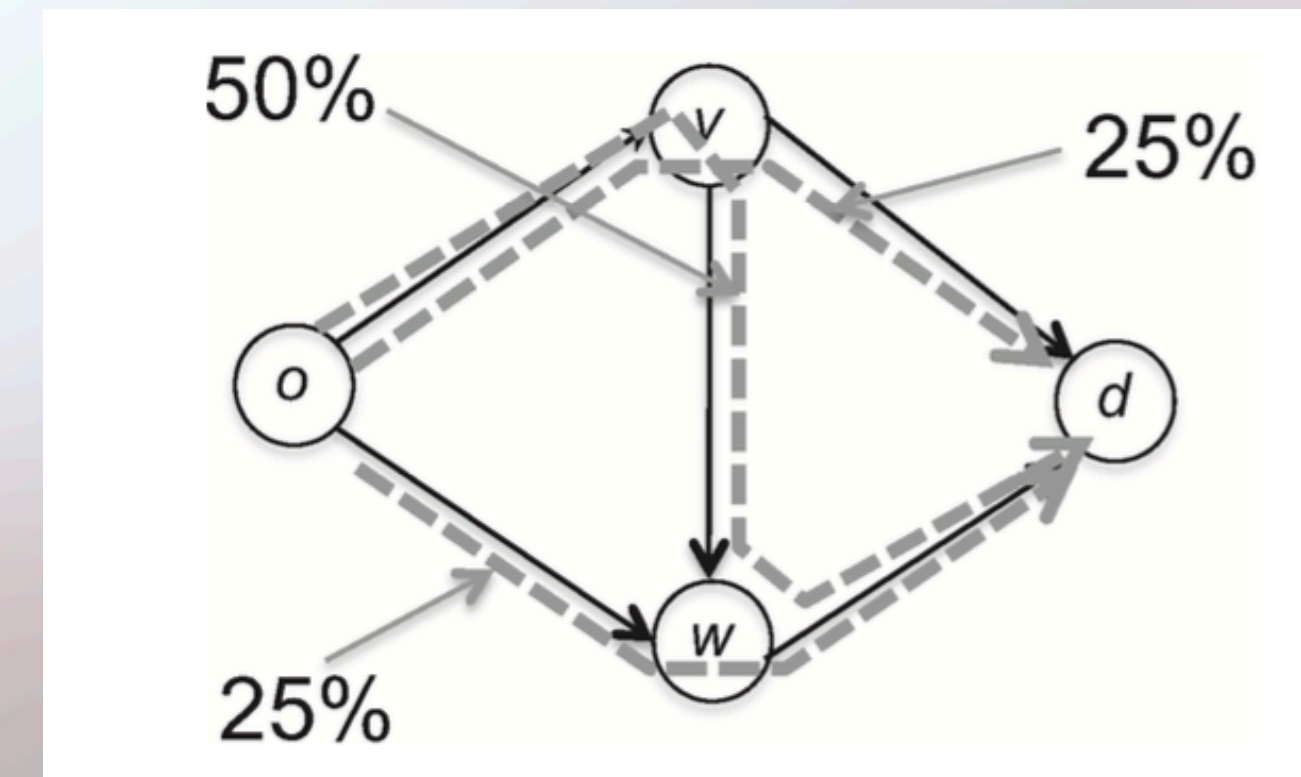
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For an edge $e \in E$ and flow f we write $f_e = \sum_{P \in \mathcal{P}: e \in P} f_P$

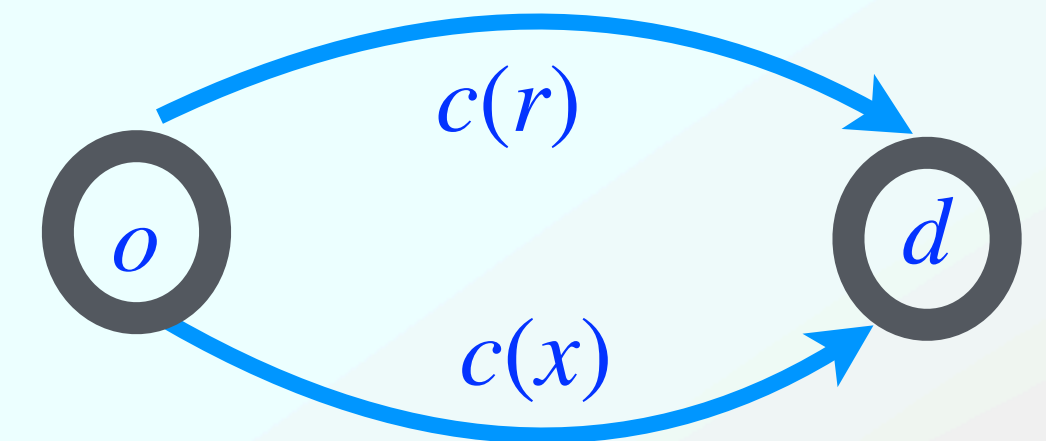


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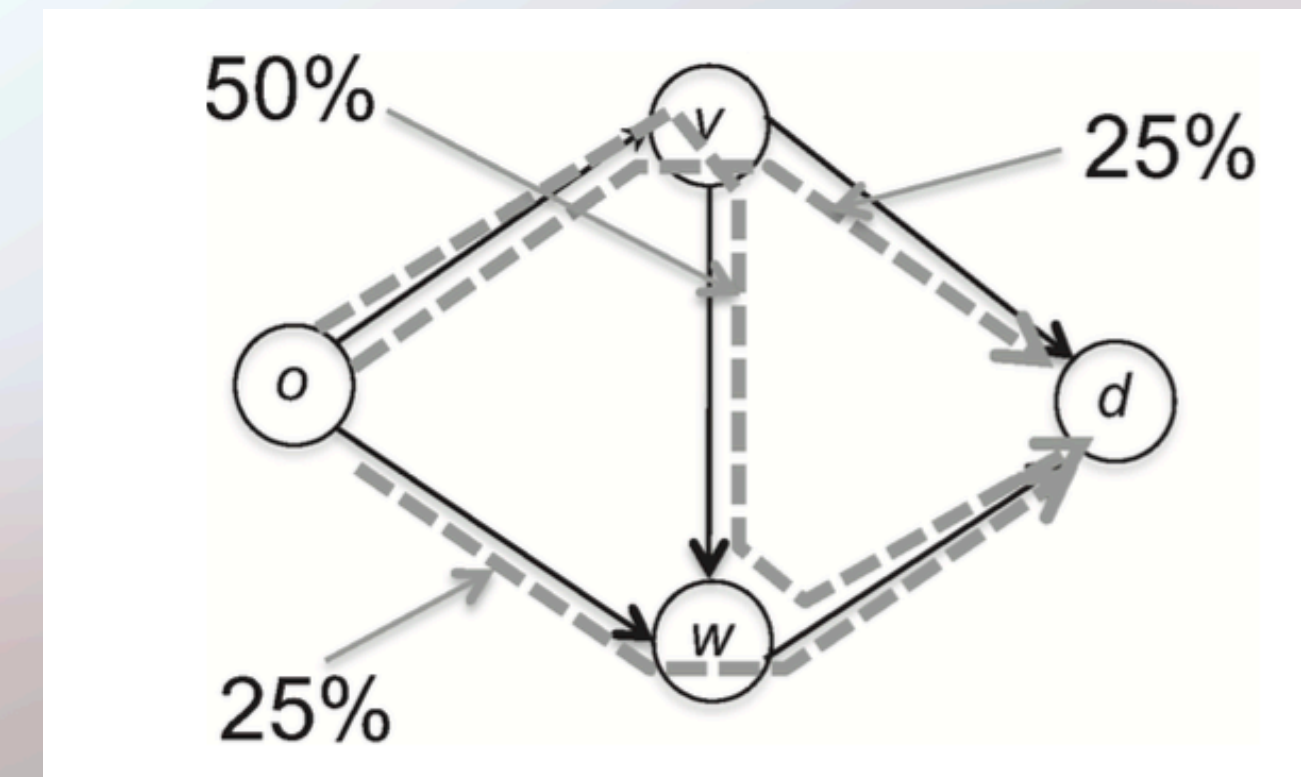


Let \mathcal{P} denote the set of non-empty $o-d$ paths of G .

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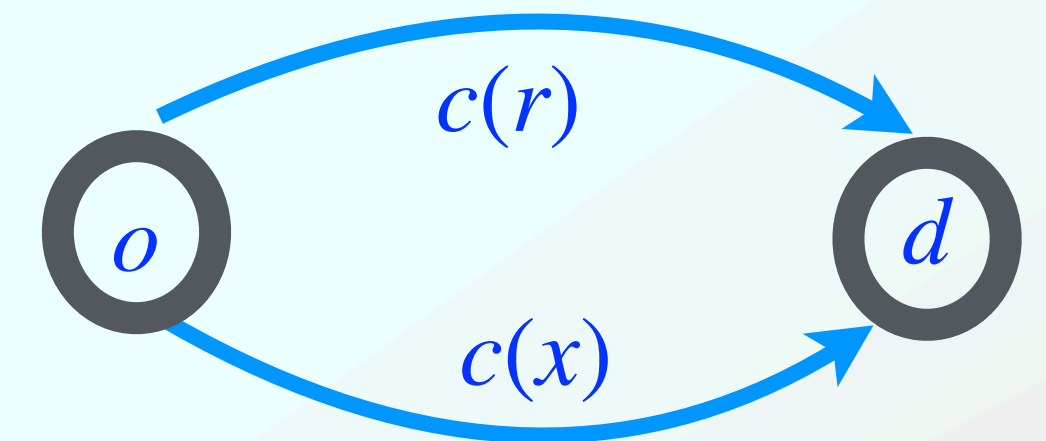
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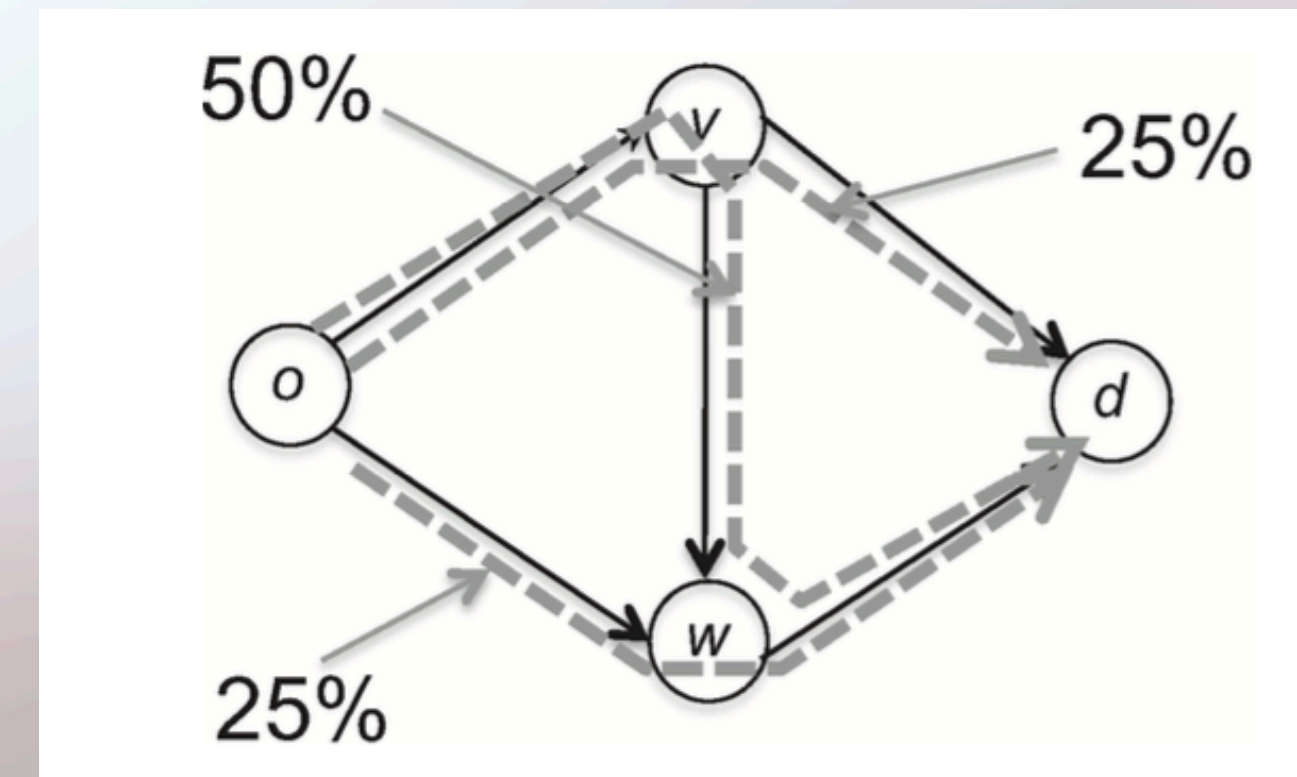


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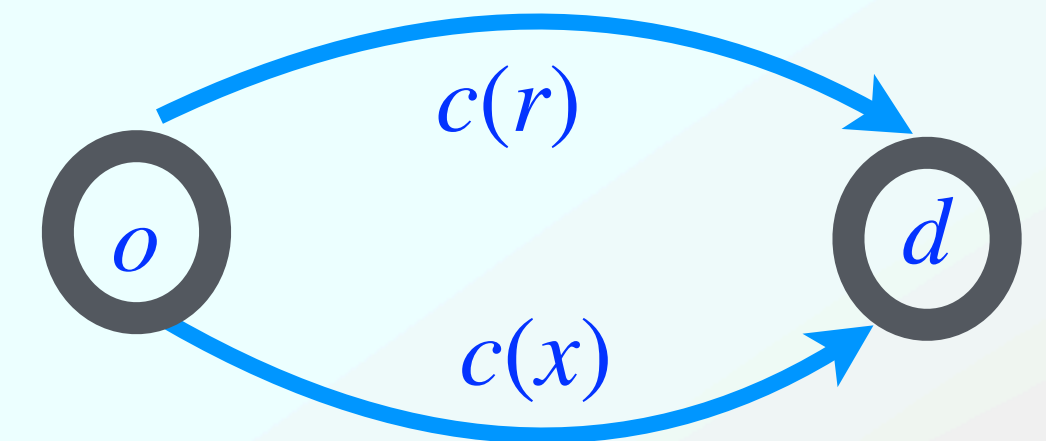
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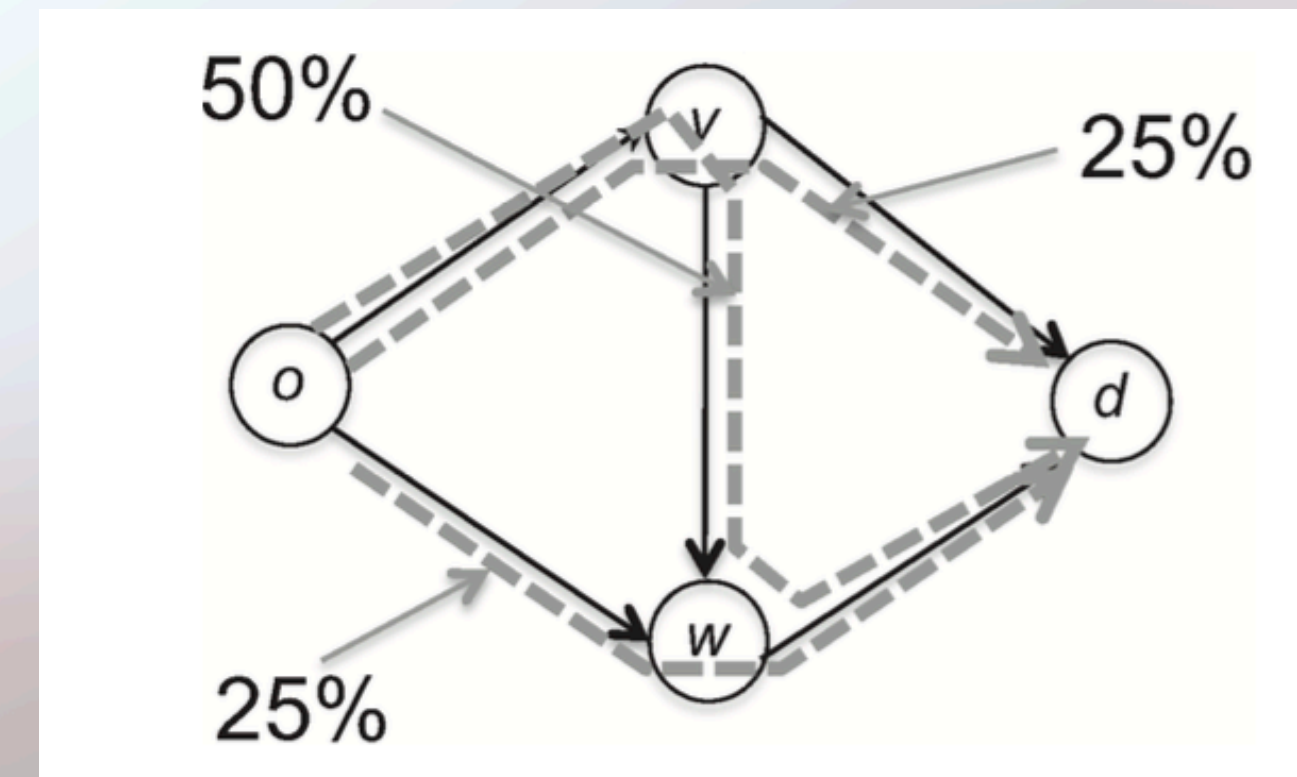
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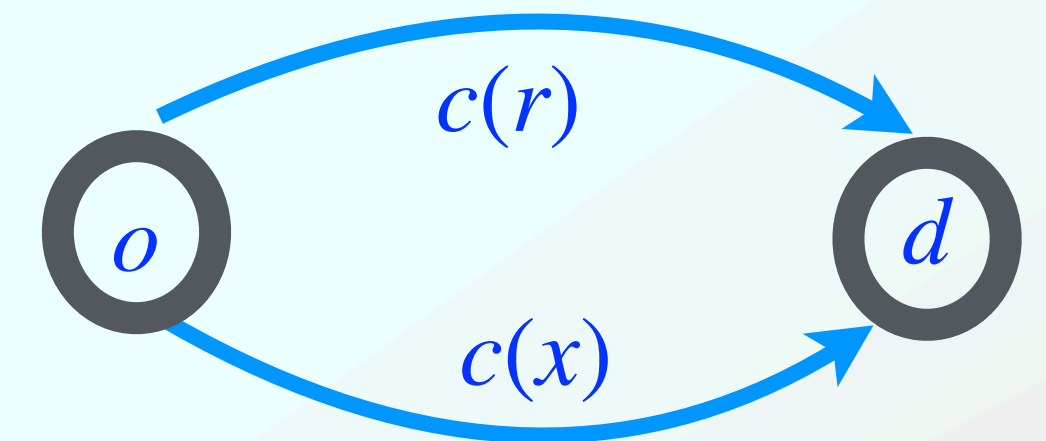


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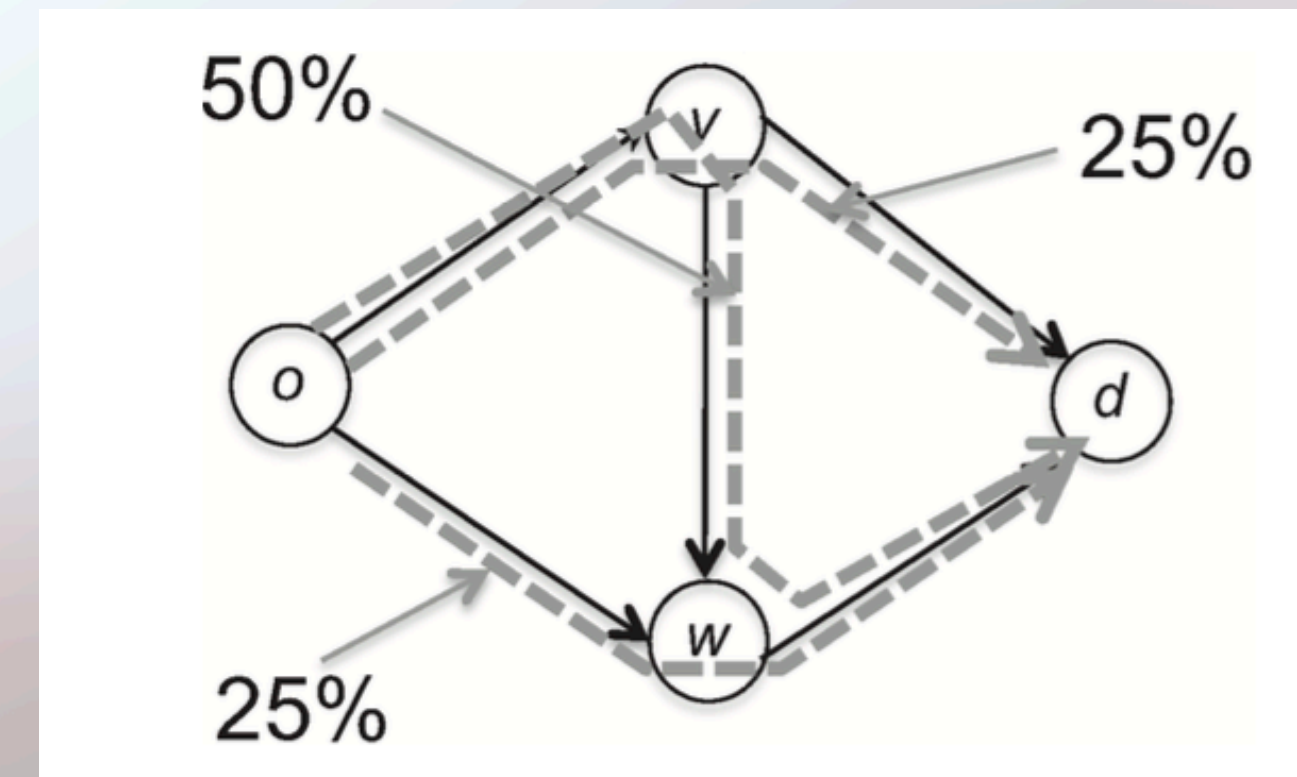
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NOT equilibrium flow! Shortest path is zig-zag & $f_{(o,w,d)} \neq 0$

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Sufficient to prove: $\alpha(\mathcal{C}) \geq \frac{C(f)}{C(f^*)} = POA$

Part 1: Freezing the cost of every edge e at equilibrium value $c_e(f_e)$ makes f optimal

Step 2: Quantify how much can f^\star be better than f ?

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Claim:
$$\sum_{e \in E} f_e^* \cdot c_e(f_e) \geq \sum_{e \in E} f_e \cdot c_e(f_e)$$

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Think about : POA across an edge $e \in E$

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