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The uses of Lie groups and Lie algebras in physics

Groups and Symmetry

Static symmetry of objects in space $\rightarrow$ transformation of variables which preserve given equations (ODE's, PDE's)

Realisations and Representations of a group

G : elements $g, g', a, b, \dots$, identity e , inverses $g^{-1}, \dots$

Realisation: set S , maps ϕ_g of S onto itself, one-to-one, onto, invertible:

$$i) \phi_{g'} \circ \phi_g = \phi_{g'g} ; ii) \phi_e = \text{Identity map};$$

$$iii) \phi_{g^{-1}} = \phi_g^{-1}$$

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Can require S to be a differentiable manifold, ϕ_g diffeomorphisms.

Representation $S \rightarrow$ linear (real or complex) linear vector space V ,

ϕ 's nonsingular linear transformations.

Dimension of V : finite or infinite; Hilbert space case it has an inner product. Write $\mathcal{H}$ for V , $U(g)$ or $D(g)$ for ϕ_g .

so in a (possibly unitary) representation:

$$g \in G \rightarrow U(g) \text{ on } \mathcal{H},$$

$$i) U(g')U(g) = U(g'g); \quad ii) U(e) = \mathbb{1}_{\mathcal{H}}; \quad iii) U(g^{-1}) = U(g)^{-1};$$

$$iv) U(g)^{\dagger} U(g) = \mathbb{1}_{\mathcal{H}} \quad (2)$$

Dynamics and Symmetry in the classical case

Properties of a physical system - real valued numerical dynamical variables. Choose an independent set of them.

Evolution of the system in time expressed by Equation of Motion (EOM)

Forms of EOM: Newtonian, Euler-Lagrange, Hamiltonian.

Configuration space Q , dimension n , differentiable manifold.

$$q \in Q \rightarrow (\text{local}) \text{ coordinates } q^d \in \mathbb{R}, \quad d=1,2,\dots,n, \text{ independent} \quad (3)$$

From Q , can construct:

Q , dim n $\rightarrow$ TQ = Tangent bundle, dim. $2n$; local coordinates and velocities; $(q, \dot{q}) \in TQ$; E-L form of EOM

$\rightarrow T^*Q$ = Cotangent bundle, dim. $2n$; position q^d and momenta p_j ; $(q, p) \in T^*Q$; Hamiltonian form of EOM

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Note at an instant of time : $(q, \dot{q}) \in TQ$, or $(q, p) \in T^*Q$.

The E-L EOM determined by $\langle (q, \dot{q}) \in TQ \rangle$, Lagrangian

$$\delta \int_{t_1}^{t_2} dt \mathcal{L}(q(t), \dot{q}(t)) = 0, \quad \delta q(t_1) = \delta q(t_2) = \delta t_1 = \delta t_2 = 0 \quad (5)$$



$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}^j} - \frac{\partial \mathcal{L}}{\partial q^j} = 0, \quad j=1, 2, \dots, n. \quad (6)$$

Properties of T^*Q is a symplectic manifold

$\theta_0 = \int_1 dq^j =$ Canonical one-form, on T^*Q

$\omega_0 = d\theta_0 = dp_j \wedge dq^j =$ Canonical, symplectic, two-form on T^*Q ,

$$d\omega_0 = 0, \quad \omega_0 \text{ nondegenerate} \quad (7)$$

$f, g, \dots \in \mathcal{F}(T^*Q) : f(q, p), g(q, p), \dots$ Poisson Bracket (PB) :

$$f, g \in \mathcal{F}(T^*Q) \rightarrow \{f, g\} \in \mathcal{F}(T^*Q),$$

$$\{f, g\}(q, p) = \frac{\partial f(q, p)}{\partial q^j} \frac{\partial g(q, p)}{\partial p_j} - \frac{\partial f(q, p)}{\partial p_j} \frac{\partial g(q, p)}{\partial q^j},$$

$$\{ \{f, g\}, h \} + \{ \{g, h\}, f \} + \{ \{h, f\}, g \} = 0. \quad (8)$$

Smooth maps $\phi: T^*Q \rightarrow T^*Q$, one-to-one, onto, invertible,

which preserve above : canonical transformations or symplectomorphisms

$$\phi \text{ is a CT} \Leftrightarrow \phi^* \omega_0 = \omega_0 \Leftrightarrow \phi^* \{f, g\} = \{\phi^* f, \phi^* g\} \quad (9)$$

From $L(q, \dot{q}) \in \mathcal{F}(TQ)$ to hamiltonian $H(q, p) \in \mathcal{F}(T^*Q)$ by Legendre transformation:

$$\text{Legendre map } TQ \rightarrow T^*Q : \quad \dot{q} = \frac{\partial L(q, \dot{q})}{\partial \dot{q}} ;$$

$$H(q, p) = \dot{q} p - L(q, \dot{q}). \quad (10)$$

Phase space EOM:

$$\dot{q} = \{q, H\} = \frac{\partial H(q, p)}{\partial p}, \quad \dot{p} = \{p, H\} = -\frac{\partial H(q, p)}{\partial q},$$

$$\frac{d}{dt} f(q, p) = \{f, H\}(q, p). \quad (11)$$

Solution of these EOM from t_1 to t_2 is a C.T., H is the generator

Point transformation symmetries Lie group G acting on Q via

diffomorphism ϕ :

$$g \in G \rightarrow \phi_g : Q \rightarrow Q : q \in Q \rightarrow q' = \phi_g(q) = \phi(g; q) \in Q. \quad (12)$$

Law for velocities:

$$\dot{q} \rightarrow \dot{q}' = \frac{\partial \phi(g; q)}{\partial q} \dot{q} \quad (13)$$

G is a group of symmetries for the system if

$$L(q', \dot{q}') = L(q, \dot{q}). \quad (14)$$

Then EOM are preserved, solutions mapped to solutions. Lemma:

i) $g \in G \rightarrow$ C.T.'s $\tilde{\phi}_g$ on T^*Q determined by ϕ_g , preserve H :

$\phi_g =$ point transformation on $Q \rightarrow \tilde{\phi}_g = CT$ on T^*Q ,

$$\tilde{\phi}_g^* \omega_0 = \omega_0, \quad \tilde{\phi}_g^* H = H. \quad (15)$$

ii) These CT's preserve the EOM (11)

iii) Elements g near e act via infinitesimal CT's:

$\{e_r\} =$ basis for G , $\alpha^r e_r \in G$, $\alpha^r \in \mathbb{R}$: $e_r \rightarrow \bar{J}_r(q, p) \in T^*Q$,

$$|\epsilon| \ll 1: \delta q^d = \epsilon \{q^d, \alpha^r \bar{J}_r\}, \quad \delta p_j = \epsilon \{p_j, \alpha^r \bar{J}_r\}. \quad (16)$$

iv) $\bar{J}_r(q, p)$ determined upto additive constants, are constants of motion (COM):

$$\frac{d\bar{J}_r}{dt} = \{\bar{J}_r, H\} = 0. \quad (17)$$

$$v) \quad \{\bar{J}_r, \bar{J}_s\} = C_{rs}^t \bar{J}_t + d_{rs},$$

$$C_{rs}^t = \text{structure constants}, \quad d_{rs} = \text{constants} \quad (18)$$

All this is 'Noether's Theorem'!

Basic fact: Lie group of symmetries acts via CT's, generators are COM.

Point Transformations: $T_r(q, p)$ linear in momenta.

Non Noether symmetries: $T_r(q, p)$ not linear in momenta.

Dynamics and Symmetry in Quantum Mechanics

Given QM system: complex Hilbert space $\mathcal{H}$, finite or infinite dimension,

vectors $\psi, \phi, \psi', \phi', \dots$, inner product (ϕ, ψ) or $\langle \phi | \psi \rangle$.

$\psi \in \mathcal{H}, \langle \psi | \psi \rangle = \|\psi\|^2 = 1: e^{i\kappa} \psi, 0 \leq \kappa \leq 2\pi \rightarrow$ Same pure state (19)

Superposition Principle:

$$\psi = c_1 \psi_1 + c_2 \psi_2 + \dots \rightarrow \text{new pure state.} \quad (20)$$

Typically, $\mathcal{H}$ carries irreducible representation of 'primitive' set of

operators obeying given commutation or other algebraic relations.

Dynamical variables are hermitian operators $\hat{A}, \hat{B}, \dots$ on $\mathcal{H}$.

The EOM of QM:

$$i\hbar \frac{d}{dt} \psi(t) = \hat{H}(t) \psi(t), \quad \hat{H} = \text{hamiltonian operator} \quad (21)$$

A Lie group G represented unitarily on $\mathcal{H}$ is a symmetry group if $\hat{H}$ is invariant:

$$G \text{ is a Lie group of symmetries} \Leftrightarrow \hat{H} U(g) = U(g) \hat{H}, \quad g \in G. \quad (22)$$

Results: i) $\psi(t)$ obeys (21), $\psi'(t) = U(g) \psi(t) \Rightarrow \psi'(t)$ obeys (21). (23)

ii) g near $e \in G$. $U(g) \approx 1 - i \alpha^a \hat{J}_a + \dots$,

$$\hat{J}_a^\dagger = \hat{J}_a, \quad [\hat{J}_a, \hat{J}_b] = i C_{ab}^c \hat{J}_c,$$

$$[\hat{J}_a, \hat{H}] = 0. \quad (24)$$

Wigner's theorem in QM

$$\psi, \phi \in \mathcal{H}, \quad \|\psi\| = \|\phi\| = 1$$

transition probability $(\psi \rightarrow \phi) = |\langle \phi, \psi \rangle|^2$. (25)

$$\hat{P}(\psi) = \psi \psi^\dagger \propto |\psi\rangle\langle\psi|, \quad \hat{P}(\phi) = \phi \phi^\dagger \propto |\phi\rangle\langle\phi|: \text{one dim. projection.}$$

$$P_{\text{Wb.}}(\psi \rightarrow \phi) = \text{Tr}(\hat{P}(\phi) \hat{P}(\psi)) \quad (26)$$

Wigner symmetry is an onto, onto, invertible map Ω :

$$\Omega(\hat{P}(\psi)) = \hat{P}(\psi'), \quad \Omega(\hat{P}(\phi)) = \hat{P}(\phi'), \quad \rightarrow; \psi', \phi': \text{determined up to phases.}$$

$$|\langle \phi', \psi' \rangle|^2 = \text{Tr}(\hat{P}(\phi') \hat{P}(\psi')) = \text{Tr}(\hat{P}(\phi) \hat{P}(\psi)) = |\langle \phi, \psi \rangle|^2. \quad (27)$$

Theorem Ω is a symmetry operation $\Rightarrow \Omega(\hat{p}(\psi)) = \hat{p}(U\psi)$,

U = map $\mathcal{H} \rightarrow \mathcal{H}$, either linear unitary or antilinear antiunitary (28)

Limit to unitary case. For the group of symmetries, generating elements:

$$g \in G \rightarrow U(g) \text{ on } \mathcal{H}, \quad U(g)^\dagger U(g) = \mathbb{1},$$

$$U(g')U(g) = e^{i\omega(g',g)} U(g'g), \quad \omega(g',g) = \text{real phase.} \quad (29)$$

If $\omega \neq 0$: unitary ray representation of G ; if $\omega = 0$: true or vector representation. In general: generators obey

$$[\hat{J}_r, \hat{J}_s] = i \epsilon_{rst} \hat{J}_t + i d_{rst} \quad (30)$$

Symmetry groups related to space time

a) Three dimensional proper orthogonal rotation $SO(3)$: isotropy of space:

$$SO(3) = \{ A = 3 \times 3 \text{ real matrix} \mid A^T A = \mathbb{1}, \det A = 1 \} \quad (31)$$

Compact, order 3, rank 1. In any unitary representation (UR):

$$[\hat{J}_r, \hat{J}_s] = i \epsilon_{rst} \hat{J}_t, \quad r, s, t = 1, 2, 3. \quad (32)$$

In QM, need to also use

$$SU(2) = \{ u = 2 \times 2 \text{ complex matrix} \mid u^\dagger u = \mathbb{1}, \det u = 1 \} \quad (33)$$

Rotational invariance in QM was UR's and UIR's of $SO(3)$.

b) Euclidean group in three dimensions, $E(3)$ homogeneity and isotropy of space: order 6, semidirect product.

$$E(3) = \{g = (A, \underline{a}) \mid A \in SO(3), \underline{a} \in \mathbb{R}^3\}; \quad (c)$$

$$g \in E(3): \underline{x} \in \mathbb{R}^3 \rightarrow \underline{x}' = g \underline{x} = A \underline{x} + \underline{a} \in \mathbb{R}^3; \quad (d)$$

$$g'g = (A', \underline{a}')(A, \underline{a}) = (A'A, \underline{a}' + A'\underline{a}). \quad (e) \quad (34)$$

Generators $\hat{\underline{J}}$ and $\hat{\underline{P}}$:

$$[\hat{J}_i, \hat{J}_j] = i \epsilon_{ijk} \hat{J}_k, \quad [\hat{J}_i, \hat{P}_j] = i \epsilon_{ijk} \hat{P}_k, \quad [\hat{P}_i, \hat{P}_j] = 0. \quad (35)$$

c) Galilei group $\mathcal{G}$ Ten parameter group, intricate structure.

$$A \in SO(3), \underline{a} \in \mathbb{R}^3, b \in \mathbb{R}, \underline{v} \in \mathbb{R}^3: g = (A, \underline{v}, b, \underline{a}):$$

$$(x, t) \rightarrow (x', t') = g(x, t) = (Ax + \underline{a} + \underline{v}t, t + b);$$

$$\mathcal{G} = \{g = (A, \underline{v}, b, \underline{a}) \mid A \in SO(3), \underline{v} \in \mathbb{R}^3, b \in \mathbb{R}, \underline{a} \in \mathbb{R}^3\};$$

$$g'g = (A', \underline{v}', b', \underline{a}')(A, \underline{v}, b, \underline{a}) = (A'A, \underline{v}' + A'\underline{v}, b' + b, \underline{a}' + A'\underline{a} + b\underline{v}'). \quad (36)$$

d) Poincaré group $\mathcal{P}$ basic to special relativity. Space time is $\mathbb{R}^4$ plus pseudo-Euclidean, i.e. Minkowski, metric.

$$x = (x^\mu) = (x^0 = ct, x^1, x^2, x^3), \quad \mu = 0, 1, 2, 3.$$

$$x \cdot x = \eta_{\mu\nu} x^\mu x^\nu = (x^0)^2 - (x^1)^2 - (x^2)^2 - (x^3)^2,$$

$$\eta_{\mu\nu} = \text{diag } (+1, -1, -1, -1). \quad (37)$$

$\mathcal{P}$ = semi direct product of space time translations and homogeneous Lorentz transformations $SO(3,1)$:

$$SO(3,1) = \{ \Lambda = (\Lambda^\mu{}_\nu) = 4 \times 4 \text{ real matrix} \mid \Lambda^T \eta \Lambda = \eta, \Lambda^0{}_0 \geq 1, \det \Lambda = 1 \};$$

$$\text{Translations} = \{ a^\mu \in \mathbb{R}^4 \};$$

$$(\Lambda, a^\mu) \in \mathcal{P}: \quad x^\mu \rightarrow x'^\mu = \Lambda^\mu{}_\nu x^\nu + a^\mu;$$

$$(\Lambda', a'^\mu) (\Lambda, a^\mu) = (\Lambda' \Lambda, a'^\mu + \Lambda'^\mu{}_\nu a^\nu). \quad (38)$$

Wigner's classic paper on UCR's of $\mathcal{P}$: 1939

The groups $Sp(2n, \mathbb{R})$ basic Cartesian variables, operators:

$$Q = \mathbb{R}^n, \quad T^*Q = T^*\mathbb{R}^n \cong \mathbb{R}^{2n}, \quad \mathcal{H} = L^2(\mathbb{R}^n) \text{ Heisenberg CCR's:}$$

$$\hat{q}_j^\dagger = \hat{q}_j, \quad \hat{p}_j^\dagger = \hat{p}_j; \quad [\hat{q}_j, \hat{p}_k] = i\delta_{jk}, \quad [\hat{q}_j, \hat{q}_k] = [\hat{p}_j, \hat{p}_k] = 0, \quad j, k = 1, 2, \dots, n. \quad (39)$$

Concise form:

$$\hat{\xi} = (\hat{\xi}_a), \quad a = 1, 2, \dots, 2n: \quad \hat{\xi}_j^\dagger = \hat{q}_j, \quad \hat{\xi}_{n+j}^\dagger = \hat{p}_j. \quad (40)$$

