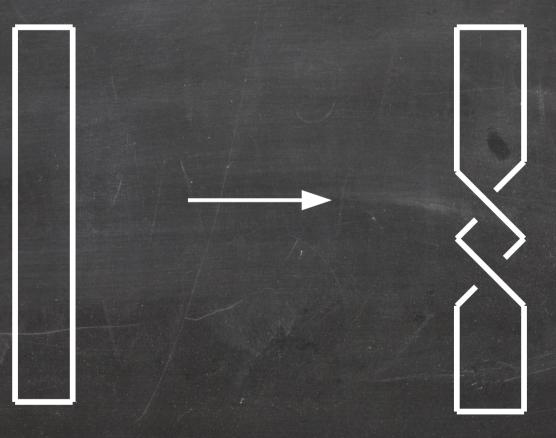
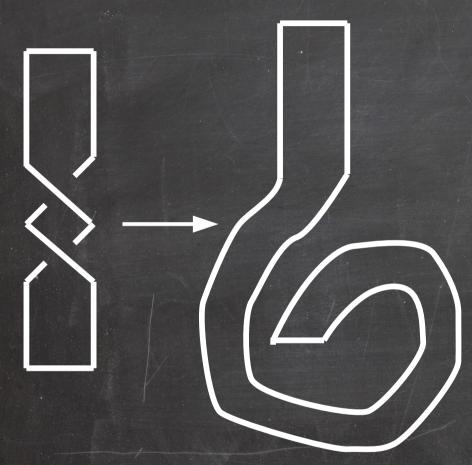
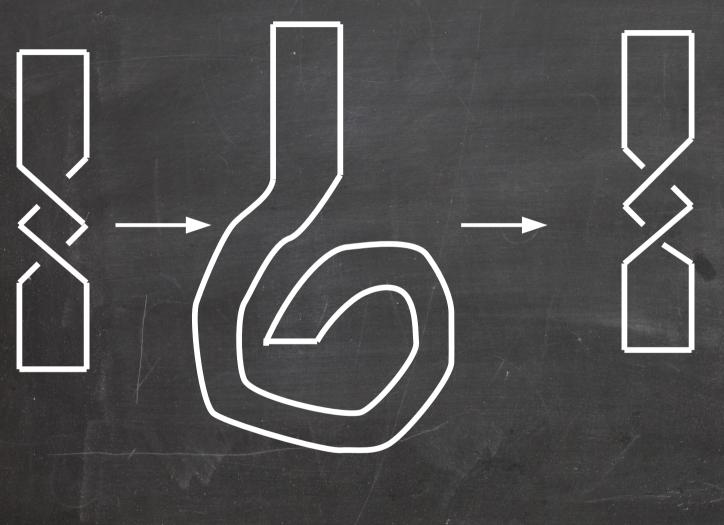
The Belt Trick

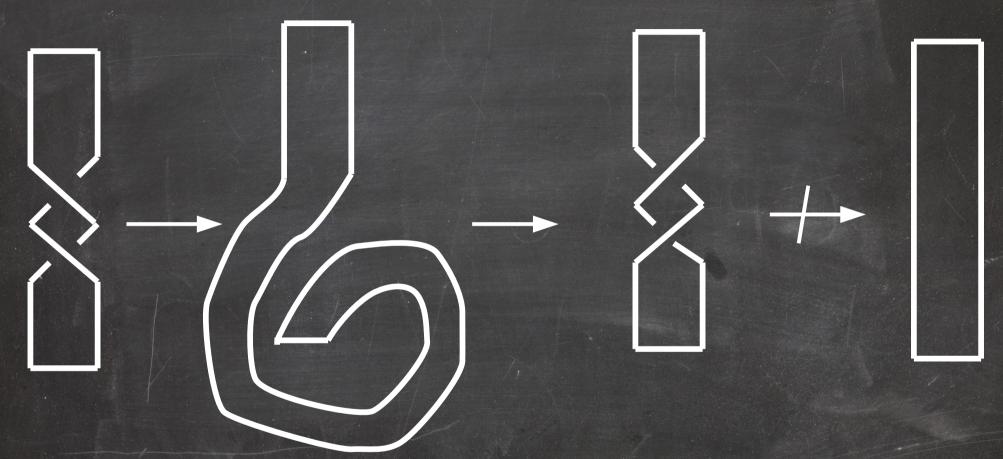
Suppose that we keep top end of a belt fixed and rotate the bottom end in a circle around it.

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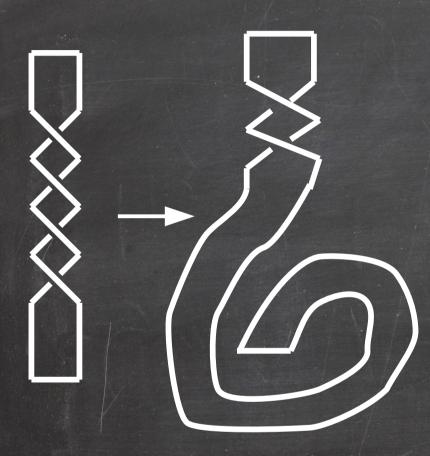


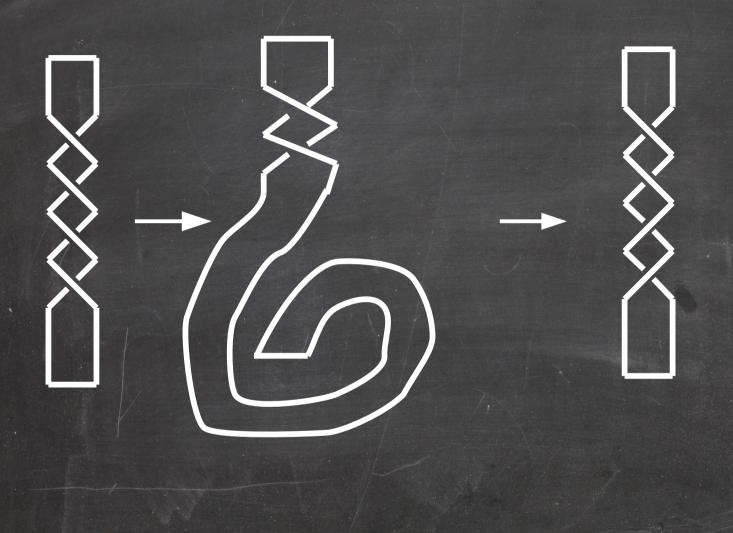


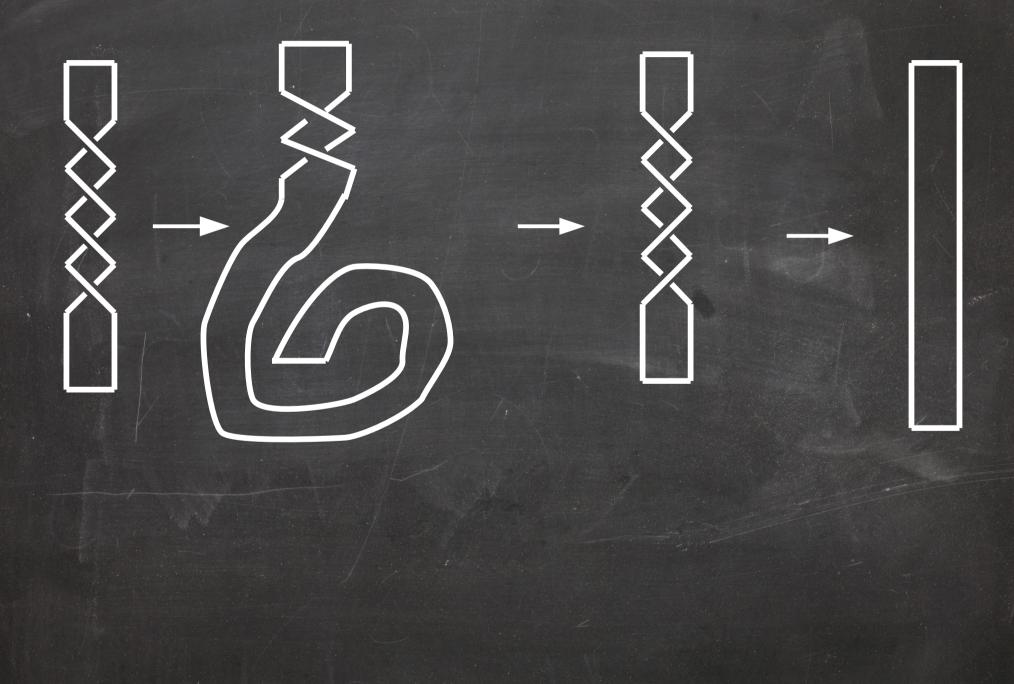


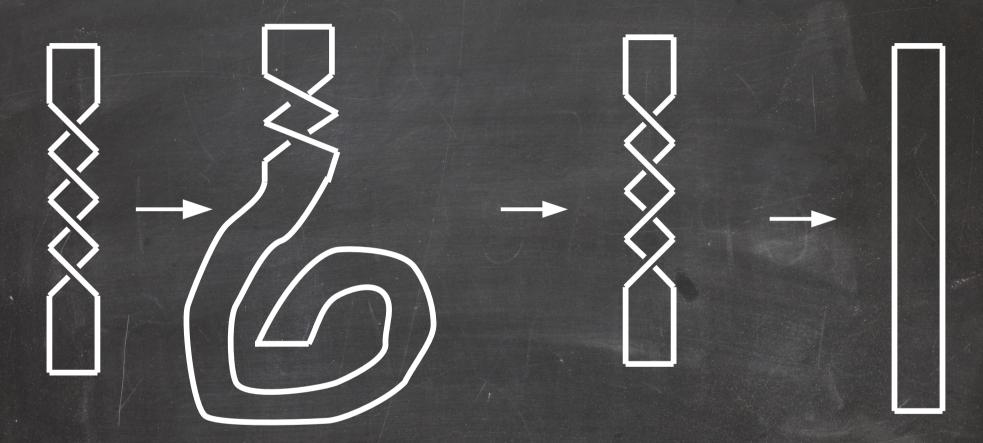
Observe that the twisted belt cannot be untwisted by these transformations



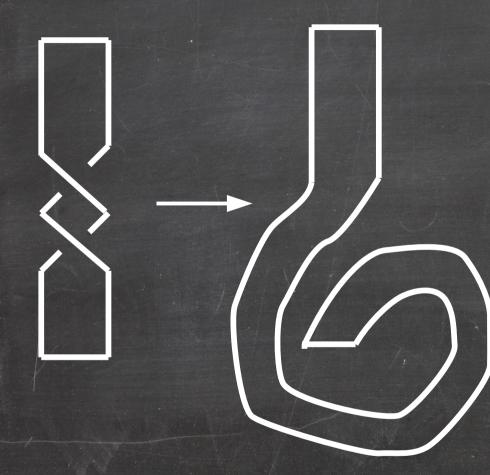








Hence the twice rotated belt can be transformed to the untwisted belt while the once rotated belt cannot. This is called THE BELT TRICK In order to understand the Belt trick one needs to consider the transformations.

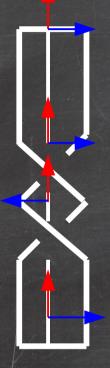


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One needs to construct an appropriate invariant.



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Belt configurations

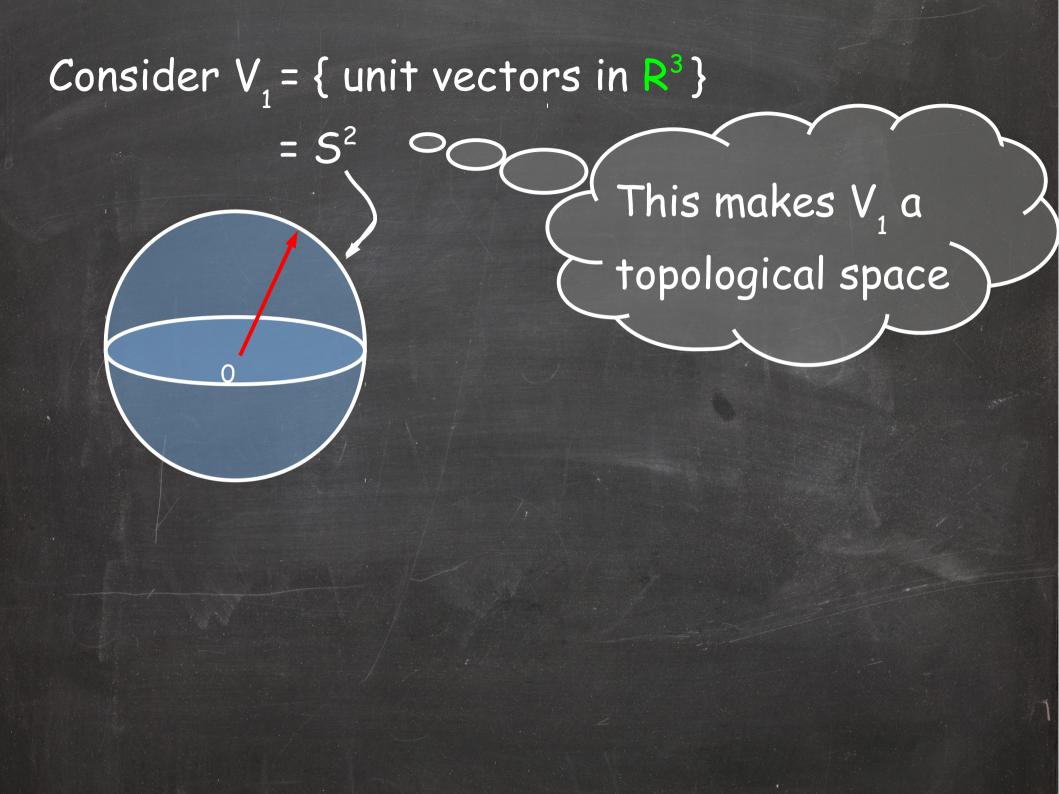
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Belt configurations Maps from I to pairs of perpendicular vectors in R³ with same value at 0 and 1.

Consider $V_1 = \{$ unit vectors in $\mathbb{R}^3 \}$ = S^2 (the sphere)

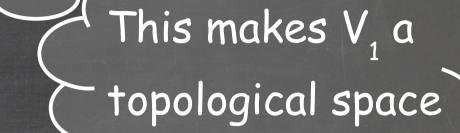
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 $= S^{2}$



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Define :

 $V_2 = \{ \text{ pairs of perpendicular unit vectors in } \mathbb{R}^3 \}$ = $\{ (u,v) \in \mathbb{R}^3 \times \mathbb{R}^3 \mid |u|=1, |v|=1, u.v = 0 \}$

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This gets a topology as a subset of $\mathbb{R}^3 \times \mathbb{R}^3$

Therefore, $V_2 \approx \{ \text{ oriented three frames } \}$

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For each oriented three frame, form the matrix with the corresponding vectors as columns. This is an orthogonal matrix of determinant 1. The set of these matrices is called SO(3).

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Any orthogonal 3x3 matrix of determinant 1 fixes a vector v (one can check that 1 is an eigenvalue).

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Therefore, SO(3) $\approx B_{\pi} / (v = -v) \approx RP^3$ (3 - dim real projective space) A belt configuration yields a map $\gamma : I \rightarrow V_2$ such that $\gamma(0) = \gamma(1)$. This is a loop in V_2 .

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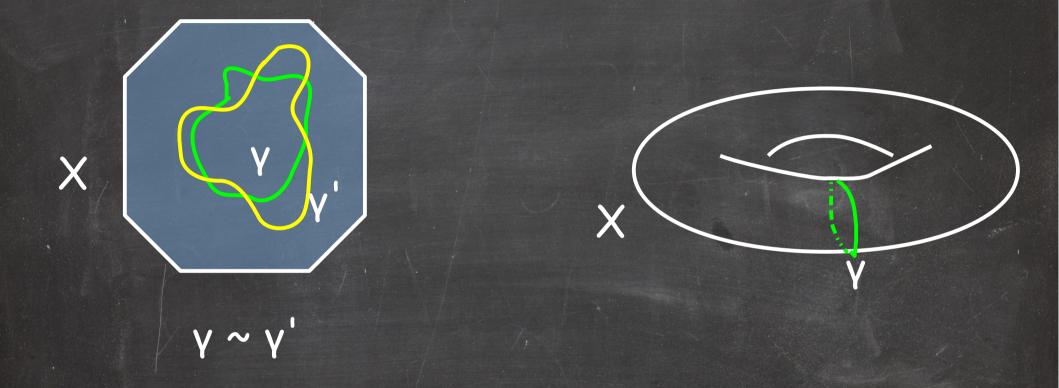
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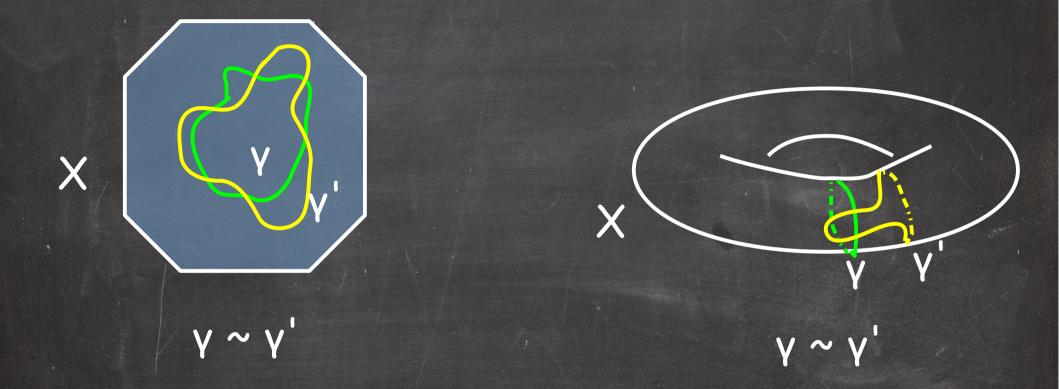
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$\pi_1(X, x) = \{ \text{ loops starting and ending at } x \}$ $(\gamma(0) = \gamma(1) = x)$

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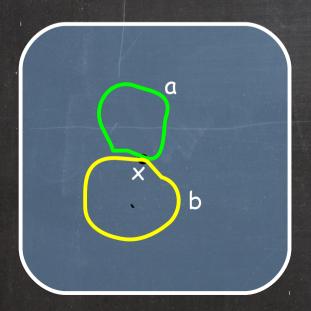
(Homotopy fixing x)

Elements of $\pi_1(X,x)$ can be multiplied :

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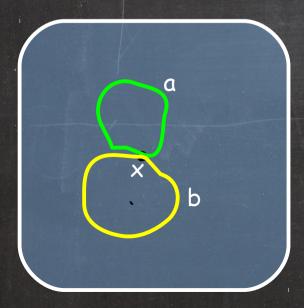
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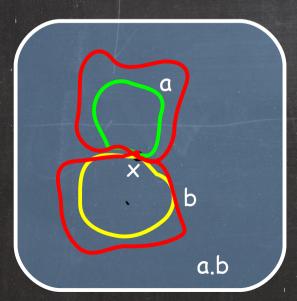
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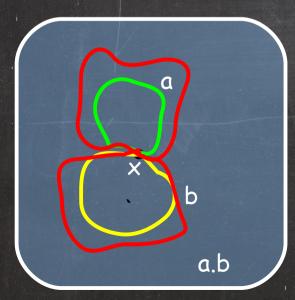
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Elements of $\pi_1(X,x)$ can be multiplied :



a.b = the loop a followed by b With this multiplication $\pi_1(X,x)$ becomes a group.

a

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In fact, two loops are homotopic if and only if they wind around the circle the same number of times in the same direction. This demonstrates : $\pi_1(S^1,x) = \mathbb{Z}$ (the group of integers)

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A deformation of belt configurations leads to a homotopy of the corresponding loops. Therefore we get an invariant :

{ Belt configurations } $\longrightarrow \pi_1(\mathbb{RP}^3, X)$

(x is some point of RP^3)

Recall $RP^3 \approx B_r / (v = -v)$ for some radius r.

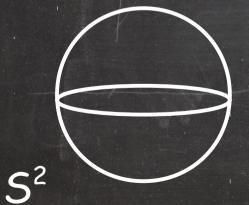
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B

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52

B

Similarly any loop can be made to miss a point and such a loop can be homotoped to the equator. The image of the equator in RP^3 is of the form $S^1/(x=-x)$. The corresponding loop a in RP^3 is the boundary of a disc (image of the sphere). This shows that a is homotopic to constant.

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The image of the half circle in RP^3 is a loop β as the end points map to the same point. This cannot be homotoped to a constant. Also note $a = \beta . \beta$.

Therefore,

 $\pi_1(\mathbb{RP}^3, \mathbf{x}) \approx \mathbb{Z}_2$

(the group of integers modulo 2)

We have constructed an invariant :

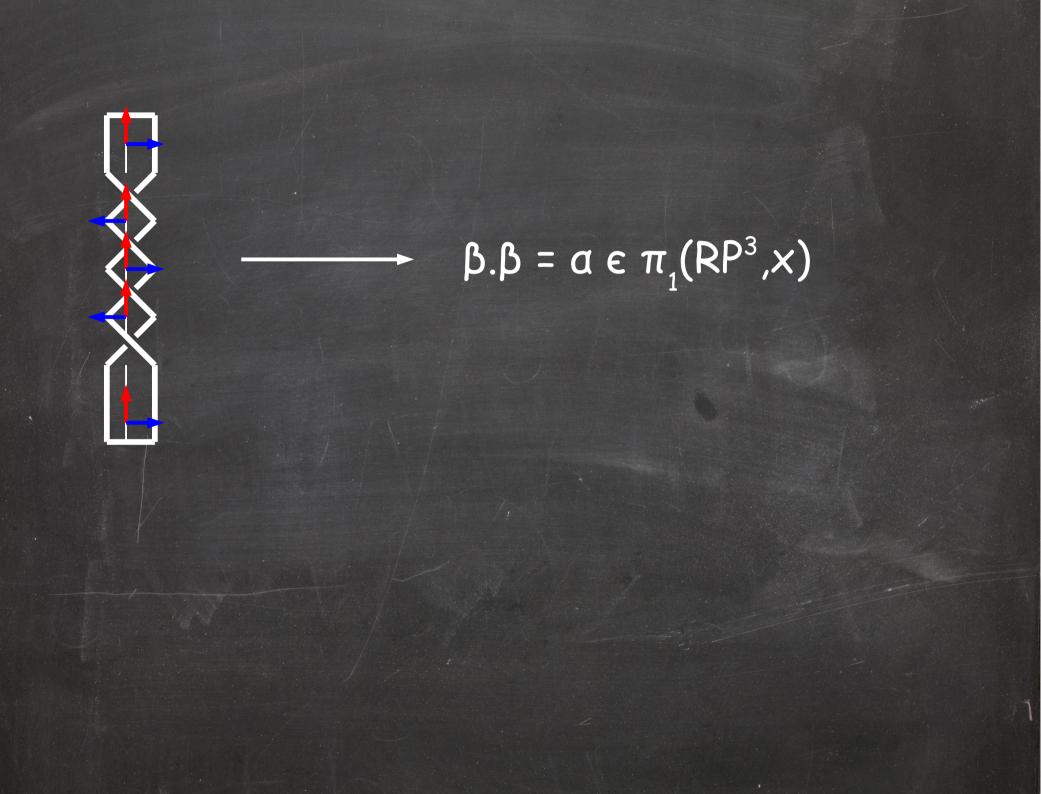
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$\beta.\beta = \alpha \in \pi_1(\mathbb{RP}^3, x)$

This is homotopically trivial.