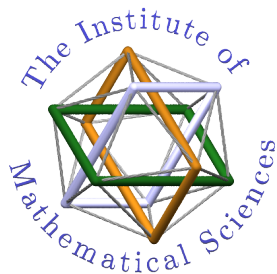


On Using Torsion Points in the Elliptic Curve Index Calculus

Guénaél Renault
Sorbonne Universités UPMC, INRIA, CNRS LIP6



General Context

Discrete Logarithm Problem (DLP)

Given a finite cyclic group $(\mathbb{G} = \langle g \rangle, +)$ and $h \in \mathbb{G}$, find k such that

$$h = [k]g = \underbrace{g + \cdots + g}_{k \text{ times}}$$

- **Generic algorithms** $O(\sqrt{\#\mathbb{G}})$
 - ▶ Baby Step Giant Step, Pollard's rho, etc.
 - ▶ For any **black box group** \mathbb{G} , optimal complexity (Shoup)
- **Index Calculus** can be quasi-polynomial, sub-exponential
 - ▶ sieving + linear algebra
 - ▶ $\mathbb{G} = (\mathbb{F}_{2^k}^\times, \times)$
 - ▶ $\mathbb{G} = (\mathbb{F}_q^\times, \times)$, $\mathbb{G} = (J_C(\mathbb{F}_q), +)$ with genus $g > 2$

☞ $\mathbb{G} = E(\mathbb{F}_q)$ **no sub-exponential** index calculus algo. in general

Context

☞ Index calculus algo. adaptation for $E(\mathbb{F}_{q^n})$ (n small)

- Semaev/Gaudry/Diem (≈ 2005) (Point Decomposition Problem)
- Semaev Summation Polynomial
- Polynomial System Solving

☞ Increasing the efficiency by using the symmetries

☞ Using Symmetries in the Index Calculus for ECDLP (J. Crypto. 2014)
(J.-C. Faugère, P. Gaudry, L. Huot, G. R.)

☞ Symmetrized Summation Polynomials (Eurocrypt'14)
(J.-C. Faugère, L. Huot, A. Joux, G. R., V. Vitse)

Outline

- 1 PDP in the Index Calculus
- 2 Polynomial System Solving
- 3 PoSSo With Symmetries
- 4 From Torsion Point to Symmetry
- 5 Characteristic 2
- 6 New Computational Record: 8th Summation Polynomial
- 7 Conclusion

Outline

- 1 PDP in the Index Calculus
- 2 Polynomial System Solving
- 3 PoSSo With Symmetries
- 4 From Torsion Point to Symmetry
- 5 Characteristic 2
- 6 New Computational Record: 8th Summation Polynomial
- 7 Conclusion

Index Calculus for ECDLP

Algorithm (Gaudry 2005)

Input: $P, Q \in E(\mathbb{F}_{q^n})$

Output: x such that $Q = [x]P$

1. Def. factor base: $\mathcal{F} = \{(x, y) \in E(\mathbb{F}_{q^n}) \mid x \in \mathbb{F}_q\}$
2. Sieving: $[a_j]P \oplus [b_j]Q = P_1 \oplus \dots \oplus P_n$, $P_i \in \mathcal{F}$ until having $\#\mathcal{F} + 1$ such relations
3. Linear algebra $\sum_j [\lambda_j \cdot a_j]P \oplus [\lambda_j \cdot b_j]Q = 0_{E(\mathbb{F}_{q^n})}$

Point Decomposition Problem

Given

- $R \in E$
- \mathcal{F} a factor base of points in E

find $P_1, \dots, P_n \in \mathcal{F}$ such that $R = P_1 \oplus \dots \oplus P_n$

Point Decomposition Problem

$PDP(n, R, \mathcal{F})$

Given

- $R \in E$
- \mathcal{F} a factor base of points in E

find $P_1, \dots, P_n \in \mathcal{F}$ such that $R = P_1 \oplus \dots \oplus P_n$

☞ Modeling the problem as a polynomial system $\{g_1, \dots, g_s\}$ and solve this system:

$$\begin{cases} (x_i, y_i) \in E \\ (x_1, y_1) \oplus (x_2, y_2) \oplus \dots \oplus (x_n, y_n) = (R_x, R_y) \end{cases}$$

☞ The solution has to be found in \mathcal{F}

Algebraic modelling of PDP: Summation polynomials

Semaev, 2004, Gaudry, 2005

☞ Projection of the PDP($n, R = 0, \mathcal{F} = \{(x, y) \in E(\mathbb{F}_{q^n}) \mid x \in \mathbb{F}_q\}$)

$$\begin{array}{c} \text{PDP: } \mathbf{g}_1(\text{---}, \dots, \text{---}) = \dots = \mathbf{g}_s(\text{---}, \dots, \text{---}) = 0 \\ \downarrow \text{Projection } \pi^n \\ \text{Summation: } \mathbf{f}_n(\text{---}, \dots, \text{---}) = 0 \end{array}$$

Algebraic modelling of PDP: Summation polynomials

Semaev, 2004, Gaudry, 2005

☞ Projection of the PDP($n, R = 0, \mathcal{F} = \{(x, y) \in E(\mathbb{F}_{q^n}) \mid x \in \mathbb{F}_q\}$)

PDP: $\langle \mathbf{g}_1(x_1, \dots, x_m, y_1, \dots, y_m), \dots, \mathbf{g}_s(x_1, \dots, x_m, y_1, \dots, y_m) \rangle$

$\pi : (x, y) \rightarrow x$ \downarrow Elimination (Resultant, Gröbner basis)

Summation: $\langle \mathbf{f}_n(x_1, \dots, x_n) \rangle = \langle \mathbf{g}_1, \dots, \mathbf{g}_s \rangle \cap \mathbb{F}_{q^n}[x_1, \dots, x_n]$
 $\deg_{x_i}(\mathbf{f}_n) \leq 2^{n-2}$

Characterization

$$\mathbf{f}_n(x_1, \dots, x_n) = 0$$

\Downarrow

$\exists (y_1, \dots, y_n) \in \overline{\mathbb{F}}_{q^n}^n$ s.t. $\forall i, P_i = (x_i, y_i) \in E$ and $P_1 \oplus \dots \oplus P_n = 0$

Algebraic modelling of PDP: Summation polynomials

Semaev, 2004, Gaudry, 2005

☞ Projection of the $\text{PDP}(n, R = 0, \mathcal{F} = \{(x, y) \in E(\mathbb{F}_{q^n}) \mid x \in \mathbb{F}_q\})$

PDP: $\langle \mathbf{g}_1(x_1, \dots, x_m, y_1, \dots, y_m), \dots, \mathbf{g}_s(x_1, \dots, x_m, y_1, \dots, y_m) \rangle$

$\pi : (x, y) \rightarrow x$ ↓ Elimination (Resultant, Gröbner basis)

Summation: $\langle \mathbf{f}_n(x_1, \dots, x_n) \rangle = \langle \mathbf{g}_1, \dots, \mathbf{g}_s \rangle \cap \mathbb{F}_{q^n}[x_1, \dots, x_n]$
 $\deg_{x_i}(\mathbf{f}_n) \leq 2^{n-2}$

Application in Index Calculus: (Gaudry 2005)

Solving $\text{PDP}(R, \mathcal{F})$ with factor base $\mathcal{F} = \{(x, y) \in E(\mathbb{F}_{q^n}) \mid x \in \mathbb{F}_q\}$.

⇕

Finding (x_1, \dots, x_n) with $x_i \in \mathbb{F}_q$ s.t. $\mathbf{f}_{n+1}(x_1, \dots, x_n, (-R)_x) = 0$

☞ In Weierstrass model $R_x = (-R)_x$

From summation polynomials to PoSSo

Problem

We want to find $P_1, \dots, P_n \in \mathcal{F} = \{(x, y) \in E \mid x \in \mathbb{F}_q\}$ such that

$$R = P_1 + \dots + P_n \iff P_1 + \dots + P_n - R = 0_E$$



Finding (x_1, \dots, x_n) with $x_i \in \mathbb{F}_q$ s.t. $f_{n+1}(x_1, \dots, x_n, R_x) = 0$

Solving process: Restriction of scalar on sum. polynomial

$\mathbb{F}_{q^n} \simeq \mathbb{F}_q(\omega) : n$ dimensional \mathbb{F}_q -vector space

$$f_{n+1}(x_1, \dots, x_n, R_x) = 0_E = \sum_{i=0}^{n-1} \varphi_i(x_1, \dots, x_n) \cdot \omega^i$$

From summation polynomials to PoSSo

Solving process: Restriction of scalar on sum. polynomial

$\mathbb{F}_{q^n} \simeq \mathbb{F}_q(\omega)$: n dimensional \mathbb{F}_q -vector space

$$f_{n+1}(x_1, \dots, x_n, R_x) = 0_E = \sum_{i=0}^{n-1} \varphi_i(x_1, \dots, x_n) \cdot \omega^i$$

$$\Rightarrow \left\{ \begin{array}{l} - \mathcal{S} = \{\varphi_0, \dots, \varphi_{n-1}\} \subset \mathbb{F}_q[x_1, \dots, x_n] \\ - n \text{ variables, } n \text{ equations} \\ - \text{solutions in } \mathbb{F}_q \end{array} \right.$$

\mathcal{H}_1 : The polynomial systems \mathcal{S} are zero-dimensional

Outline

- 1 PDP in the Index Calculus
- 2 Polynomial System Solving**
- 3 PoSSo With Symmetries
- 4 From Torsion Point to Symmetry
- 5 Characteristic 2
- 6 New Computational Record: 8th Summation Polynomial
- 7 Conclusion

Solving 0-dim polynomial systems

Let $\mathcal{S} = \{f_1, \dots, f_n\}$ where $f_i \in \mathbb{K}[x_1, \dots, x_n]$ and $\text{Deg}(f_i) \leq 2^{n-1}$

Solving \mathcal{S} means here to compute $\mathcal{V}_{\mathbb{K}}(\langle \mathcal{S} \rangle)$

Solving 0-dim polynomial systems

Let $\mathcal{S} = \{f_1, \dots, f_n\}$ where $f_i \in \mathbb{K}[x_1, \dots, x_n]$ and $\text{Deg}(f_i) \leq 2^{n-1}$

Solving \mathcal{S} means here to compute $\mathcal{V}_{\mathbb{K}}(\langle \mathcal{S} \rangle)$

Gröbner basis

Since $|\mathcal{V}_{\mathbb{K}}| < \infty$, the Gröbner basis \mathcal{G} of $\langle \mathcal{S} \rangle$ w.r.t. **lexicographical order** with $x_1 > \dots > x_n$ then \mathcal{G} has a **triangular form**

$$\begin{cases} h_{1,1}(x_1, \dots, x_n), \dots, h_{1,k_1}(x_1, \dots, x_n) \\ \vdots \\ h_{n-1,1}(x_{n-1}, x_n), \dots, h_{n-1,k_{n-1}}(x_{n-1}, x_n) \\ h_n(x_n) \end{cases}$$

☞ Factoring univariate polynomials over a finite field.

Solving 0-dim polynomial systems

Let $\mathcal{S} = \{f_1, \dots, f_n\}$ where $f_i \in \mathbb{K}[x_1, \dots, x_n]$ and $\text{Deg}(f_i) \leq 2^{n-1}$

Solving \mathcal{S} means here to compute $\mathcal{V}_{\mathbb{K}}(\langle \mathcal{S} \rangle)$

☞ Compute a GB of $\langle \mathcal{S} \rangle$ w.r.t. a **lexicographical order**.

Zero-dim solve

1. Compute GB DRL from \mathcal{S} (F_4/F_5)
2. Compute GB LEX from GB DRL (FGLM)

Solving 0-dim polynomial systems

Let $\mathcal{S} = \{f_1, \dots, f_n\}$ where $f_i \in \mathbb{K}[x_1, \dots, x_n]$ and $\text{Deg}(f_i) \leq 2^{n-1}$

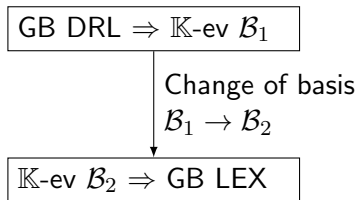
Compute GB DRL from \mathcal{S}

☞ Linear alg. on Macaulay mat.

$$\begin{array}{c} m_1 > m_2 > \dots \\ \vdots \\ t_{i,j} f_i \left(\begin{array}{ccc} c_{i,j}^1 & c_{i,j}^2 & \dots \end{array} \right) \end{array}$$

Compute GB LEX from GB DRL

☞ See $\mathbb{K}[x_1, \dots, x_n]/\langle \mathcal{S} \rangle$ as a \mathbb{K} -ev



Faugère F_4, F_5

Faugère, Gaudry, Huot, R. ISSAC'14

$$\rightsquigarrow O(ne^{n\omega} 2^{(n-1)n\omega} + n \cdot \text{deg}(\langle \mathcal{S} \rangle)^\omega)$$

☞ $\text{deg}(\langle \mathcal{S} \rangle)$ = the number of solutions (with multiplicities)

☞ ω represents the linear algebra constant

On the complexity of computing GB DRL

- ☞ These results are usually obtain for homogeneous polynomial systems
- ☞ In order to avoid **fall of degree** issues, need to consider **regular** situation

Regular sequences

A sequence of homogeneous polynomials $(f_1, \dots, f_n) \subset \mathbb{K}[x_1, \dots, x_n]$ is said to be **regular** when

$$f_{i+1} \text{ is a regular element in } \mathbb{K}[x_1, \dots, x_n] / \langle f_1, \dots, f_i \rangle$$

Affine regular sequences

A sequence of affine polynomials $(f_1, \dots, f_n) \subset \mathbb{K}[x_1, \dots, x_n]$ is said to be **regular** when the sequence $f_1^{(h)}, \dots, f_n^{(h)}$ of corresponding **homogeneous component of highest degree** is regular.

- ☞ Complexity DRL(pol. sys. affine regular) < DRL(its homogenization)

\mathcal{H}_2 : The affine polynomial systems \mathcal{S} are regular ($\mathcal{H}_2 \Rightarrow \mathcal{H}_1$)

Outline

- 1 PDP in the Index Calculus
- 2 Polynomial System Solving
- 3 PoSSo With Symmetries**
- 4 From Torsion Point to Symmetry
- 5 Characteristic 2
- 6 New Computational Record: 8th Summation Polynomial
- 7 Conclusion

Invariant Polynomial/System

Let be given a polynomial system

$$\mathcal{S} : \begin{cases} f_1(x_1, \dots, x_n) \\ \vdots \\ f_{n-1}(x_1, \dots, x_n) \\ f_n(x_1, \dots, x_n) \end{cases}$$

$$\sigma \in \mathbb{G} \subset \mathrm{GL}(\mathbb{K}, n), \quad \sigma \cdot f_i = f_i(\sigma \cdot \underline{x})$$

☞ Assume all f_i are invariant under the action of \mathbb{G} .
How this assumption can help in solving the polynomial system?

Invariant ring

Definition

Let $\mathbb{K}[x_1, \dots, x_n]$ be a polynomial ring and $\mathbb{G} \subset \text{GL}(\mathbb{K}, n)$.

$$\mathbb{K}[x_1, \dots, x_n]^{\mathbb{G}} = \{p \in \mathbb{K}[x_1, \dots, x_n] \mid \sigma \cdot p = p \text{ for all } \sigma \in \mathbb{G}\}$$

We want to efficiently solve

$$\mathcal{S} : \begin{cases} f_1(x_1, \dots, x_n) \\ \vdots \\ f_{n-1}(x_1, \dots, x_n) \\ f_n(x_1, \dots, x_n) \end{cases}$$

under the assumption $f_1, \dots, f_n \in \mathbb{K}[x_1, \dots, x_n]^{\mathbb{G}}$

Hironaka decomposition

Hilbert's finiteness theorem

Let $G \subset GL(\mathbb{K}, n)$. Its invariant ring $\mathbb{K}[x_1, \dots, x_n]^G$ is finitely generated.

$$\mathbb{K}[x_1, \dots, x_n]^G = \bigoplus_{i=1}^t \eta_i \mathbb{K}[\theta_1, \dots, \theta_n].$$

- *primary invariants* $\theta_1, \dots, \theta_n \in \mathbb{K}[x_1, \dots, x_n]^G$
 - *secondary invariants* $\eta_1, \dots, \eta_t \in \mathbb{K}[x_1, \dots, x_n]^G$
- ☞ primary invariants are **algebraically independent**

Example of Hironaka decomposition

$$\mathbb{Q}[x_1, x_2, x_3]^{A_3} = \bigoplus_{i=1}^2 \eta_i \mathbb{Q}[\theta_1, \theta_2, \theta_3]$$

where

- $\theta_1 = x_1 + x_2 + x_3$, $\theta_2 = x_1x_2 + x_2x_3 + x_1x_3$, $\theta_3 = x_1x_2x_3$
- $\eta_1 = 1$, $\eta_2 = x_1^2x_3 + x_1x_2^2 + x_2x_3^2$

$$f = x_1^3x_2^4x_3 + x_1^4x_2^2x_3^2 + x_1^3x_2^3x_3^2 + x_1^2x_2^4x_3^2 + x_1^4x_2x_3^3 + x_1^3x_2^2x_3^3 + x_1^2x_2^3x_3^3 + x_1^2x_2^2x_3^4 + x_1x_2^3x_3^4 + x_1^3x_2 + 2x_1^2x_2^2 + x_1x_2^3 + x_1^3x_3 + 5x_1^2x_2x_3 + 5x_1x_2^2x_3 + x_2^3x_3 + 2x_1^2x_3^2 + 5x_1x_2x_3^2 + 2x_2^2x_3^2 + x_1x_3^3 + x_2x_3^3$$

$$f \in \mathbb{Q}[x_1, x_2, x_3]^{A_3} \rightsquigarrow f = \theta_1^2\theta_2\eta_1 + \theta_2\theta_3\eta_2$$

Solving by using symmetries

$$\mathbb{K}[x_1, \dots, x_n]^{\mathbb{G}} = \bigoplus_{i=1}^t \eta_i \cdot \mathbb{K}[\theta_1, \dots, \theta_n].$$

Change of variable: $f \in \mathbb{K}[x_1, \dots, x_n]^{\mathbb{G}} \longrightarrow \tilde{f}(\theta_1, \dots, \theta_n, \eta_1, \dots, \eta_t)$

$$\mathcal{I} = \langle \mathcal{S} \rangle \in \mathbb{K}[x_1, \dots, x_n] \longrightarrow \mathcal{J} = (\mathcal{I} \cup \mathcal{I}_{\Omega}) \cap \mathbb{K}[y_1, \dots, y_{n+t}]$$

with $\mathcal{I}_{\Omega} = \langle \theta_1 - y_1, \dots, \theta_n - y_n, \eta_1 - y_{n+1}, \dots, \eta_t - y_{n+t} \rangle$

Computing $\mathcal{V}(\mathcal{I})/\mathbb{G}$

- Compute LEX Gröbner basis \mathcal{G}_{Ω} of $\mathcal{I} \cup \mathcal{I}_{\Omega}$
- $\mathcal{G} = \mathcal{G}_{\Omega} \cap \mathbb{K}[y_1, \dots, y_{n+t}]$ is a Gröbner basis of $\mathcal{J} = I(\mathcal{V}(\mathcal{I})/\mathbb{G})$.

$$\mathcal{V}(\mathcal{I}) = \bigcup_{(v_1, \dots, v_{n+t}) \in \mathcal{V}(\mathcal{I})/\mathbb{G}} \mathcal{V}(\mathcal{G}(y_1 = v_1, \dots, y_{n+t} = v_{n+t}))$$

Solving by using symmetries

$$\mathbb{K}[x_1, \dots, x_n]^{\mathbb{G}} = \bigoplus_{i=1}^t \eta_i \cdot \mathbb{K}[\theta_1, \dots, \theta_n].$$

Change of variable: $f \in \mathbb{K}[x_1, \dots, x_n]^{\mathbb{G}} \longrightarrow \tilde{f}(\theta_1, \dots, \theta_n, \eta_1, \dots, \eta_t)$

$$\mathcal{I} = \langle \mathcal{S} \rangle \in \mathbb{K}[x_1, \dots, x_n] \longrightarrow \mathcal{J} = (\mathcal{I} \cup \mathcal{I}_{\Omega}) \cap \mathbb{K}[y_1, \dots, y_{n+t}]$$

with $\mathcal{I}_{\Omega} = \langle \theta_1 - y_1, \dots, \theta_n - y_n, \eta_1 - y_{n+1}, \dots, \eta_t - y_{n+t} \rangle$

Computing $\mathcal{V}(\mathcal{I})/\mathbb{G}$

- Compute LEX Gröbner basis \mathcal{G}_{Ω} of $\mathcal{I} \cup \mathcal{I}_{\Omega}$
- $\mathcal{G} = \mathcal{G}_{\Omega} \cap \mathbb{K}[y_1, \dots, y_{n+t}]$ is a Gröbner basis of $\mathcal{J} = I(\mathcal{V}(\mathcal{I})/\mathbb{G})$.
- **Pros:** $\deg(\mathcal{J}) = \deg(\mathcal{I})/\#\mathbb{G} \rightsquigarrow$ complx of FGLM step / by $(\#\mathbb{G})^{\omega}$.
- **Cons:** DRL GB of \mathcal{J} may be **more difficult** to compute
 - ▶ $n + t$ variables
 - ▶ η_1, \dots, η_t are **not independent** \rightsquigarrow add equations: $F(\eta_1, \dots, \eta_t) = 0$.

Invariant ring as polynomial ring

Symmetric group: the well known example

$$\mathbb{K}[x_1, \dots, x_n]^{\mathfrak{S}_n} = \mathbb{K}[e_1, \dots, e_n]$$

where $e_k = \sum_{1 \leq i_1 < i_2 < \dots < i_k \leq n} x_{i_1} x_{i_2} \cdots x_{i_k}$ is the k^{th} elementary symmetric polynomial.

- Applying the change of variables

$$\begin{cases} y_1 = e_1(x_1, \dots, x_n) \\ \vdots \\ y_n = e_n(x_1, \dots, x_n) \end{cases}$$

$$\mathcal{I} \subset \mathbb{K}[x_1, \dots, x_n] \longrightarrow \mathcal{J} \subset \mathbb{K}[y_1, \dots, y_n]$$

- The evolution of the degree

$$\deg(\mathcal{I}) = n! \cdot \deg(\mathcal{J})$$

Invariant ring as polynomial ring

Theorem (Shepard, Todd ; Chevalley)

If $\text{char}(\mathbb{K}) \nmid \#\mathbb{G}$ then

$$\mathbb{G} \text{ is a reflection group} \implies \mathbb{K}[x_1, \dots, x_n]^{\mathbb{G}} = \mathbb{K}[\theta_1, \dots, \theta_n]$$

where $\theta_1, \dots, \theta_n \in \mathbb{K}[x_1, \dots, x_n]$ are algebraically independent.

- Applying the change of variables

$$\begin{cases} y_1 = \theta_1(x_1, \dots, x_n) \\ \vdots \\ y_n = \theta_n(x_1, \dots, x_n) \end{cases}$$

$$\mathcal{I} \subset \mathbb{K}[x_1, \dots, x_n] \longrightarrow \mathcal{J} \subset \mathbb{K}[y_1, \dots, y_n]$$

- The evolution of the degree

$$\deg(\mathcal{I}) = \#\mathbb{G} \cdot \deg(\mathcal{J})$$

Evolution on the total complexity for solving PoSSo

Let $\mathcal{S} = \{f_1, \dots, f_n\}$ where $f_i \in \mathbb{K}[x_1, \dots, x_n]^{\mathbb{G}}$ with \mathbb{G} reflection grp

Compute GB DRL from \mathcal{S}

☞ Linear alg. on Macaulay mat.

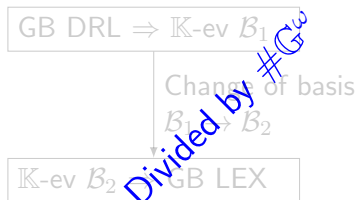
$$t_{i,j} f_i \begin{pmatrix} m_1 > m_2 > \dots \\ \vdots \\ c_{i,j}^1 & c_{i,j}^2 & \dots \end{pmatrix}$$

???

Faugère F_4, F_5

Compute GB LEX from GB DRL

☞ See $\mathbb{K}[x_1, \dots, x_n]/\langle \mathcal{S} \rangle$ as a \mathbb{K} -ev



Faugère, Gaudry, Huot, R. ISSAC'14

On the complexity of computing GB DRL and Symmetries

$$\mathcal{S} = \{f_1, \dots, f_n\} \subset \mathbb{K}[\theta_1, \dots, \theta_n] \subset \mathbb{K}[x_1, \dots, x_n], \text{Deg}(\theta_i) = w_i$$

- \mathcal{S} regular
- $\theta_i^{(h)}$ algebraically independent

DRL with weights (w_1, \dots, w_n) (Faugère, Safey El Din, Verron, 2013)

The complexity of GB DRL is divided by $(w_1 \cdots w_n)^\omega$

Regularity preservation (Faugère, Gaudry, Huot, R.)

The system obtained after the change of coordinates is still regular.

Corollary

$\mathcal{S} = \{f_1, \dots, f_n\} \subset \mathbb{K}[x_1, \dots, x_n]^\mathbb{G}$, \mathbb{G} reflection group. Using the symmetries divides the complexity for solving \mathcal{S} by $\#G^\omega$ (no other hypothesis).

Evolution on the total complexity for solving PoSSo

Let $\mathcal{S} = \{f_1, \dots, f_n\}$ where $f_i \in \mathbb{K}[x_1, \dots, x_n]^{\mathbb{G}}$ with \mathbb{G} reflection grp

Compute GB DRL from \mathcal{S}

☞ Linear alg. on Macaulay mat.

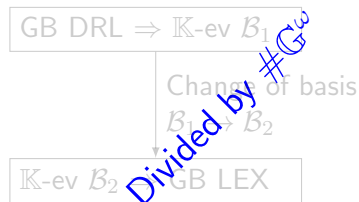
$$t_{i,j} f_i \begin{pmatrix} m_1 > m_2 > \dots \\ c_{i,j}^1 & c_{i,j}^2 \end{pmatrix}$$

Divided by $\#\mathbb{G}^w$

Faugère F_4, F_5

Compute GB LEX from GB DRL

☞ See $\mathbb{K}[x_1, \dots, x_n]/\langle \mathcal{S} \rangle$ as a \mathbb{K} -ev



Faugère, Gaudry, Huot, R. ISSAC'14

Outline

- 1 PDP in the Index Calculus
- 2 Polynomial System Solving
- 3 PoSSo With Symmetries
- 4 From Torsion Point to Symmetry**
- 5 Characteristic 2
- 6 New Computational Record: 8th Summation Polynomial
- 7 Conclusion

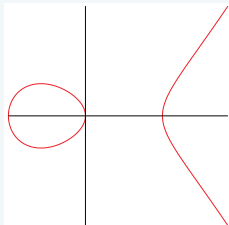
Elliptic curve representations

Ordinary elliptic curves

Weierstrass equation, $E : y^2 = x^3 + ax + b$

Arithmetic:

- Number of operations in \mathbb{F}_{q^n} :
 - (Doubling) 5 mult + 6 squares + 1 div
 - (Adding) 12 mult + 2 squares
- Group law not unified



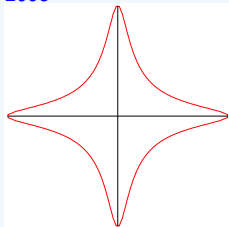
Efficient arithmetic on Elliptic curves

Edwards, Bulletin of the AMS 2007 ; Bernstein et al., AFRICACRYPT 2008

Edwards representation, $E : ax^2 + y^2 = 1 + dx^2y^2$

Arithmetic:

- Number of operations in \mathbb{F}_{q^n} :
 - (Doubling) 3 mult + 4 squares
 - (Adding) 10 mult + 1 square + 1 div
- Group law **unified** \rightsquigarrow resistant to side channel attacks.



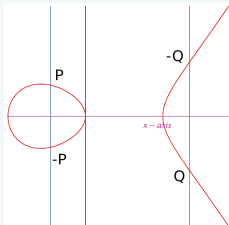
Elliptic curve representations

Ordinary elliptic curves

Weierstrass equation, $E : y^2 = x^3 + ax + b$

Symmetry:

- (negative of a point) $P = (x, y) \Rightarrow \ominus P = (x, -y)$.
↪ Reflection w.r.t. x -axis.



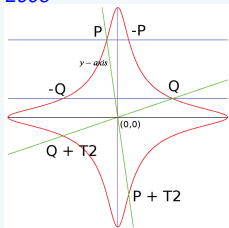
Efficient arithmetic on Elliptic curves

Edwards, Bulletin of the AMS 2007 ; Bernstein et al., AFRICACRYPT 2008

Edwards representation, $E : ax^2 + y^2 = 1 + dx^2y^2$

Symmetries:

- (negative of a point) $P = (x, y) \Rightarrow \ominus P = (-x, y)$.
↪ Reflection w.r.t. y -axis.
- (addition with T_2) $P = (x, y)$ and $T_2 = (0, -1)$
 $\Rightarrow P \oplus T_2 = (-x, -y)$.
↪ Point reflection w.r.t. $(0, 0)$.



Application of summation polynomials

PDP(R, \mathcal{F})

We want to find $P_1, \dots, P_n \in \mathcal{F} = \{(x, y) \in E \mid x \in \mathbb{F}_q\}$ such that

$$R = P_1 \oplus \dots \oplus P_n \iff P_1 \oplus \dots \oplus P_n \ominus R = 0_E$$

where R is a fixed point in E .

A first symmetry

 The problem has intrinsic symmetries: $R = P_1 \oplus P_2 \iff R = P_2 \oplus P_1$



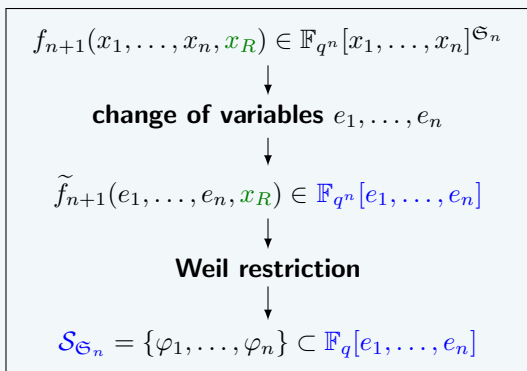
Does not imply that summation polynomials are symmetric in general.
Fortunately it is the case!

 How to use more symmetries?

System symmetrization - Weierstrass model

$$f_{n+1}(x_1, \dots, x_n, x_R) \in \mathbb{F}_{q^n}[x_1, \dots, x_n]^{\mathfrak{S}_n}$$

Corollary (*Gaudry 2005*)



$$\Leftrightarrow \text{Deg}(\varphi_i) \leq 2^{n-1}$$

\mathcal{H}_2 : The affine polynomial systems $\mathcal{S}_{\mathfrak{S}_n}$ are regular

Edwards curves: Action of 2-torsion point

☞ Reflection w.r.t. y -axis, projection on the y_i 's for summation polynomial

Definition

$E_{a,d} : ax^2 + y^2 = 1 + dx^2y^2$ has a 2-torsion point $T_2 = (0, -1)$

Property

$\forall P = (x, y) \in E_{a,d}(\mathbb{F}_{q^n}),$
 $P \oplus T_2 = (-x, -y).$

Action on the points (geometry)

For any combination of an even number of additions by T_2 :

$$\begin{aligned} P_1 \oplus \cdots \oplus P_n = R &\iff (P_1 \oplus T_2) \oplus (P_2 \oplus T_2) \oplus P_3 \oplus \cdots \oplus P_n = R \\ (y_1, \dots, y_n) \in V_R &\iff (-y_1, -y_2, y_3, \dots, y_n) \in V_R \end{aligned}$$

What is the name of the group \mathbb{G} acting on the variety?

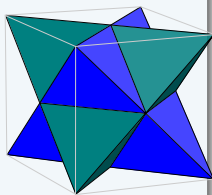
The Coxeter group $D_n \supset \mathfrak{S}_n$

Definition

D_n is the symmetry group of the n -demihypercube.

$$D_n = (\mathbb{Z}/2\mathbb{Z})^{n-1} \rtimes \mathfrak{S}_n \implies \#D_n = n! \cdot 2^{n-1}$$

$(\mathbb{Z}/2\mathbb{Z})^{n-1}$: even sign changes on $\{y_1, \dots, y_n\}$.



D_n properties

- Reflection group

- $\mathbb{F}_q[y_1, \dots, y_n]^{D_n} = \mathbb{F}_q[s_1, \dots, s_{n-1}, e_n]$

- ▶ $s_i = \sum_{1 \leq j_1 < \dots < j_i \leq n} \prod_{k=1}^i y_{j_k}^2$ elem. symmetric polynomial in y_1^2, \dots, y_n^2 .

- ▶ $e_n = \prod_{k=1}^n y_k$ the n^{th} elem. symmetric polynomial.

From geometry to algebra

Let \mathbb{G} be a linear group.

Problem



$$\mathbb{G} \cdot \mathcal{S} = \mathcal{S} \not\Rightarrow \mathbb{G} \cdot \langle \mathcal{S} \rangle = \langle \mathcal{S} \rangle \iff \mathbb{G} \cdot \mathcal{V}(\langle \mathcal{S} \rangle) = \mathcal{V}(\langle \mathcal{S} \rangle)$$

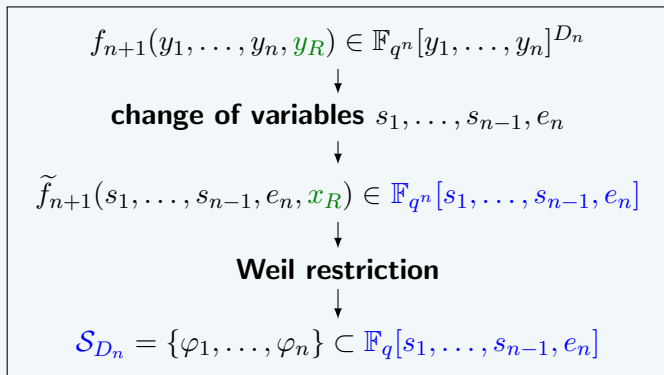
Invariance of summation polynomials under D_n (Faugère, Gaudry, Huot, R.)

$$f_{n+1}(y_1, \dots, y_n, y_R) \in \mathbb{F}_{q^n}[y_1, \dots, y_n]^{D_n}$$

☞ We are in the conditions of Shepard, Todd Thm (large charac.)

New change of variables

Corollary



Each $s_i = \theta_i(e_1, \dots, e_n)$ with $\text{Deg}(\theta_i) = 2 \rightarrow \text{weights } (2, \dots, 2, 1)$

Theorem (Faugère, Gaudry, Huot, R.)

Under the same hypothesis \mathcal{H}_2 on $\mathcal{S}_{\mathfrak{S}_n}$, by using the action of T_2 the complexity for solving PDP is divided by $2^{\omega(n-1)}$

Some practical results

Magma or fgb

- $\#\mathbb{F}_q$: 16 bits

n		Step 1	Step 2	Total	# ops
		Time (s)	Time (s)	time (s)	
4	W. sym	6	460	466	2^{29}
	E/J D_n	0	3	3	2^{23}
5 fgb	W. sym	> 2 days			
	E/J D_n	567	2165	2732	2^{45}

- $n = 4$

$\#\mathbb{F}_q$ (bits)		32	64	128	160
Total time (s)	W. sym	6922	4717	5837	6898
	E/J D_n	43	40	53	73

Outline

- 1 PDP in the Index Calculus
- 2 Polynomial System Solving
- 3 PoSSo With Symmetries
- 4 From Torsion Point to Symmetry
- 5 Characteristic 2**
- 6 New Computational Record: 8th Summation Polynomial
- 7 Conclusion

Action of the 2-torsion in charac. 2 (Faugère, Huot, Joux, R., Vitse)

Elliptic curve E defined over $\mathbb{F}_{2^{kn}}$ with $j(E) \neq 0$:

$$y^2 + xy = x^3 + ax^2 + b$$

Assume $b = \gamma^4$.

T_2 the 2-torsion point of E

- $T_2 = (0, \gamma^2)$
- $P \oplus T_2 = \frac{\gamma^2}{x(P)}$

☞ No chance to use such a point as in large characteristic!

Characteristic 2: change of coordinates for a better action

Elliptic curve E defined over $\mathbb{F}_{2^{kn}}$ with $j(E) \neq 0$:

$$y^2 + xy = x^3 + ax^2 + b$$

Assume $b = \gamma^4$.

↗ Change of coordinates: $x \mapsto \frac{\gamma}{x+\gamma} + \lambda$

T_2 the 2-torsion point of E becomes

- $T_2 = (1 + \lambda, \gamma^2)$
- $P \oplus T_2 = x(P) + 1$

Characteristic 2: change of coordinates for a better action

Elliptic curve E defined over $\mathbb{F}_{2^{kn}}$ with $j(E) \neq 0$:

$$y^2 + xy = x^3 + ax^2 + b$$

Assume $b = \gamma^4$.

☞ Change of coordinates: $x \mapsto \frac{\gamma}{x+\gamma} + \lambda$

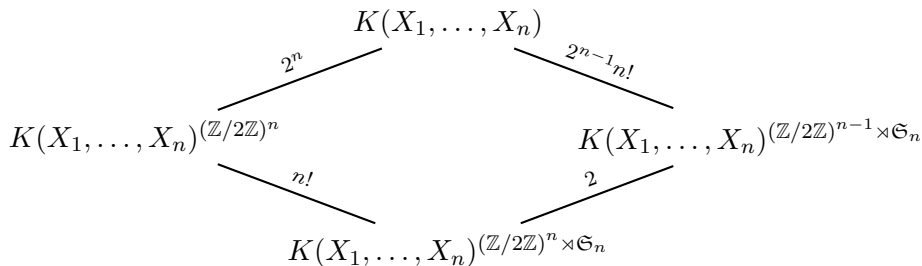
T_2 the 2-torsion point of E becomes

- $T_2 = (1 + \lambda, \gamma^2)$
- $P \oplus T_2 = x(P) + 1$

☞ Better action but no more linear, anyway we are in the modular case!

Some Galois theory with the action $X_i \mapsto X_i + 1$

$$K = \mathbb{F}_{2^{kn}}$$



- $K(X_1, \dots, X_n)^{(\mathbb{Z}/2\mathbb{Z})^n} = K(X_1^2 + X_1, \dots, X_n^2 + X_n)$
- $K(X_1, \dots, X_n)^{(\mathbb{Z}/2\mathbb{Z})^n \rtimes \mathfrak{S}_n} = K(s_1, \dots, s_n), s_i = e_i(X_1^2 + X_1, \dots, X_n^2 + X_n)$
- $K(X_1, \dots, X_n)^{(\mathbb{Z}/2\mathbb{Z})^{n-1} \rtimes \mathfrak{S}_n} = K(e_1, s_2, \dots, s_n), e_1 = X_1 + \dots + X_n$

$$K[X_1, \dots, X_n]^{(\mathbb{Z}/2\mathbb{Z})^{n-1} \rtimes \mathfrak{S}_n} = K[e_1, s_2, \dots, s_n]$$

Characteristic 2: conclusion (Faugère, Huot, Joux, R., Vitse)

Summation polynomial in characteristic 2 ($\lambda = 0, 1$)

- $f_{n+1}(x_1, \dots, x_n, x_R) \in \mathbb{F}_{2^{kn}}[x_1, \dots, x_n]^{D_n} = \mathbb{F}_{2^{kn}}[e_1, s_2 \dots, s_n]$
- $f_{n+1}(x_1, \dots, x_n, x_R) \in \mathbb{F}_{2^{kn}}[e_1^2, s_2^2 \dots, s_{n-1}^2, s_n]$

Theorem

Under the same hypothesis \mathcal{H}_2 on $\mathcal{S}_{\mathbb{G}_n}$, by using the action of T_2 the complexity for solving PDP is divided by $2^{\omega 2(n-1)}$

Practical results (Oakley 'Well-Known Groups' 3 over $\mathbb{F}_{2^{31 \times 5}}$)

To obtain one relation

- Joux-Vitse $n - 1$ -method: ≈ 37 years
- This work: ≈ 5.5 hours

Outline

- 1 PDP in the Index Calculus
- 2 Polynomial System Solving
- 3 PoSSo With Symmetries
- 4 From Torsion Point to Symmetry
- 5 Characteristic 2
- 6 New Computational Record: 8th Summation Polynomial**
- 7 Conclusion

Iterative Construction

$$S_n(x_1, \dots, x_n) = \text{Res}_X(S_{n-k+1}(x_1, \dots, x_{n-k}, X), S_{k+1}(x_{n-k+1}, \dots, x_n, X))$$

$$k \in \{2, \dots, n-2\}$$

$$\rightsquigarrow O(2^{n^2})$$

☞ In characteristic 2, rewrite it with smaller degrees!

Iterative Construction

$$S_n(x_1, \dots, x_n) \in \mathbb{F}_{2^{kn}}[e_1^2, s_2^2, \dots, s_{n-1}^2, s_n]$$

$$s_i = e_i(X_1^2 + X_1, \dots, X_n^2 + X_n)$$

$$\text{Res}_X \left(S_{n-k+1}^p \left(e_{1,n-k}^2, s_{2,n-k}^2, \dots, s_{n-k-1,n-k}^2, s_{n-k,n-k}, X \right), \right. \\ \left. S_{k+1}^p \left(e_{1,k}^2, s_{2,k}^2, \dots, s_{k-1,k}^2, s_{k,k}, X \right) \right).$$

$$k \in \{2, \dots, n-2\}$$

$$\Omega : \begin{cases} e_1^2 & = e_{1,n-k}^2 + e_{1,k}^2 \\ s_2^2 & = s_{2,n-k}^2 + s_{2,k}^2 + \alpha_1 \alpha_2 \\ s_3^2 & = s_{3,n-k}^2 + s_{3,k}^2 + \alpha_1 s_{2,k}^2 + \alpha_2 s_{2,n-k}^2 \\ s_4^2 & = s_{4,n-k}^2 + s_{4,k}^2 + \alpha_1 s_{3,k}^2 + \alpha_2 s_{3,n-k}^2 + s_{2,n-k}^2 s_{2,k}^2 \\ & \vdots \\ s_{n-2}^2 & = s_{n-k,n-k}^2 s_{k-2,k}^2 + s_{n-k-1,n-k}^2 s_{k-1,k}^2 + s_{n-k-2,n-k}^2 s_{k,k}^2 \\ s_{n-1}^2 & = s_{n-k,n-k}^2 s_{k-1,k}^2 + s_{n-k-1,n-k}^2 s_{k,k}^2 \\ s_n & = s_{n-k,n-k} s_{k,k} \end{cases}$$

$$\alpha_1 = e_{1,n-k}^2 + e_{1,n-k} \text{ and } \alpha_2 = e_{1,k}^2 + e_{1,k}.$$

Iterative Construction

$$S_n(x_1, \dots, x_n) \in \mathbb{F}_{2^{kn}}[e_1^2, s_2^2, \dots, s_{n-1}^2, s_n]$$

$$s_i = e_i(X_1^2 + X_1, \dots, X_n^2 + X_n)$$

$$\text{Res}_X \left(\begin{array}{l} S_{n-k+1}^p \left(e_{1,n-k}^2, s_{2,n-k}^2, \dots, s_{n-k-1,n-k}^2, s_{n-k,n-k}, X \right), \\ S_{k+1}^p \left(e_{1,k}^2, s_{2,k}^2, \dots, s_{k-1,k}^2, s_{k,k}, X \right) \end{array} \right).$$

$$k \in \{2, \dots, n-2\}$$

- The change of var. Ω can be applied with a Grobner basis comp.
- On can obtain S_6 with this method
- We obtain S_7 by using some shortcuts (essentially by hand)

☞ The 8th Summation polynomial still intractable!

Sparse multivariate polynomial interpolation

$$(e_1^2, s_2^2, \dots, s_{n-1}^2, s_n) \longrightarrow \boxed{\phantom{\text{algorithm}}} \longrightarrow v$$

$S_n(e_1^2, s_2^2, \dots, s_{n-1}^2, s_n)$

Zippel's probabilistic algorithm

- Interpolation of dense univariate polynomials
- Iterative on the variables
- The evaluation step has to be very efficient ($O(nt2^{n-3})$ evaluations)

Sparse multivariate polynomial interpolation

$$S_n(e_1^2, s_2^2, \dots, s_{n-1}^2, s_n)$$

$$(e_1^2, s_2^2, \dots, s_{n-1}^2, s_n) \longrightarrow \text{Res}_X(S_{n-k+1}^p, S_{k+1}^p) \longrightarrow v$$

Zippel's probabilistic algorithm

- The evaluation step has to be very efficient ($O(nt2^{n-3})$ evaluations)

$$\Omega : \begin{cases} e_1^2 &= e_{1,n-k}^2 + e_{1,k}^2 \\ s_2^2 &= s_{2,n-k}^2 + s_{2,k}^2 + \alpha_1 \alpha_2 \\ s_3^2 &= s_{3,n-k}^2 + s_{3,k}^2 + \alpha_1 s_{2,k}^2 + \alpha_2 s_{2,n-k}^2 \\ s_4^2 &= s_{4,n-k}^2 + s_{4,k}^2 + \alpha_1 s_{3,k}^2 + \alpha_2 s_{3,n-k}^2 + s_{2,n-k}^2 s_{2,k}^2 \\ &\vdots \\ s_{n-2}^2 &= s_{n-k,n-k}^2 s_{k-2,k}^2 + s_{n-k-1,n-k}^2 s_{k-1,k}^2 + s_{n-k-2,n-k}^2 s_{k,k}^2 \\ s_{n-1}^2 &= s_{n-k,n-k}^2 s_{k-1,k}^2 + s_{n-k-1,n-k}^2 s_{k,k}^2 \\ s_n &= s_{n-k,n-k}^2 s_{k,k} \end{cases}$$

$$\alpha_1 = e_{1,n-k}^2 + e_{1,n-k} \text{ and } \alpha_2 = e_{1,k}^2 + e_{1,k}$$



Grobner basis comp. not enough efficient: 1.4sec. \rightsquigarrow 5 years for S_8

Sparse multivariate polynomial interpol. using symmetry

$$S_n(e_1^2, s_2^2, \dots, s_{n-1}^2, s_n)$$

$$(e_1^2, s_2^2, \dots, s_{n-1}^2, s_n) \longrightarrow \text{Res}_X (S_{n-k+1}^p, S_{k+1}^p) \longrightarrow v$$

- ☞ (s_1^2, \dots, s_n^2) can be deduced from $(e_1^2, s_2^2, \dots, s_{n-1}^2, s_n)$
- ☞ The s_i^2 come from elem. symm. pol: $s_i^2 = e_i(x_1^4 + x_1^2, \dots, x_n^4 + x_n^2)$

$$f_n(X) = X^n + \tilde{s}_1^2 X^{n-1} + \dots + \tilde{s}_{n-1}^2 X + \tilde{s}_n^2 = \prod_{i=1}^n (X + (\tilde{x}_i^4 + \tilde{x}_i^2)) .$$

$$f_n(X) = f_k(X) f_{n-k}(X)$$

- ☞ Evaluation points of S_{n-k+1}^p, S_{k+1}^p deduced from $f_k(x), f_{n-k}(X)$.

Sparse multivariate polynomial interpol. using symmetry

$$(e_1^2, s_2^2, \dots, s_{n-1}^2, s_n) \longrightarrow \text{Res}_X (S_{n-k+1}^p, S_{k+1}^p) \longrightarrow v$$

$S_n(e_1^2, s_2^2, \dots, s_{n-1}^2, s_n)$

Final computation with fast evaluation

Grobner basis comp. \rightarrow factorization, 3 degree 2 pol. to solve (over \mathbb{F}_{2^k})

✂ Using this fast evaluation we computed S_8 in $\approx 40.5\text{h}$

Outline

- 1 PDP in the Index Calculus
- 2 Polynomial System Solving
- 3 PoSSo With Symmetries
- 4 From Torsion Point to Symmetry
- 5 Characteristic 2
- 6 New Computational Record: 8th Summation Polynomial
- 7 Conclusion**

Conclusion

☞ Here some introductory results are presented, more are given in our EC'14 paper:

Torsion points of small order

Faugère, Huot, Joux, R., Vitse EC'14

- Study more general projection (Diem's view point)
- Characterize the possible interesting torsion points
- Show how to use full 2-torsion in large char. (w/ experimental results)