Systems Biology: A Personal View XVI. Interactions in Ecology

Sitabhra Sinha IMSc Chennai

Spatial & Temporal Scales in Ecological Studies



Adapted from Pimm, The Balance of Nature ?

Modeling population dynamics of species

A single species: population dynamics with intra-species competition represented by a logistic term (like mean-field theory, we assume its environment to be fixed)

$$dx/dt = r x [I - (x/K)]$$

r: Growth rate, K: carrying capacity

Introducing interactions between species

Mutual competition between two species using the same resources can be modeled as:

$$dx/dt = r x [I - (x/K) - (x'/K)]$$

But interactions can be of different kind, viz., predator-prey !

2 species Resource-Consumer Dynamics

- Prey-Predator trophic relations
- Host-parasite
- Plant-Herbivore

In general can be of the form:

$$dx/dt = \phi(x) - g(x, y) y$$
$$dy/dt = n(x, y) y - d y$$

 $\phi(x)$: growth of prey in absence of predators g(x,y): capture rate of prey per predator n(x,y): rate at which captured prey is converted into predator population increase – assumed to be ε g(x,y) where ε is efficiency d: rate at which predators die in absence of prey

Different choices of the functional forms can give different models

Lotka-Volterra Model (1920-6)

The first model of consecutive chemical reactions giving rise to oscillations in molecular concentrations

$$\begin{array}{c} \mathsf{A} + \mathsf{X} \to \mathsf{2}\mathsf{X} \\ \mathsf{X} + \mathsf{Y} \to \mathsf{2}\mathsf{Y} \\ \mathsf{Y} \to \mathsf{P} \end{array}$$

(Autocatalysis: +ve feedback)



Alfred Lotka

More reasonable in the context of ecology

Prey (x) – Predator (y) eqns $dx/dt = r x - k_{xy} x y$ $dy/dt = k_{yx} x y - d y$ Volterra (1926) $dx/dt = r x - k_{zy} x y$ $dy/dt = k_{yx} (x y - d y)$

Lotka-Volterra Model (1920-6)

D'Ancona: The problem of high proportion of predator fishes in the Adriatic Sea during WWI (1914-1918)

Prey (x) – Predator (y) eqns + effect of fishing

$$dx/dt = (r - a) x - k_{xy} x y$$

$$dy/dt = k_{yx} x y - (d + b) y$$

500

400

300

200

100

0 Ò

50

100

х

>



150

200

250

Volterra (1926) Equilibrium populations: $x^* = (d+b)/k_{xy}, y^* = (r-a)/k_{xy}$

In absence of fishing during the war years (a=0,b=0), x* decreased while y* increased

In general, we observe oscillations because cycles around the equilibria are neutrally stable



Chaos in Lotka-Volterra System



- Two-species Lotka-Volterra systems: periodic oscillations.
- Chaos in Lotka Volterra system with three species (Arneodo, Coullet and Tresser, 1980).
- In principle possible for a species to persist in food web that is not dynamically stable by going through complex cycles.

• However, the cycles must be strictly bounded - otherwise populations will reach levels from which they cannot recover.

Rosenzweig-MacArthur Model (1963)

Predator-Prey model with Holling Type 2 (hyperbolic) functional response

Functional response of predation to prey density (Holling, 1959)





C S Holling (1930-)

Prey (x) – Predator (y) eqns

$$\frac{dx}{dt} = r x [I - (x / K)] - q y [x / (b+x)]}{dy/dt} = -d y + \varepsilon q y [x / (b+x)]$$

Gives rise to limit cycle oscillations

3 species Rosenzweig-MacArthur Model



Going beyond 3 species opens up an entire world of dynamical possibilities...

Ecological (Interaction) Networks

And specifically,

Food Webs

that comprise links representing trophic relations