

Dynamics of Distal Group Actions

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“Indian Women and Mathematics”

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Dynamical Systems

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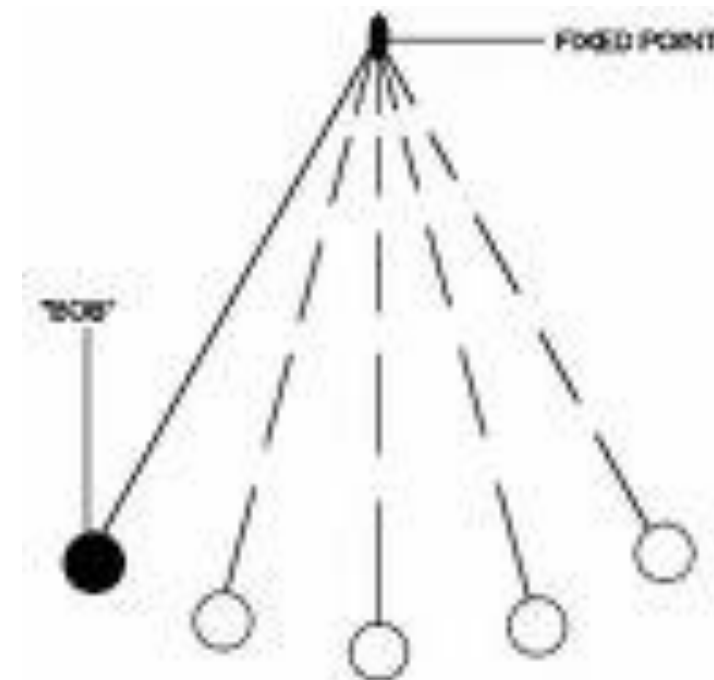
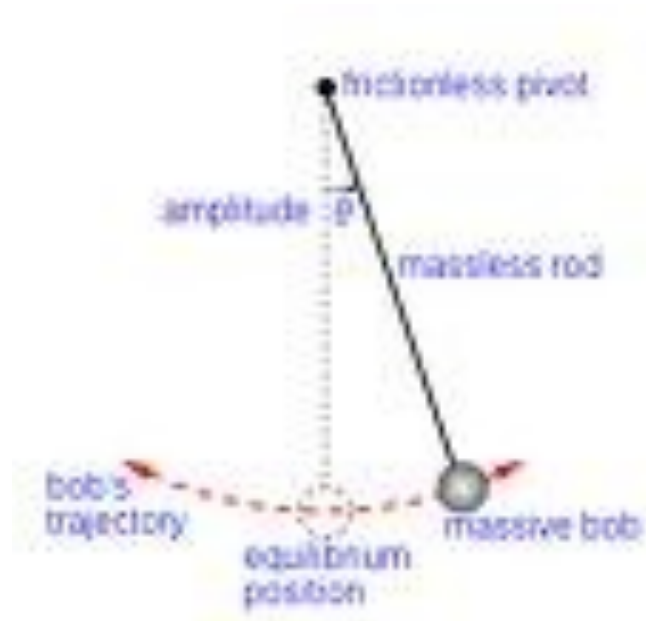
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It could be regular or chaotic. We discuss some specific **examples** now.

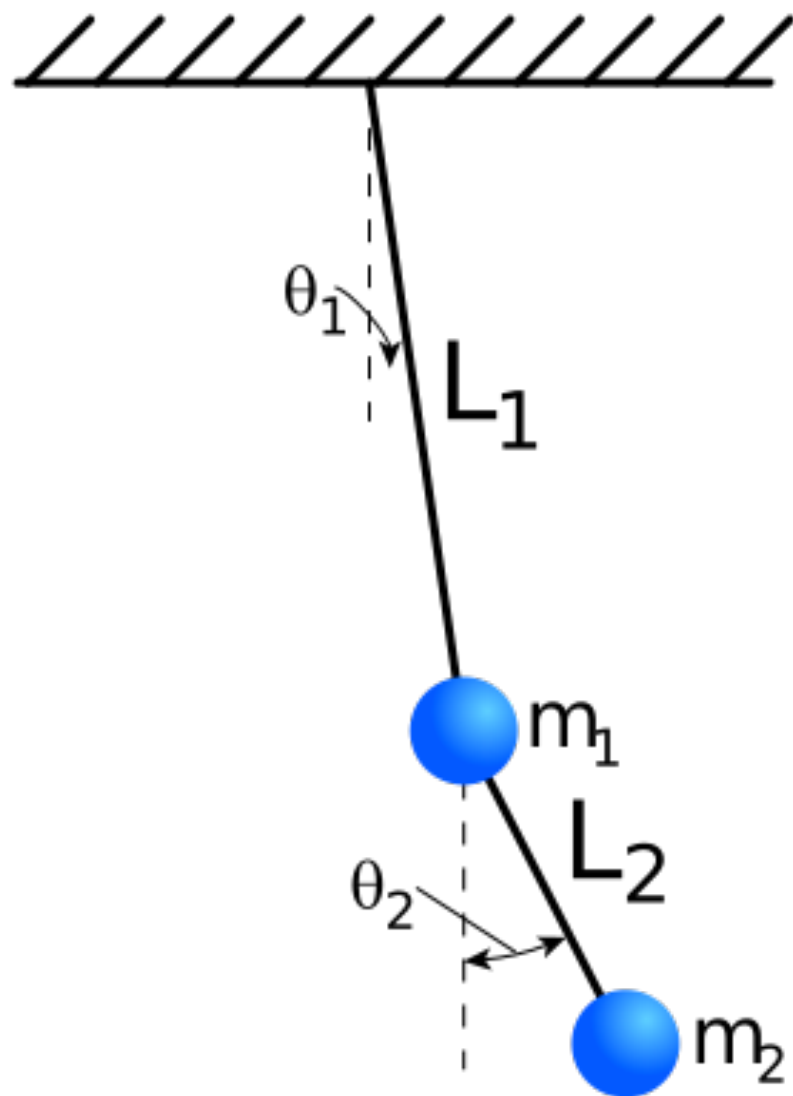
Single Pendulum

- Single Pendulum behaves nicely.



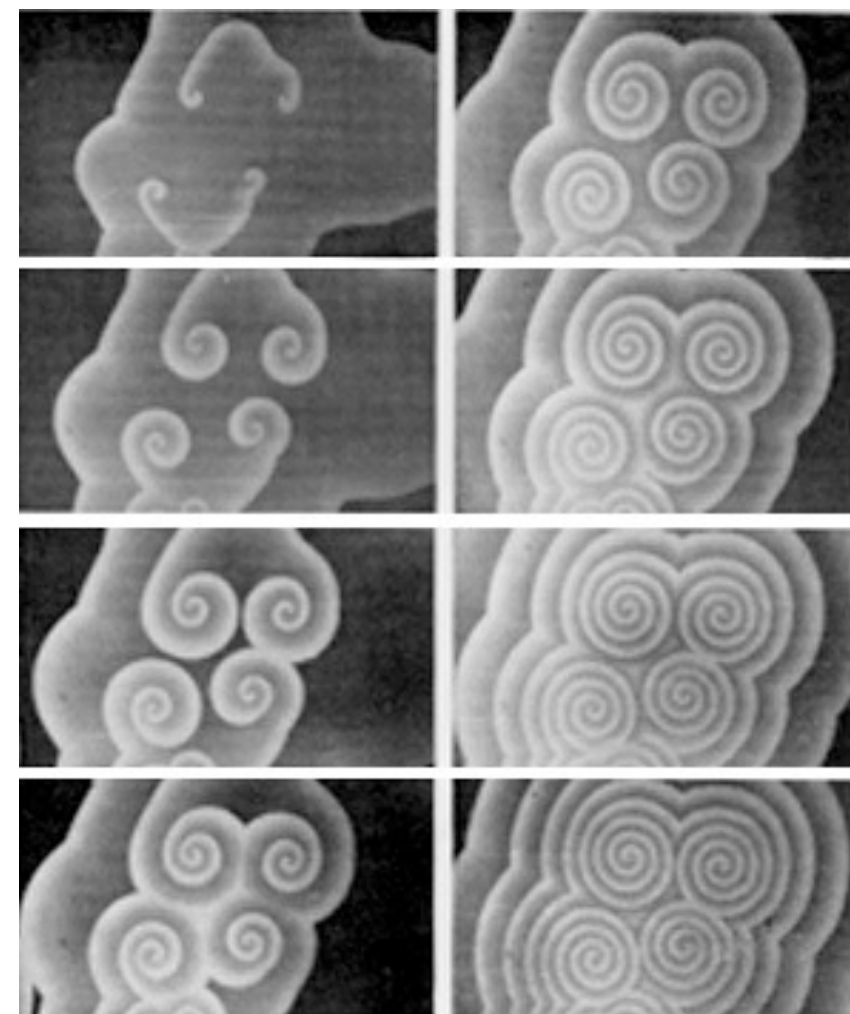
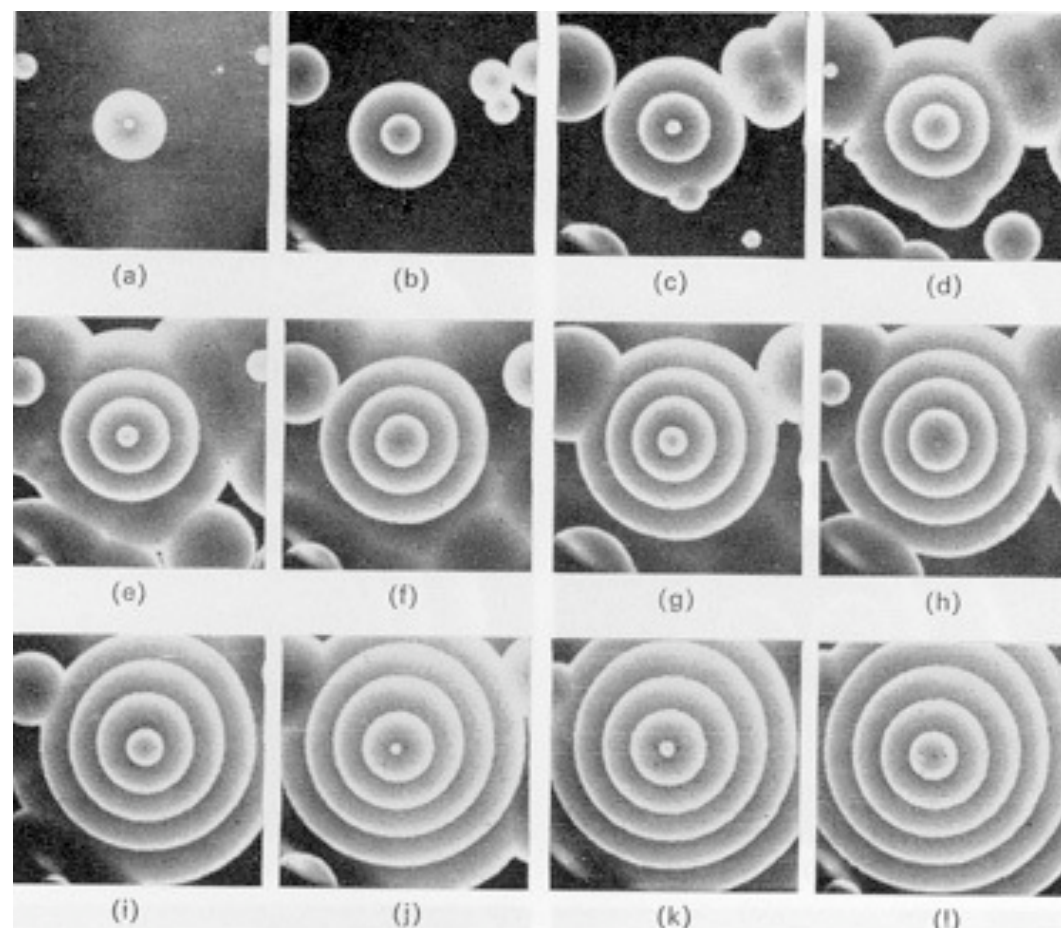
Double Pendulum

- But double pendulum displays chaos.



Belousov-Zhabotinsky reaction

- Describes changes in chemical concentrations ($\text{Ce}^{3+}/\text{Ce}^{4+}$ couple as catalyst and Citric Acid as reactant)
- Model using reaction diffusion equations $u_t = \nabla^2 u + f(u)$.



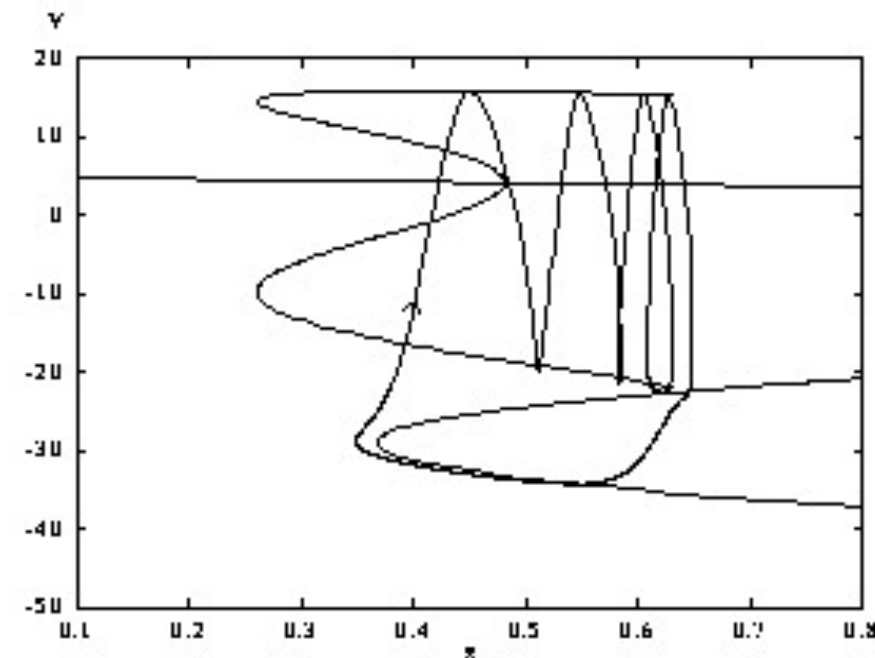
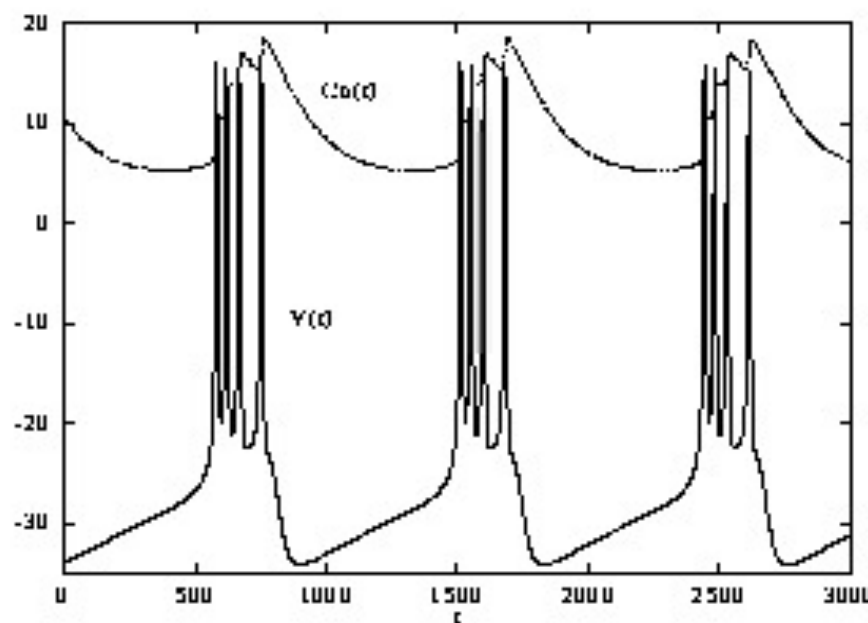
Mathematical models for neuronal

- Goal is to model how the voltage across a cell membrane changes over time (My former colleague [Amitabh Bose](#) works in this field).
- Hodgkin and Huxley derived equations in 1950's to describe this. They found that neurons behave almost like electrical circuits.
- Example trace from a bursting neuron related to breathing.

pre-Botzinger bursting neuron (in vitro)



1 sec



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(pure mathematics)

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- In case the map is ergodic (chaotic), there is one orbit of T which is dense in X (like in the path of double pendulum) i.e. $\{T^n(x): n=1, 2, 3, \dots\}$ is dense or $\{T_t(x)\}$ is dense in X . It is not very sensitive to initial conditions.

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- Distal maps were introduced by **Hilbert** and studied by many mathematicians.

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- Also the space of probability measures on distal groups (conjugacy maps are distal) have special properties, for. e.g. on compact groups, discrete groups, abelian groups (real line), finite groups etc.
- We will give a splitting of the space into invariant **ergodic components** as we shall see later.

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- Here, $T^n(x) = x$ or $-x$ for all n .
- If $|r| < 1$, then T contracts any point and orbit of any point goes to zero.
- Namely, $T^n(x) = r^n x \rightarrow 0$ as n tends to infinity all x . So it can not be distal.

Rotations on Unit Circle S^1

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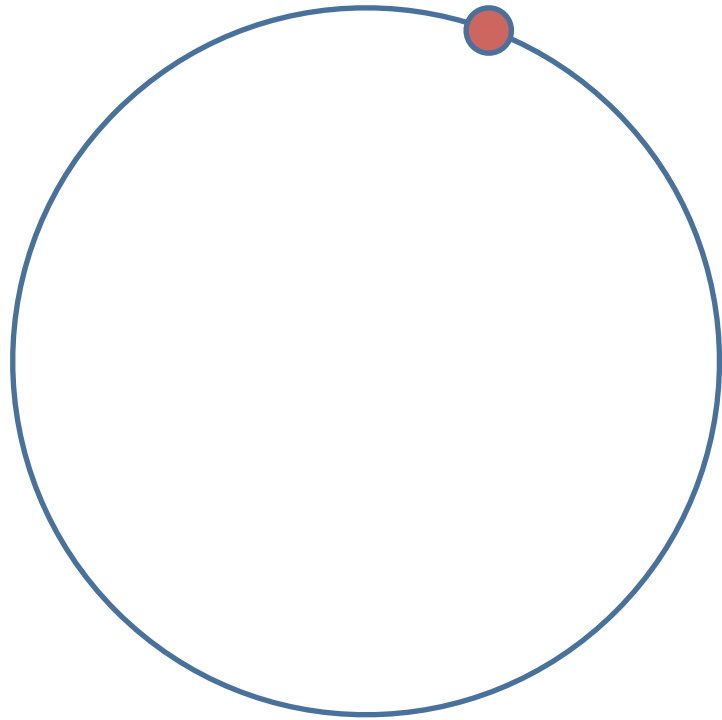
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- In most cases, ergodicity and distality are two opposite phenomena.

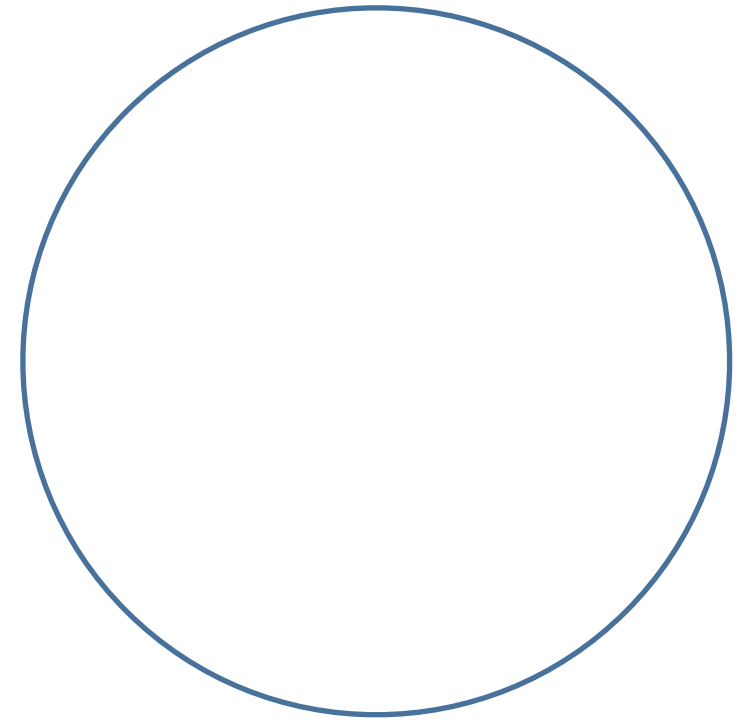
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- We next have a pictorial description of rotation maps thanks to my former colleague **Amitabh Bose**.

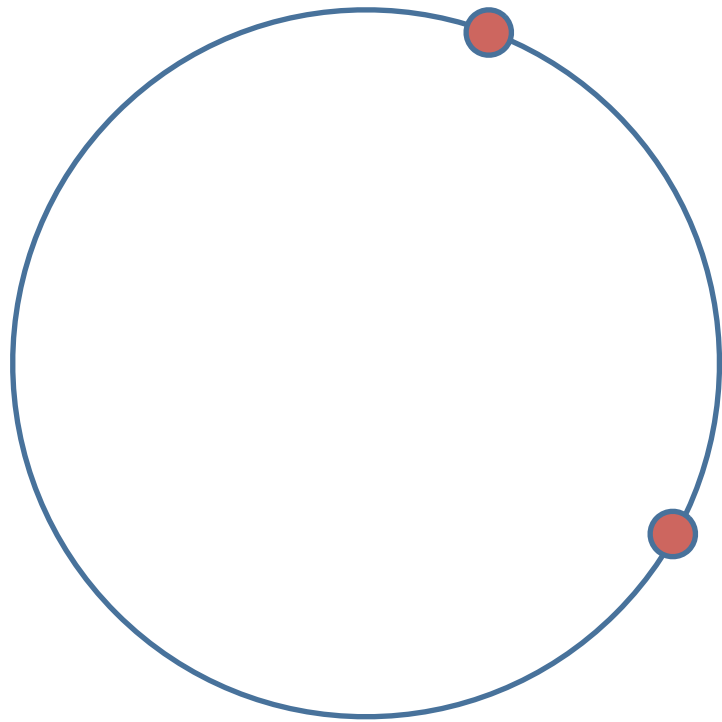
Periodic orbit



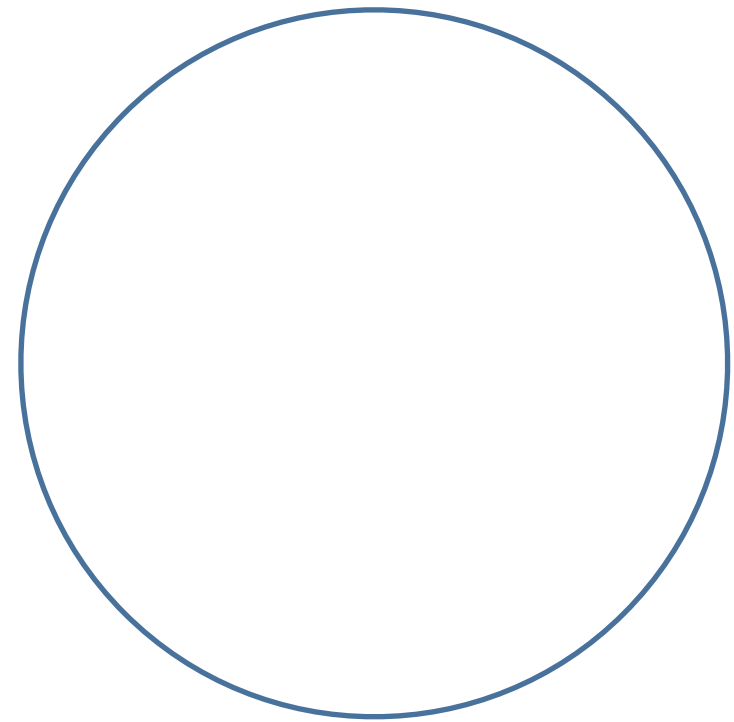
Dense orbit



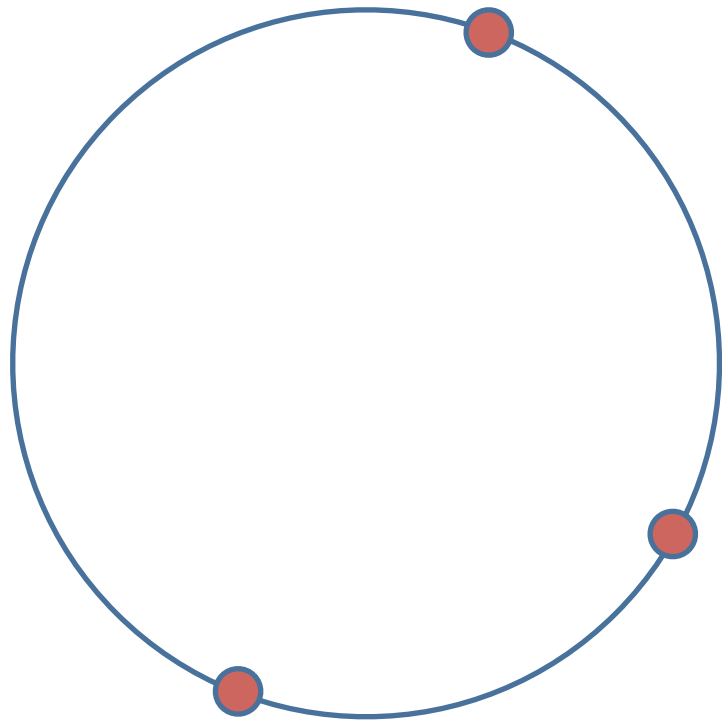
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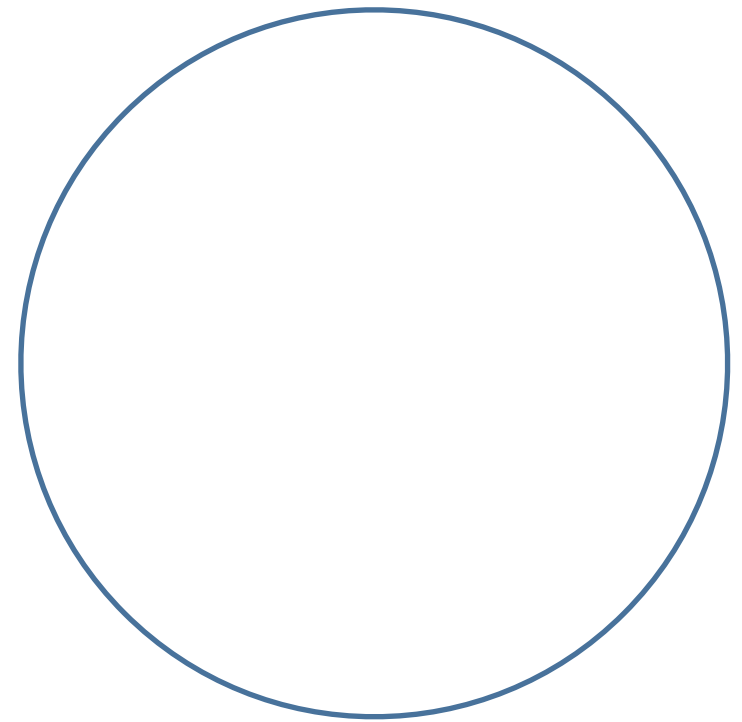
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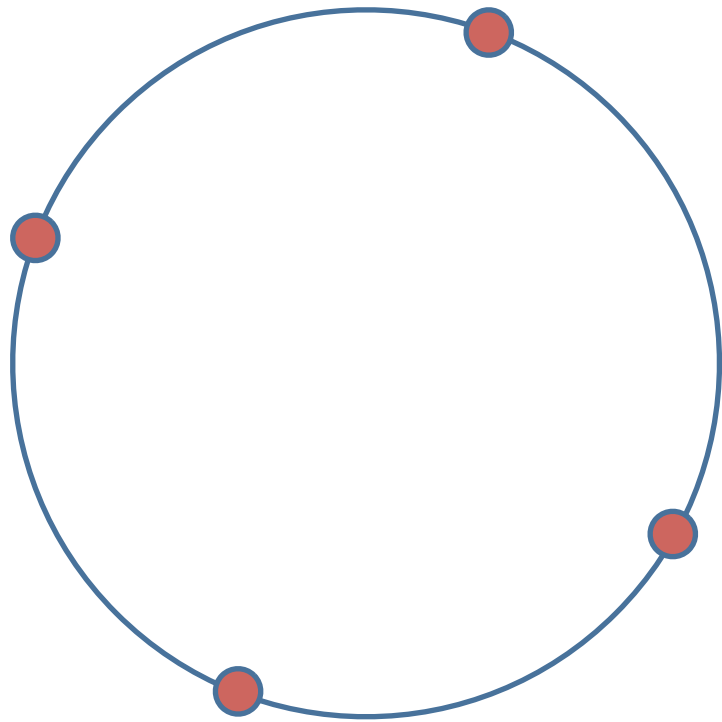
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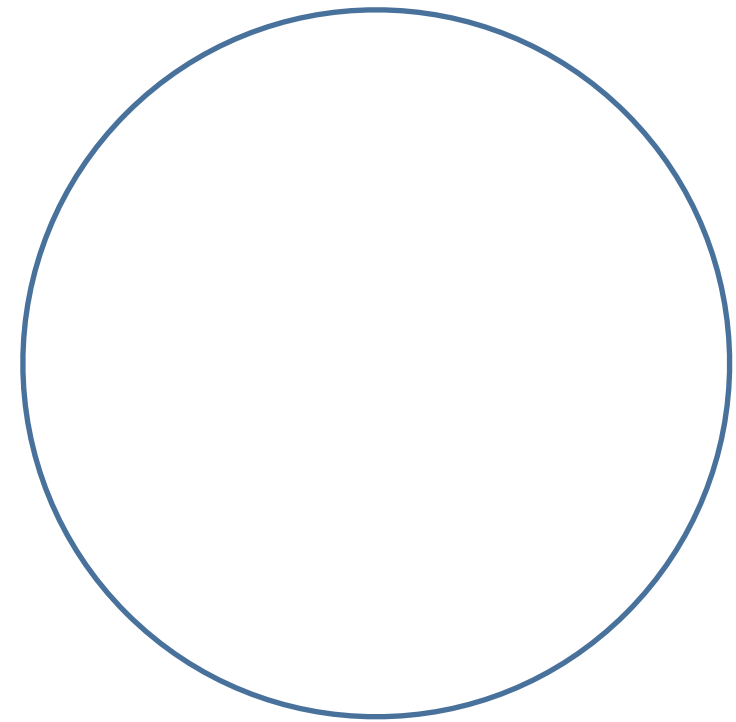
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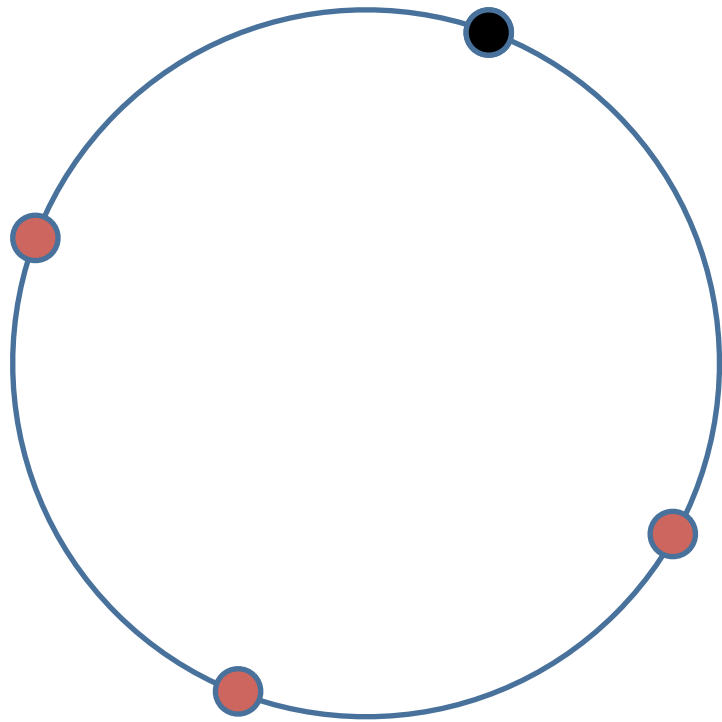
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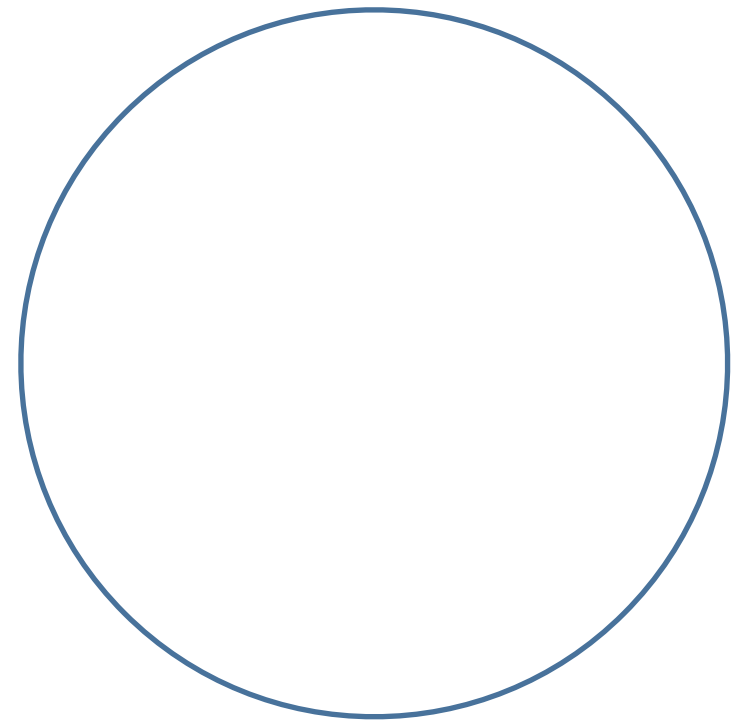
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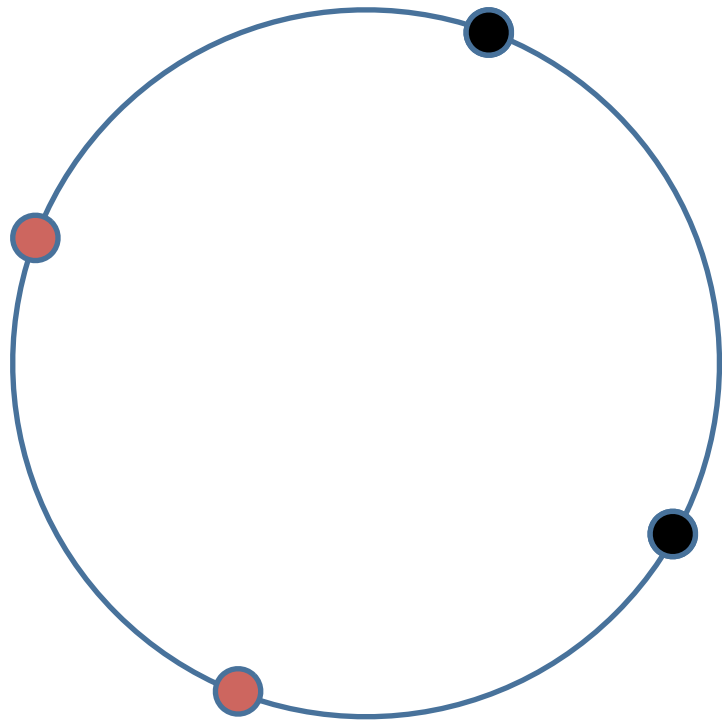
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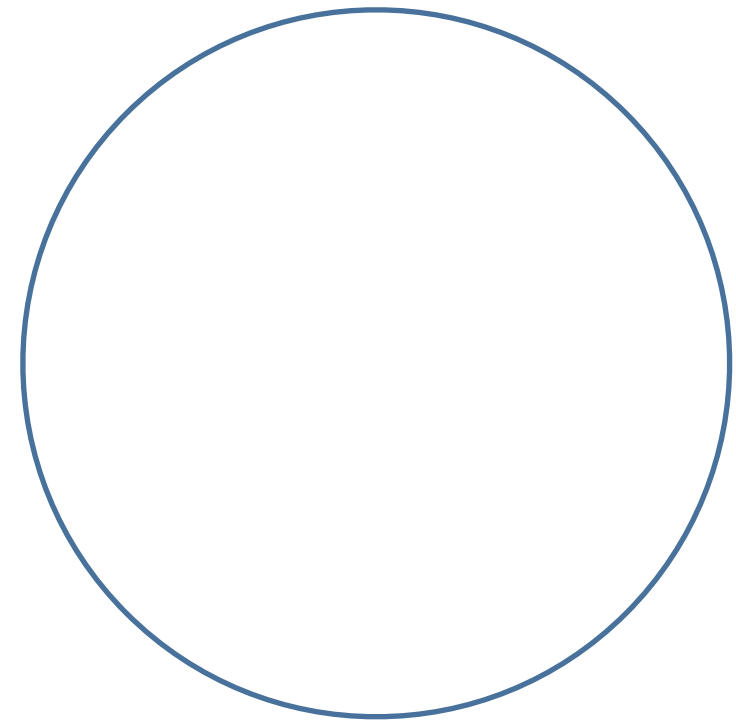
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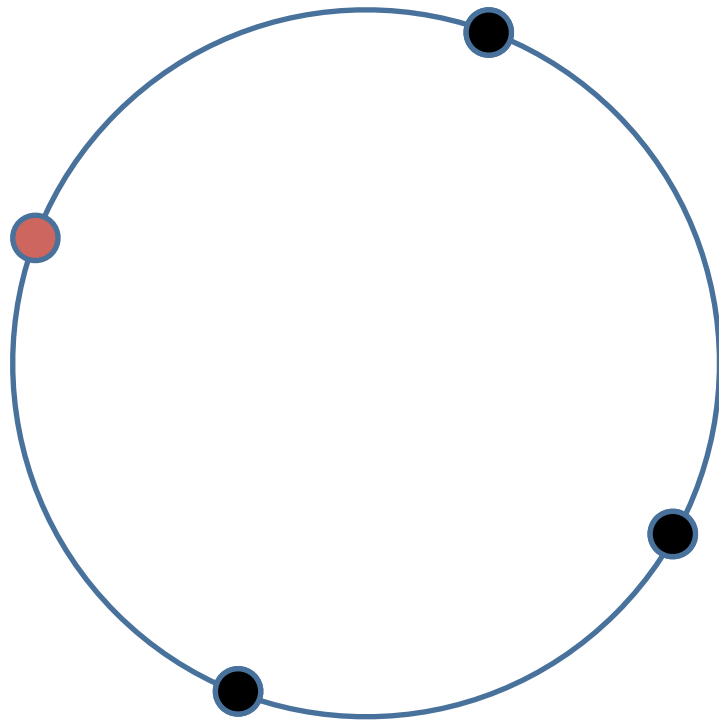
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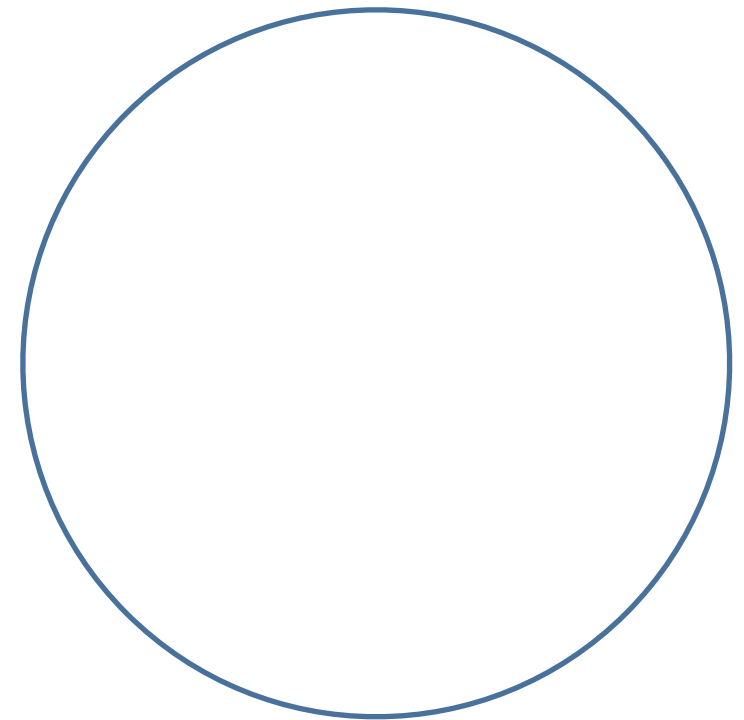
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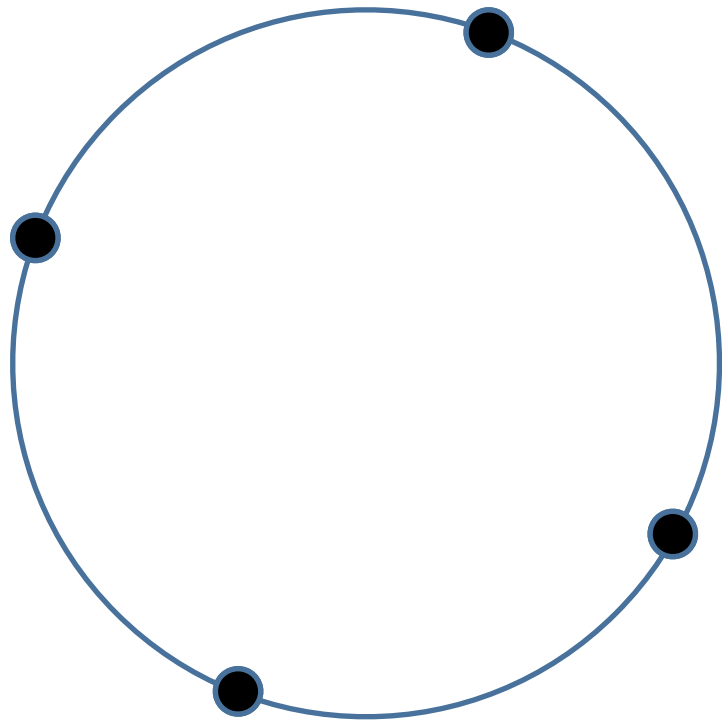
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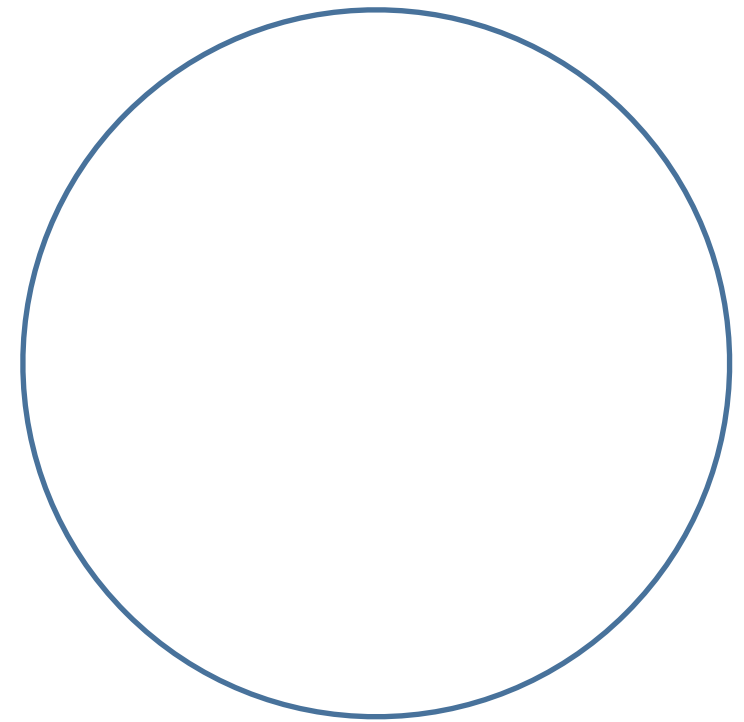
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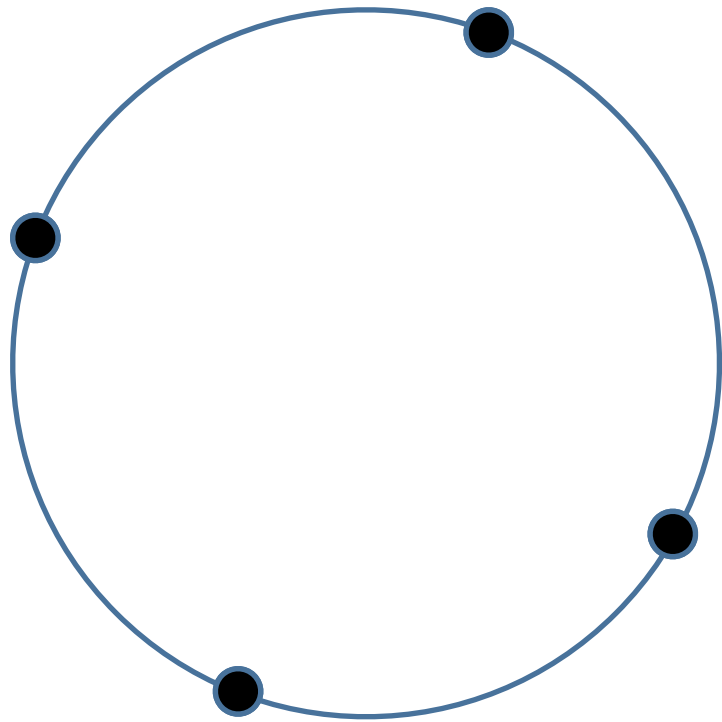
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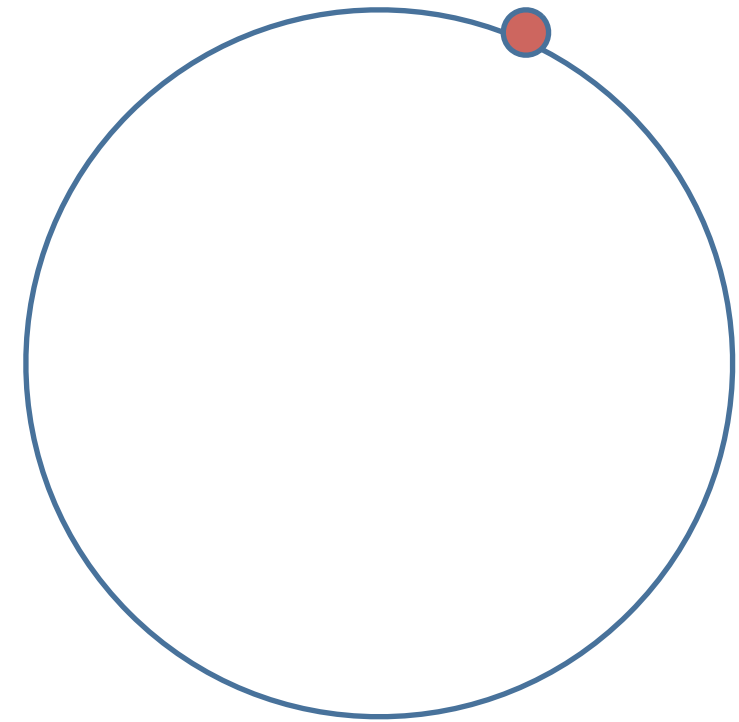
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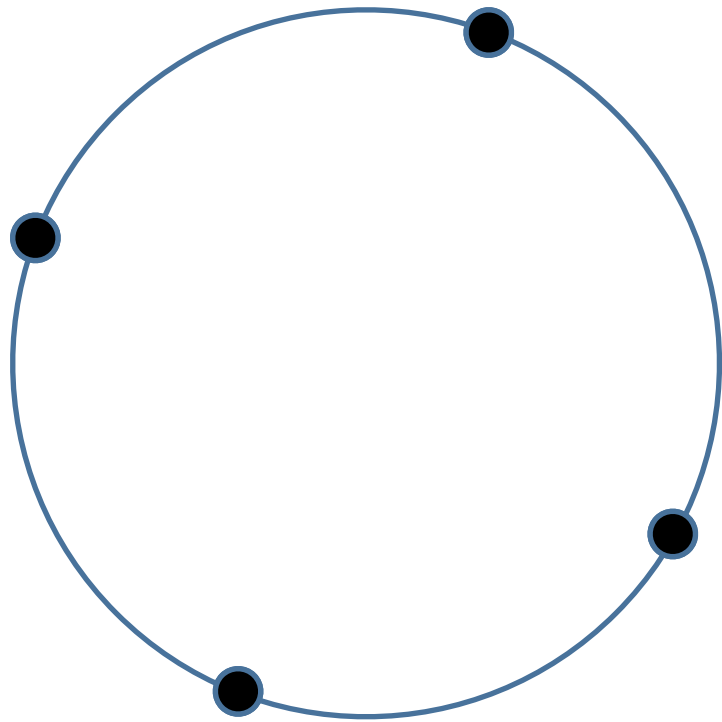


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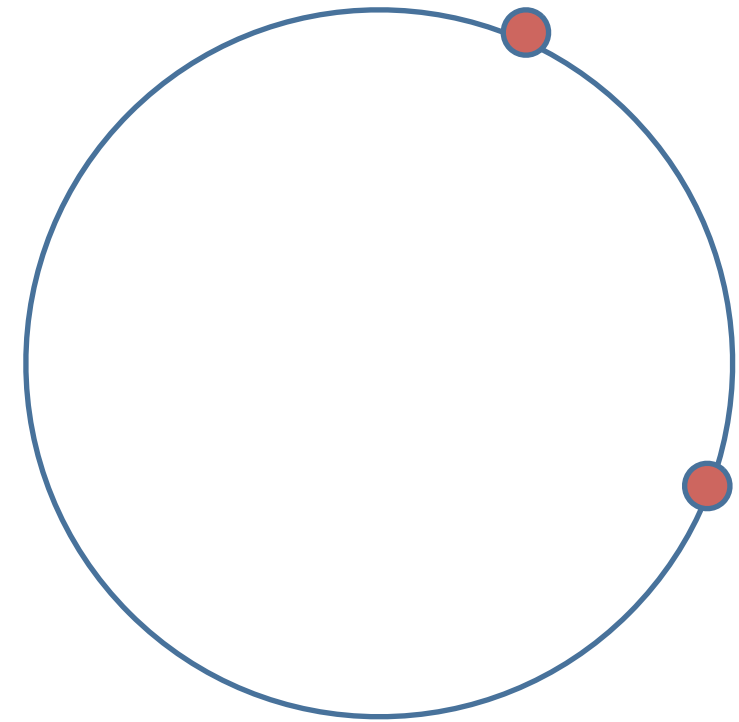


● 1st Cycle

Periodic orbit

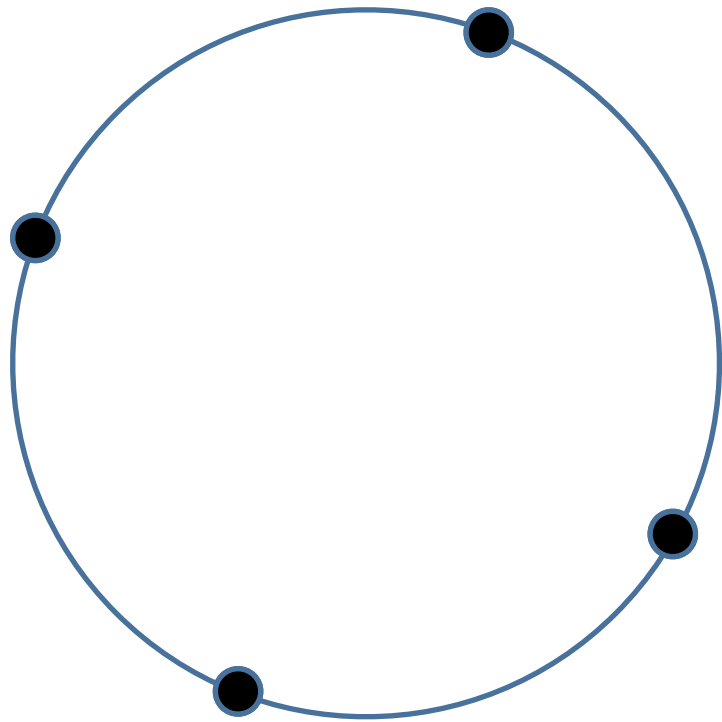


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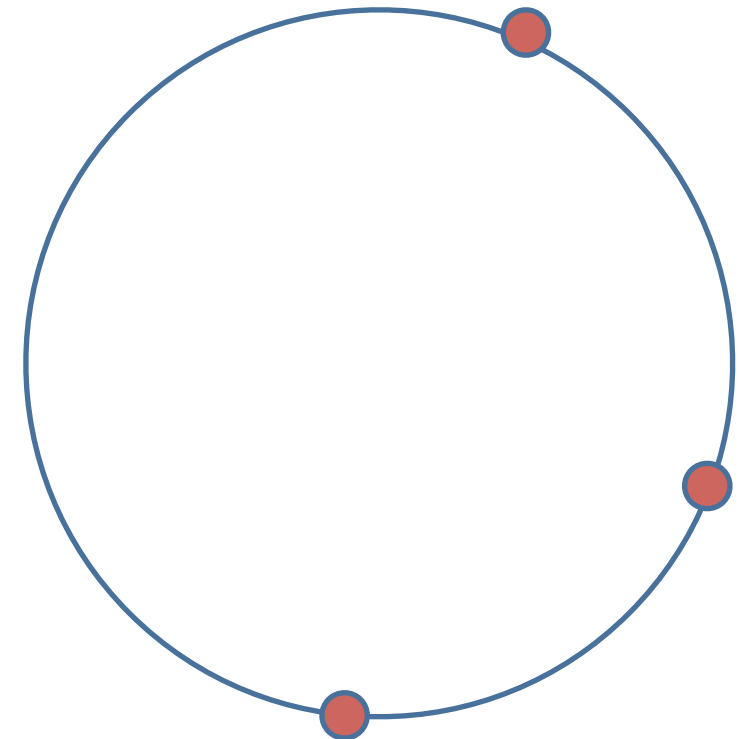


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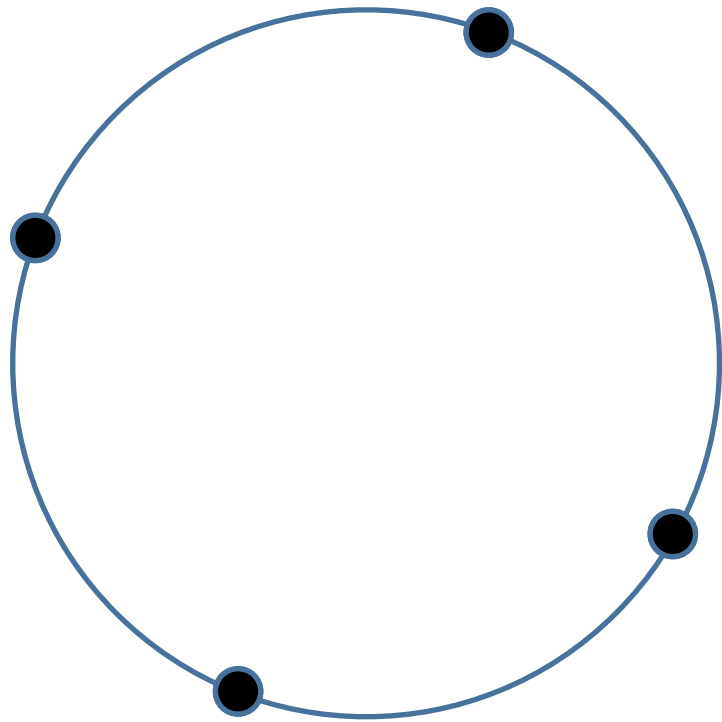


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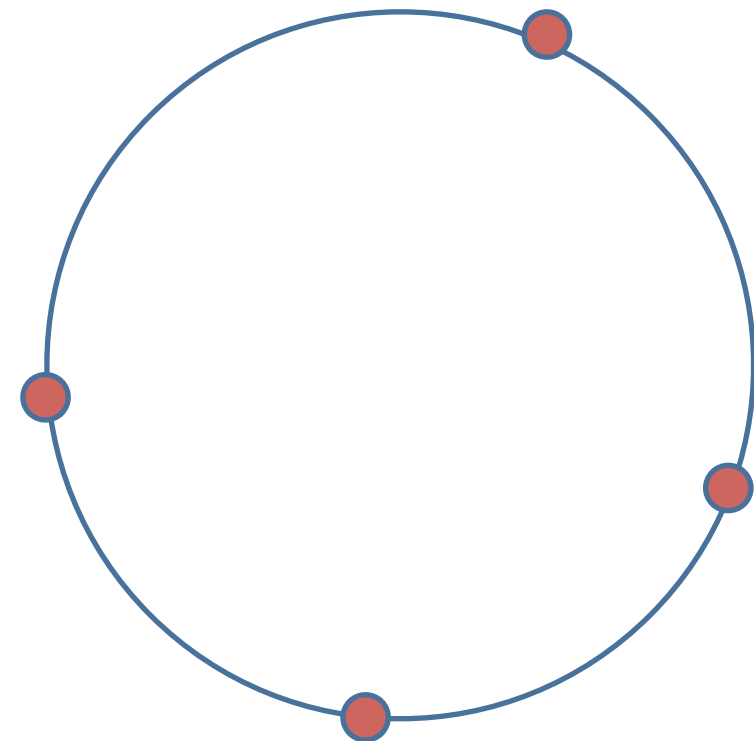


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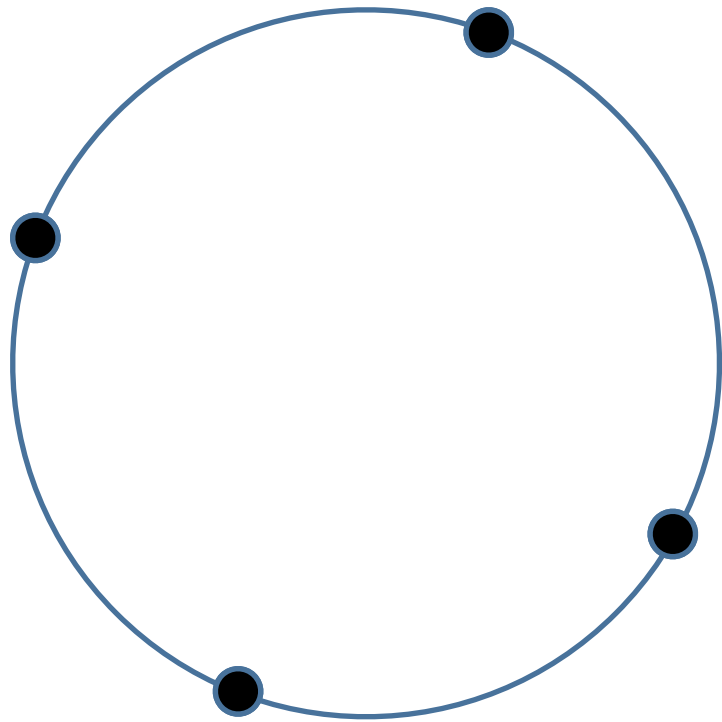


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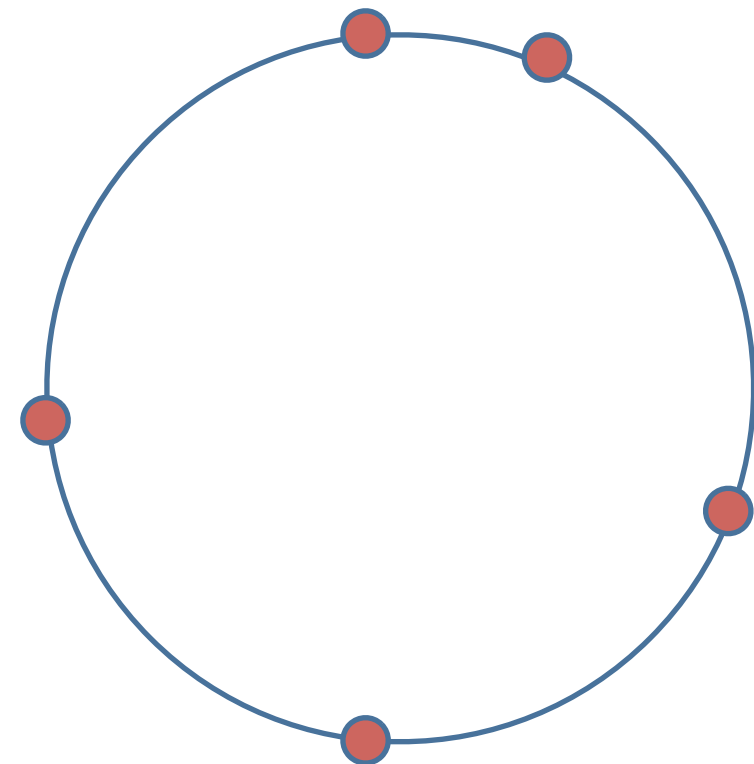


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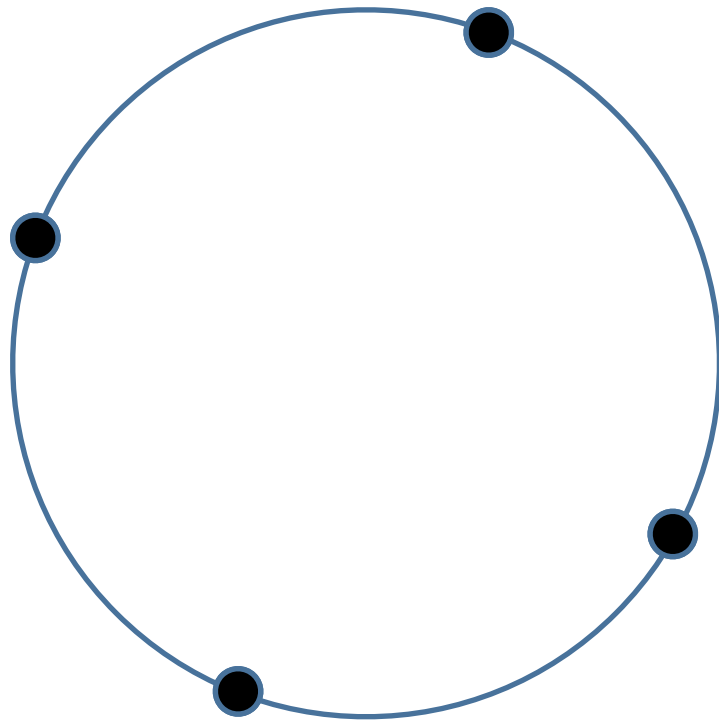


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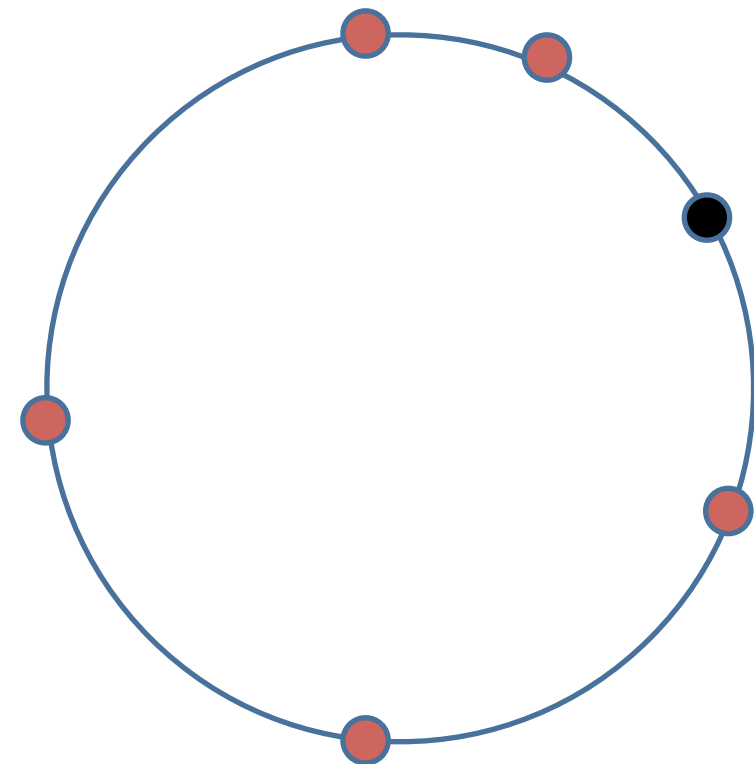


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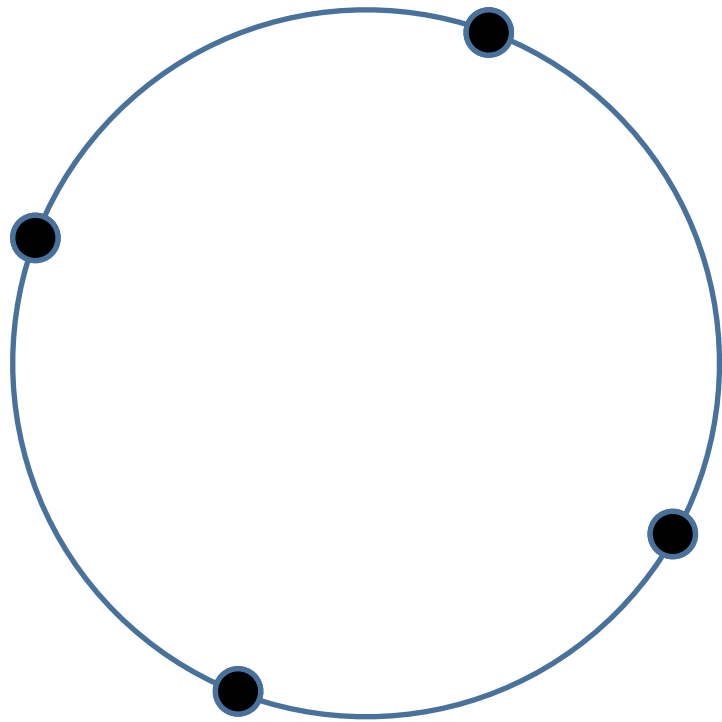
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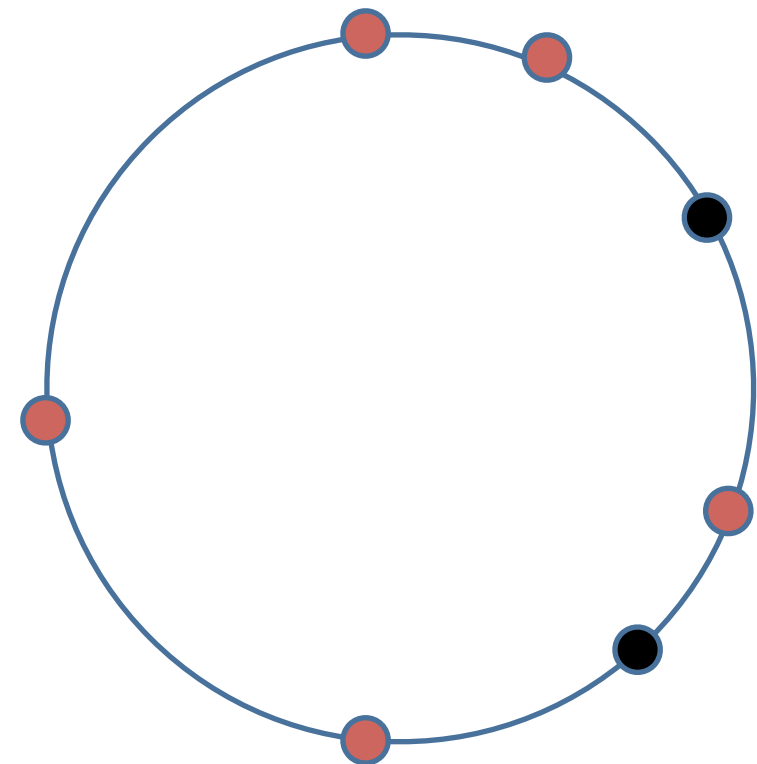
● 1st Cycle

● 2nd Cycle

Periodic orbit



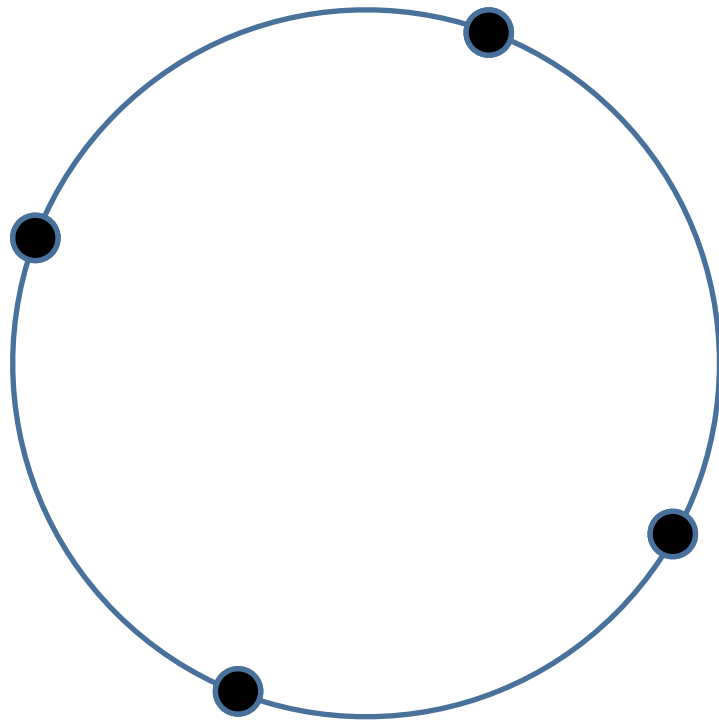
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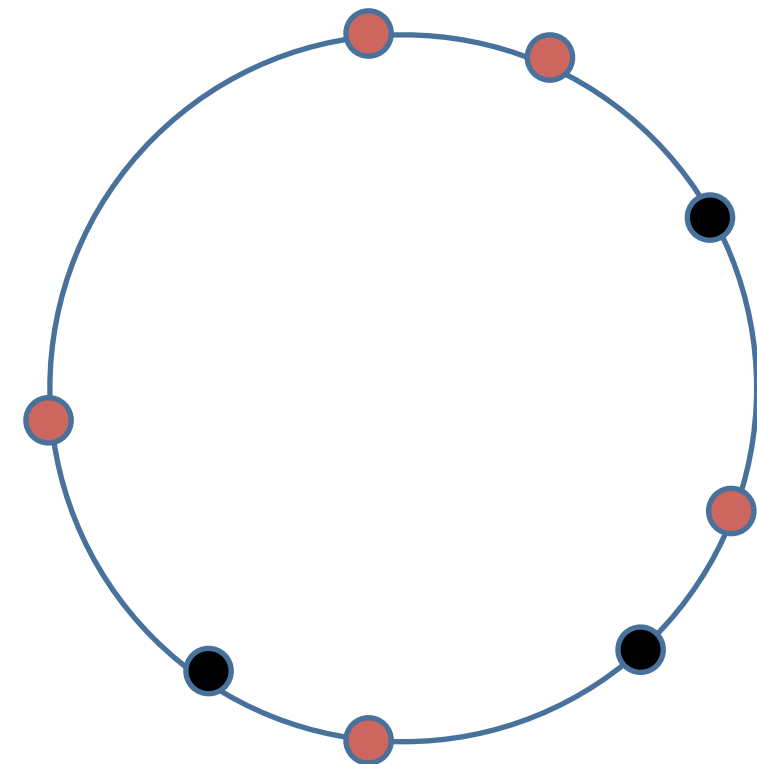
● 1st Cycle

● 2nd Cycle

Periodic orbit



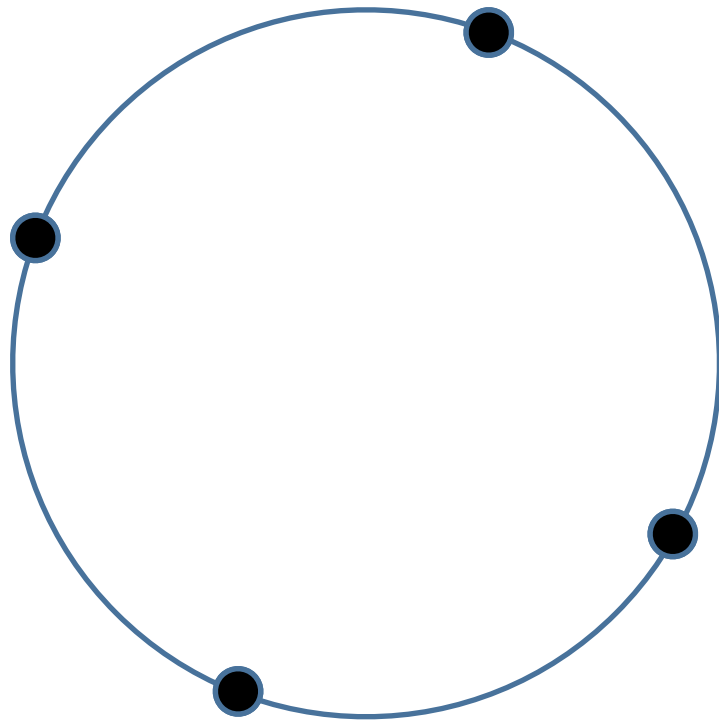
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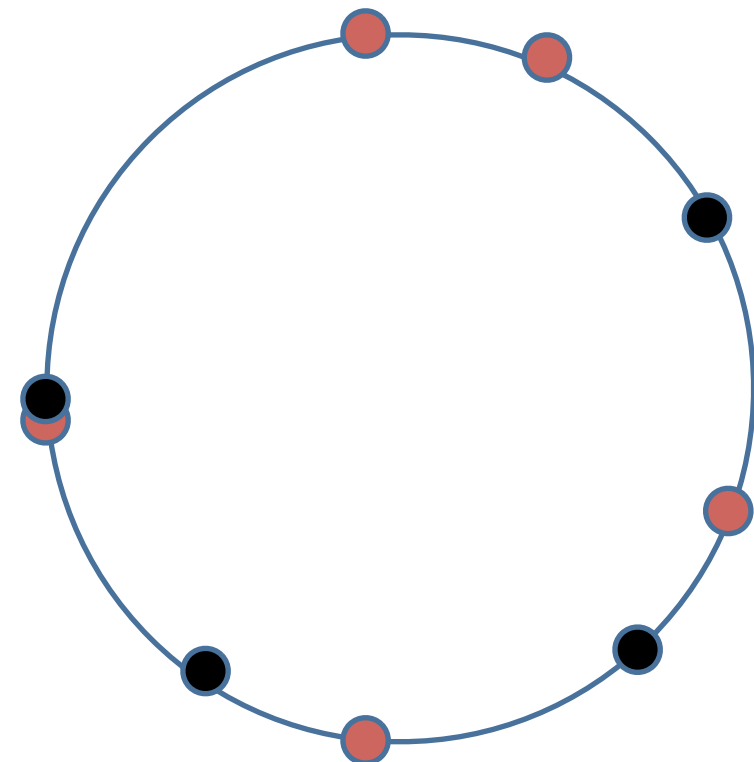
● 1st Cycle

● 2nd Cycle

Periodic orbit



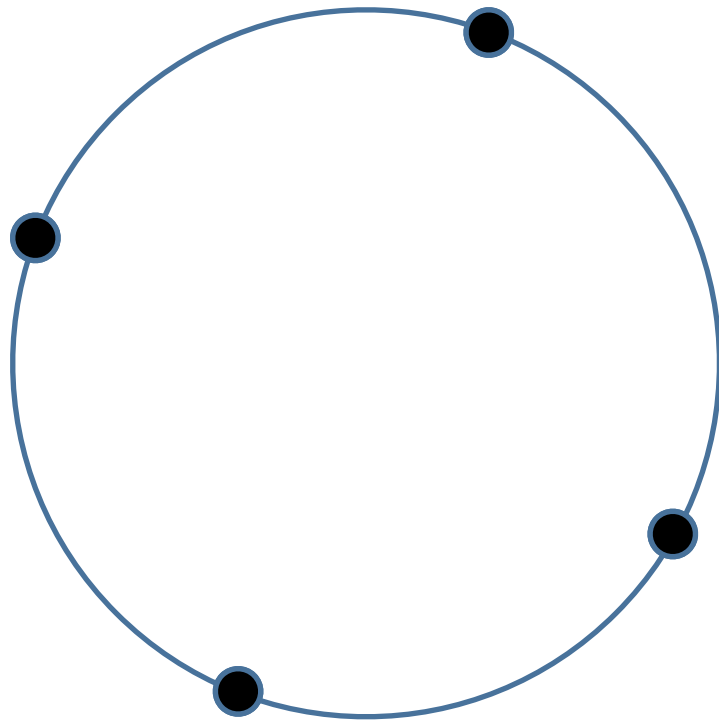
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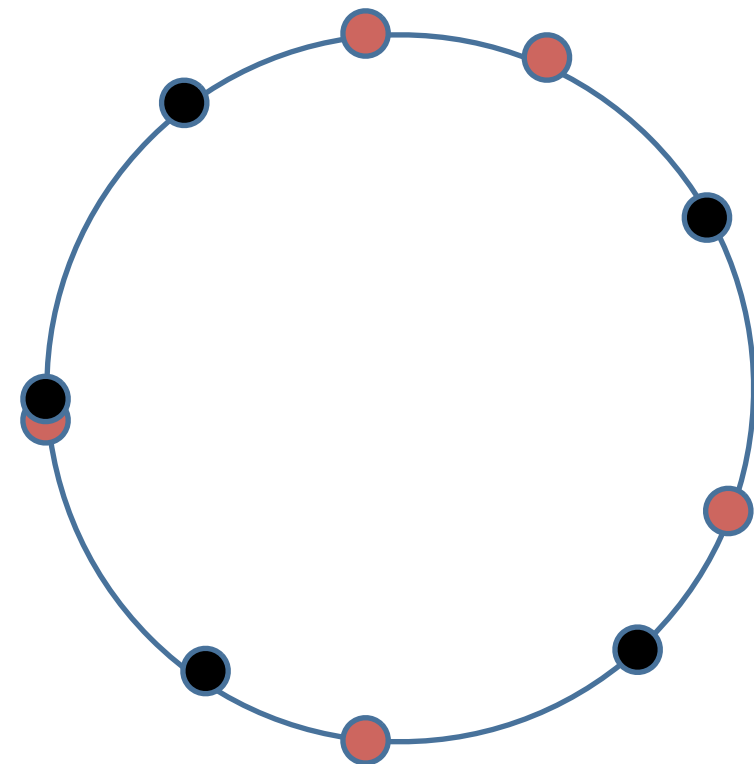
● 1st Cycle

● 2nd Cycle

Periodic orbit



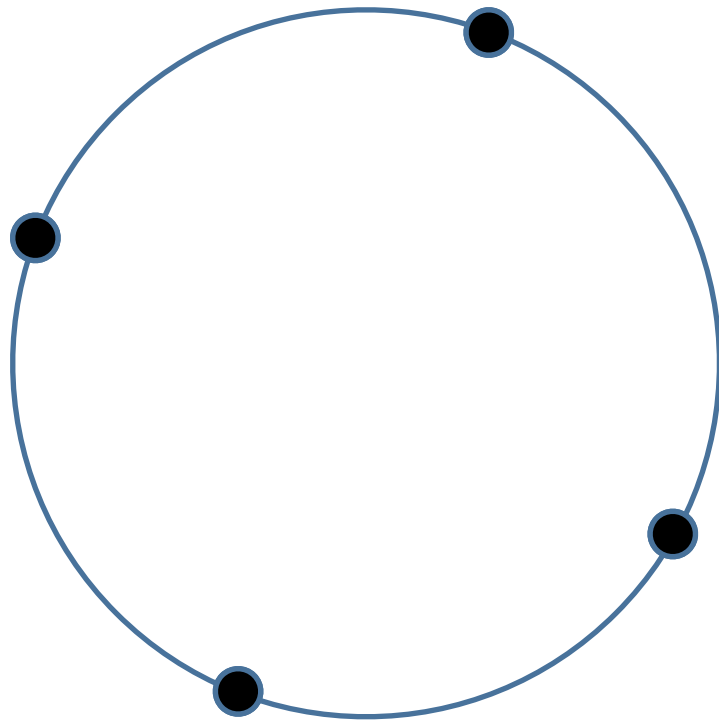
Dense orbit



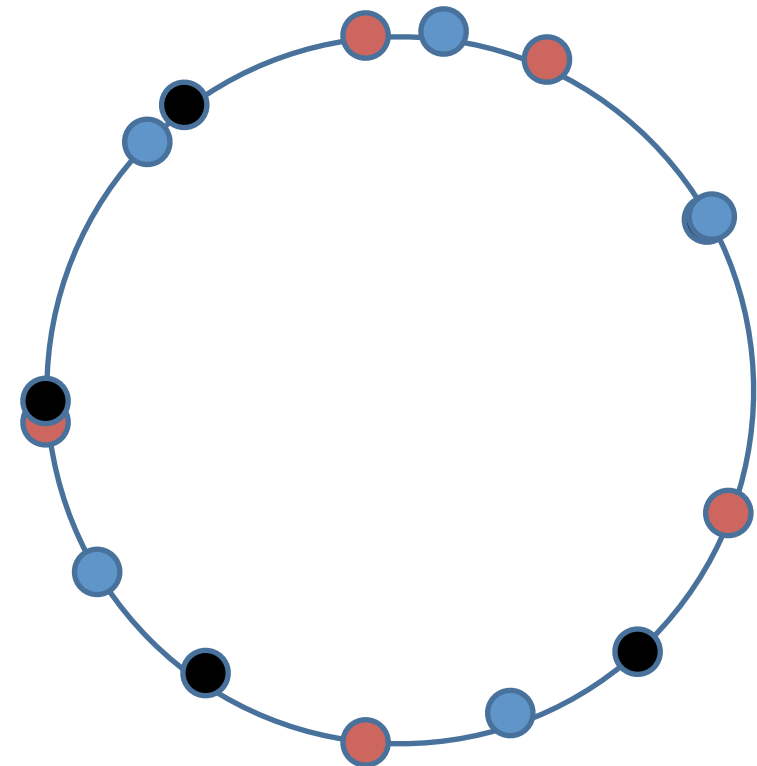
● 1st Cycle

● 2nd Cycle

Periodic orbit

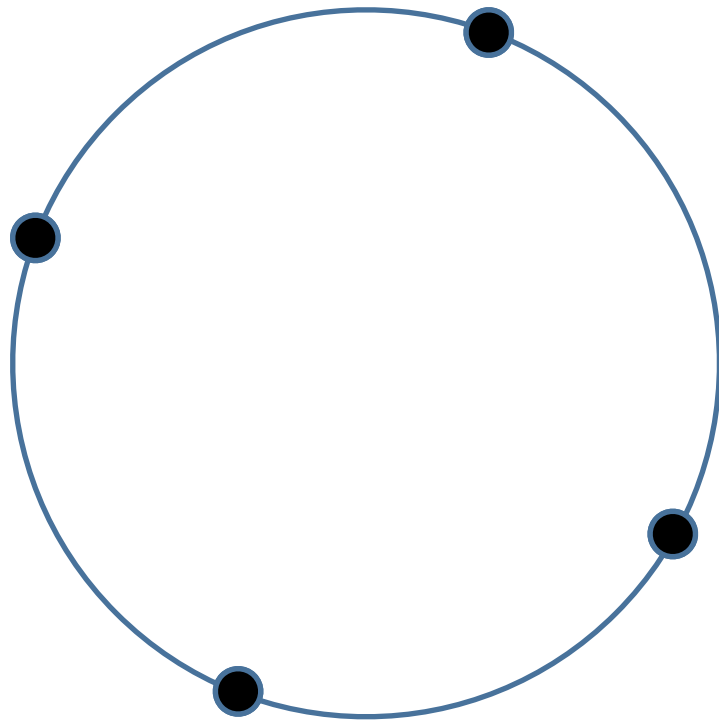


Dense orbit

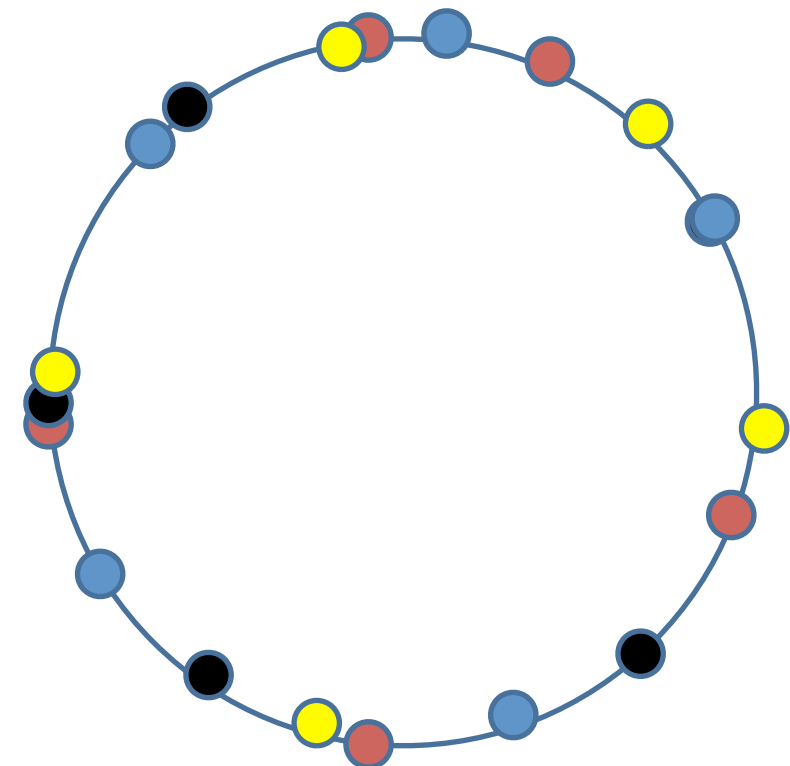


- 1st Cycle
- 2nd Cycle
- 3rd Cycle

Periodic orbit



Dense orbit



● 1st Cycle

● 2nd Cycle

● 3rd Cycle

● 4th Cycle

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- [MOC] stands for “Minimal Orbit Closures”.
- If T has [MOC], then X splits into distinct T-invariant components (closed orbits) and the T-action on each component is ergodic.

Example

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Take a map $T(r, s) = (rs, s)$. It twists the donut.

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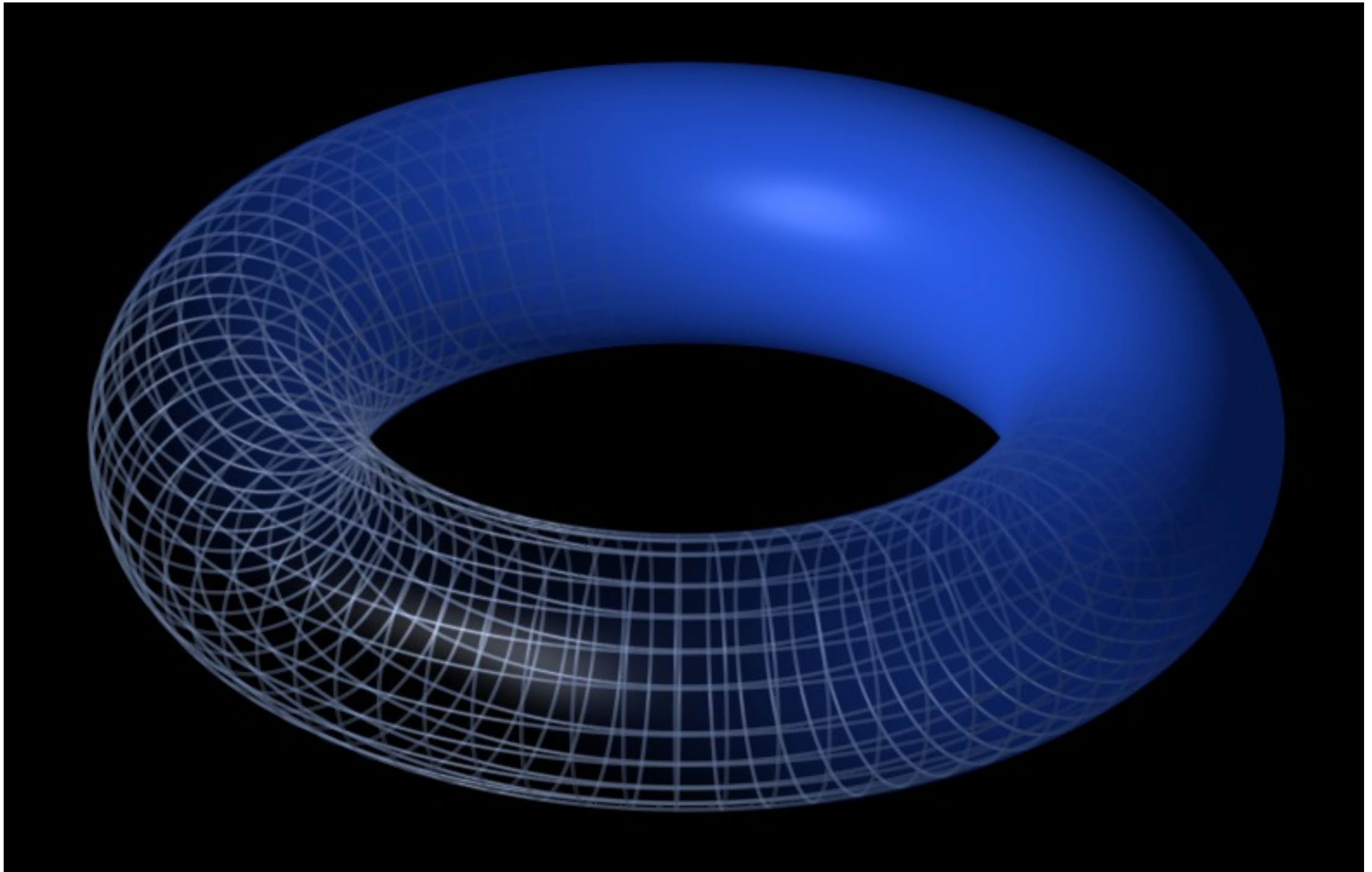
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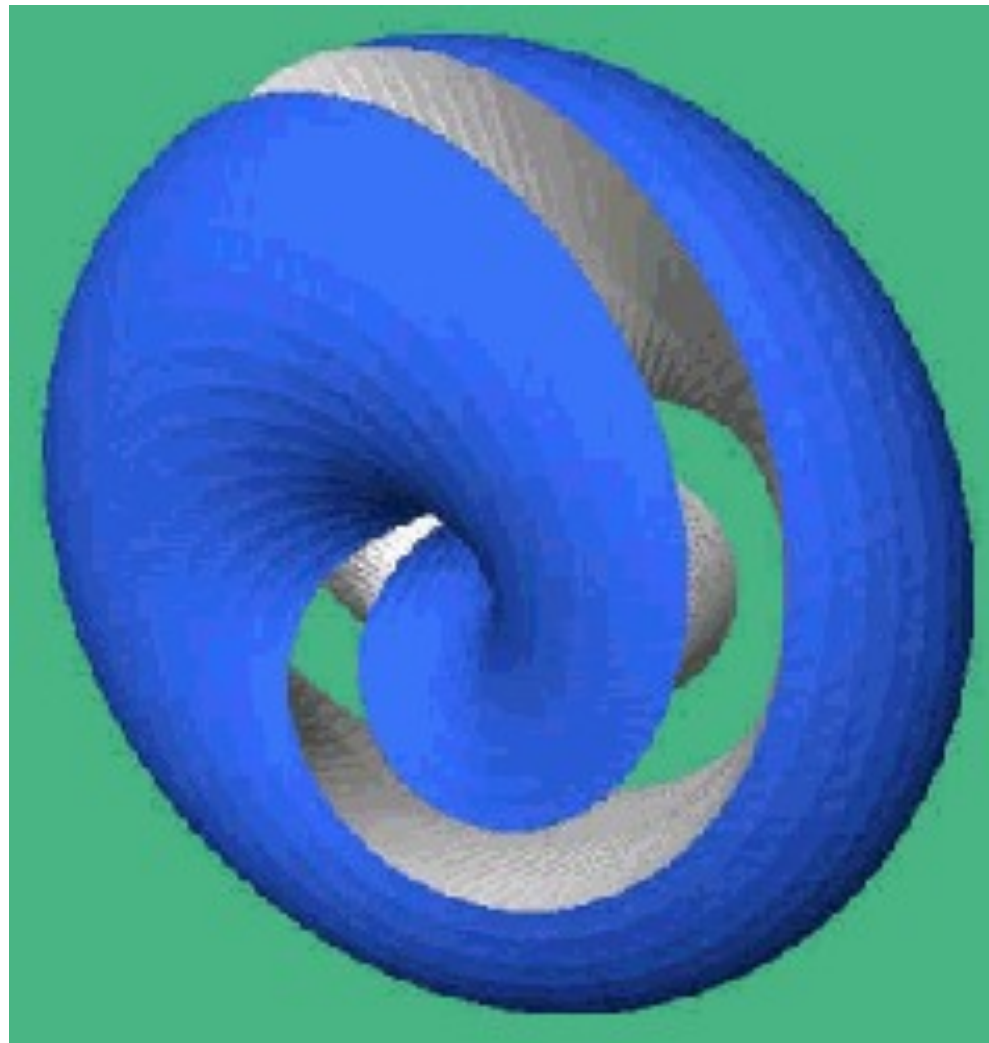
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- So no orbit is dense in the torus $S^1 \times S^1$.
- This map T has [MOC].
(Here we have some pictures.)



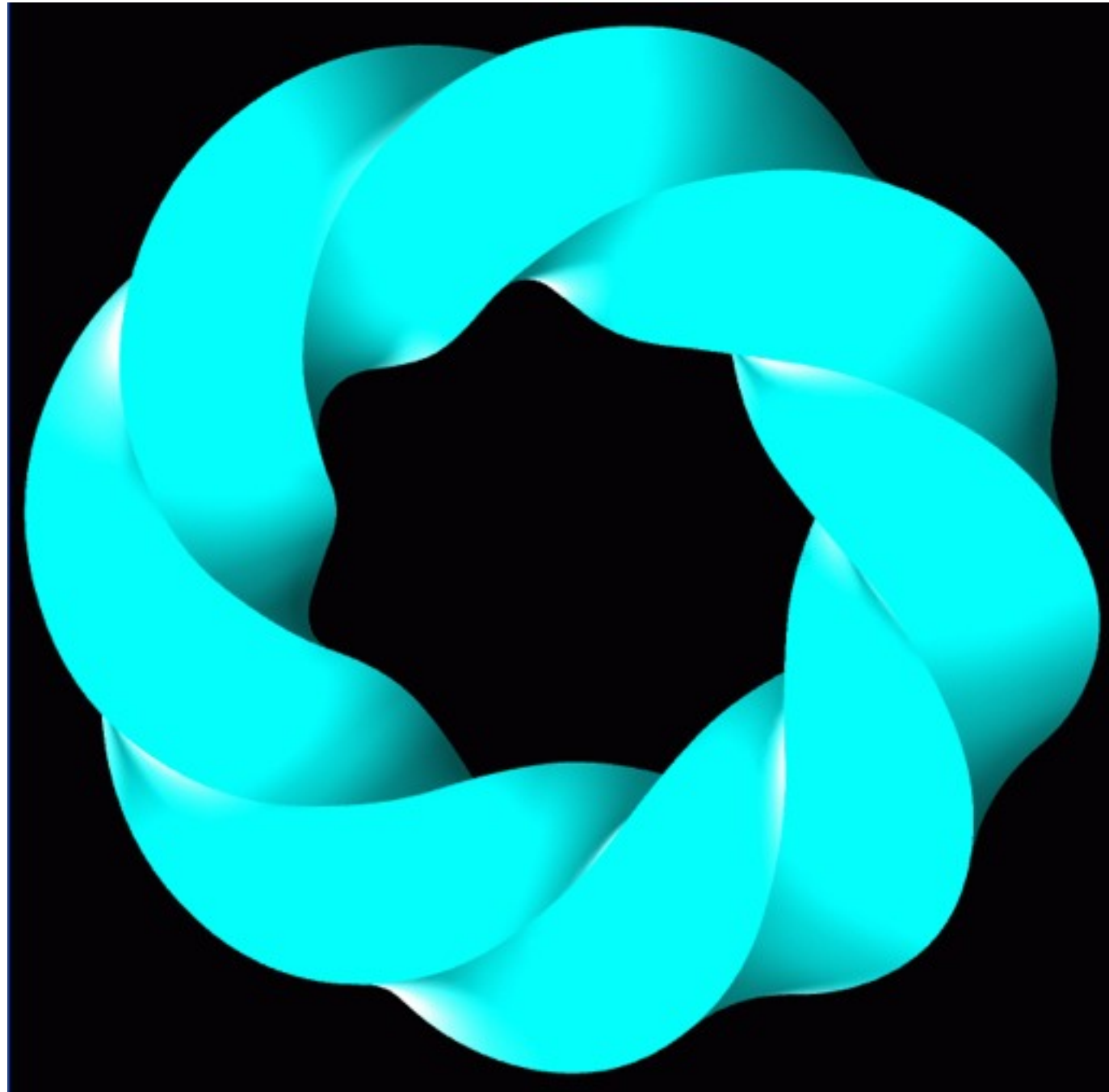
Torus after one iteration of T



Torus after one iteration of T



Torus After a few Iteration of



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- Conversely, we would like to discuss the following question:
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Distality and Orbits

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- This is known to be true for any distal action on compact spaces, (for e.g. rotation maps, or the map on torus described before).

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(For e.g. on Lie groups are locally like Euclidean spaces; closed subgroups of the matrix group; $GL(n, \mathbb{R})$ = group of $n \times n$ invertible matrices \approx Linear transformations on \mathbb{R}^n).