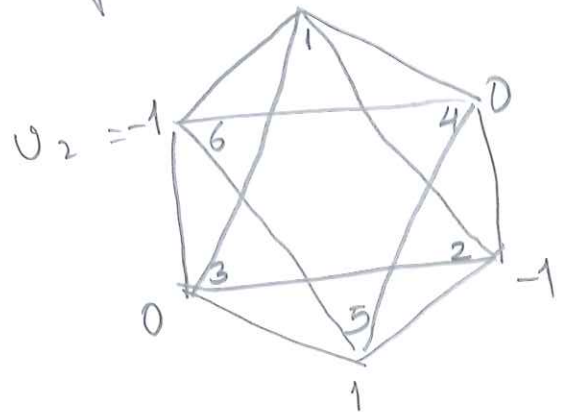
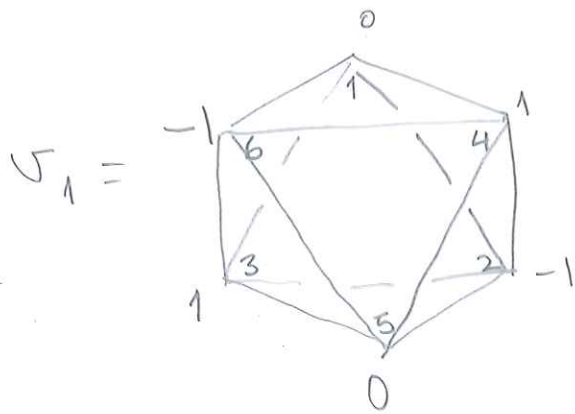


A two-dimensional rep. of $S_4:1$



$$s_1 = (15)(23)(46)$$

$$\rho(s_1) = \begin{pmatrix} -1 & -1 \\ 0 & 1 \end{pmatrix}$$

$$\rho(b_2) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\rho(b_3) = \begin{pmatrix} -1 & -1 \\ 0 & 1 \end{pmatrix}$$

$$\rho \otimes E(b_1) = \begin{pmatrix} 1 & 1 \\ 0 & -1 \end{pmatrix}$$

$$\rho \otimes E(b_2) = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}$$

$$\rho \otimes E(b_3) = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

Want an intertwiner:

$$T: V \rightarrow V$$

$$T \rho(s_i) v = \rho(s_i) T v \quad (*)$$

So if v is a ± 1 eigenvector for $\rho(s_1)$,

Tv should be a ∓ 1 eigenvector.

-1 eigenvector: $\begin{pmatrix} 1 \\ 0 \end{pmatrix} = v_1 \quad \leftarrow = w_1$

+1 eigenvector: $\begin{pmatrix} 1 \\ -2 \end{pmatrix} = v_1 - 2v_2 \quad \leftarrow = w_2$

With respect to $T(v_1) = c_1(v_1 - 2v_2)$ (1)

~~$T(v_2) = c_2$~~

$T(v_1 - 2v_2) = c_2 v_1$

(2)

$$\frac{T(1) - (2)}{2} ; T(v_2) = \frac{c_1(v_1 - 2v_2) - c_2 v_1}{2}$$

~~$= \frac{c_1}{2} v_1 - (c_1 - c_2)$~~

$$\frac{c_1 - c_2}{2} v_1 - c_1 v_2$$

$$T = \begin{pmatrix} c_1 & \frac{c_1 - c_2}{2} \\ -2c_1 & -c_1 \end{pmatrix}$$

$c_1 = 1$ $T = \begin{pmatrix} 1 & \frac{1 - c_2}{2} \\ -2 & -1 \end{pmatrix}$

$$\begin{pmatrix} 1 & \frac{1 - c_2}{2} \\ -2 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \neq \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & \frac{1 - c_2}{2} \\ -2 & -1 \end{pmatrix}^{-1}$$

(put $i = 2$ in (*)) $T = \begin{pmatrix} 1 & 2 \\ -2 & -1 \end{pmatrix}$

$$\begin{pmatrix} \frac{1 - c_2}{2} & 1 \\ -1 & -2 \end{pmatrix} + \begin{pmatrix} -2 & -1 \\ 1 & \frac{1 - c_2}{2} \end{pmatrix} = 0$$

$$\frac{1 - c_2}{2} = 2$$

$$1 - c_2 = 4 \quad c_2 = -3$$

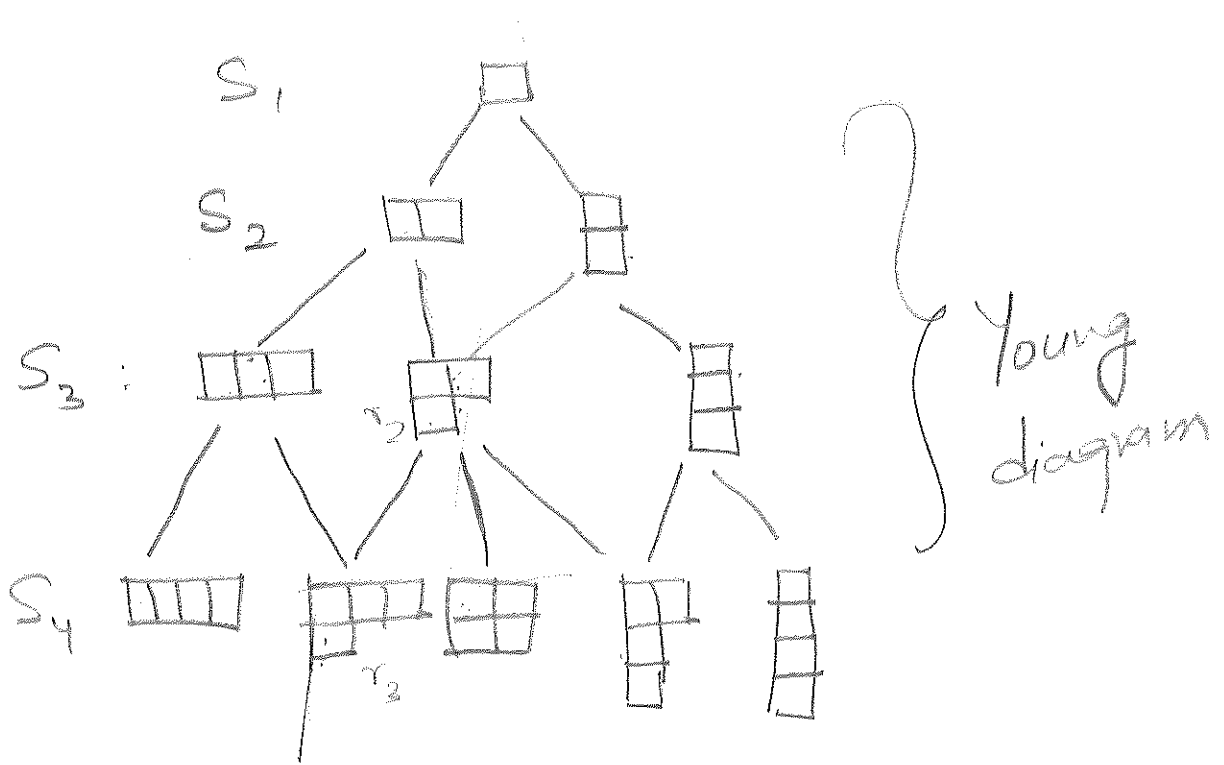
Catalog of irreducible representations

$$S_2 : \begin{matrix} \text{dim } 1 \\ 1 \end{matrix}, \begin{matrix} \text{dim } 1 \\ \epsilon \end{matrix}$$

$$S_3 : \begin{matrix} 1 \\ \text{1 dim} \end{matrix}, \begin{matrix} \tau \\ \text{2 dim} \end{matrix}, \begin{matrix} \epsilon \\ 1 \end{matrix}$$

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$$S_4 : \begin{matrix} 1 \\ \text{1 dim} \end{matrix}, \begin{matrix} \tau \\ \text{3 dim} \end{matrix}, \begin{matrix} \rho \\ \text{2 dim} \end{matrix}, \begin{matrix} \tau \oplus \epsilon \\ \text{3 dim} \end{matrix}, \begin{matrix} \epsilon \\ \text{1 dim} \end{matrix}$$



Young diagram

boxes left & top justified

$$S_n \rightsquigarrow \begin{matrix} \overbrace{\square \square \square \square \square}^{n-1} \\ \square \end{matrix} = \tau_{n-1}$$

V

$$Q^n = Q \oplus V$$